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LINEAR REGRESSION MODELS OF SOUND VELOCITY
IN THE NORTH ATLANTIC OCEAN BELOW A CRITICAL DEPTH

by

RICHARD ROLAND KUNKEL, 1945-

A DISSERTATION

Presented to the Faculty of the Graduate School of the
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ABSTRACT

Sound velocity models currently in use by the U. S. Navy require difficult data sampling at great expense. This study is to investigate the feasibility of a sound velocity model dependent only upon position that would be valid for a selected, reasonably large, near homogenous area of the ocean. The most important position parameters are latitude, longitude, and depth.

To accomplish this objective a critical depth of 2500 meters was established for an 8° by 20° rectangle of the Sargasso Sea which lies within the North Atlantic Ocean. The critical depth is defined as the depth at which the characteristics of the area of the ocean being considered become stable enough to predict sound velocity as a function of position within a specified accuracy.

Such a model was produced with the aid of new concepts of independent term generation within stepwise multiple regression software that allowed a study of a variety of models with unprecedented ease.

ACKNOWLEDGEMENTS

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Appreciation is extended to Mr. Richard A. Bolton of the United States Naval Oceanographic Office who originally suggested the undertaking of this study, facilitated the obtainment of data, supplied graphic software, and conceived of many new ideas made available in Appendix A.

Cordial recognition is due Dr. A. K. Rigler of the Computer Science Department for his continual daily assistance in analyzing and perfecting this study.

Finally, deepest gratitude is expressed to the author's wife, Karen, and son, Timothy, for their patience and understanding during these years of study, and to the writer's wife special recognition is deserved for the many hours she spent at his side during the construction and final typing of this paper.

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I. INTRODUCTION

Although oceanography, the application of sciences to the phenomena of the oceans, is an old science in that man wondered about the oceans of the world long ago; it is also a very new science. Until recently only the oceans' surfaces had been explored to any extent. Men knew little of the depths, little of the details of these great water filled basins that cover 70.8 percent of the surface of the earth.

Acquiring adequate knowledge of the subsurface of the oceans is a task to which the United States Navy has committed itself. Within the scope of this task is the determination of the speed of sound at any given depth in the oceans of the world. One recognizes the importance of this problem when reviewing the statistics of submarine warfare during World War II. However, the problem of determining sound velocity in the oceans has become more pertinent and important in a peacetime atmosphere with man's insistence on exploring the oceans and their boundaries.

Since the oceans of the world cover over two-thirds of the earth's surface, the investigation of sound velocity in all oceans can not be undertaken under one project. Furthermore, the composition of the oceans are so variable that even one body of water is usually subdivided into specified sections. Thus, one must look at only a certain section of a body of water at a time in or-

der to obtain an accurate sound velocity model for that section. The number of sections needed seems to be dependent on the variability of the body of water being considered.

The Atlantic Ocean alone covers 16.2 percent of the earth's surface. Because of its dimensions, it is divided into the North and South Atlantic. Again the North Atlantic's size warrants that it be subdivided and that only one subdivision be investigated at a time. It is the purpose of this study to investigate sound velocity in a section of the North Atlantic Ocean, and in turn to determine a more reasonable and feasible sound velocity model than those already in existence for the section considered.

In order to determine whether a model is more reasonable or feasible some criteria must be established for this end. The criteria used in this paper is the number of independent terms necessary to implement the model, the expense in acquiring data for the model, and the accuracy of the model. All of the above have been obstacles to the Navy in utilizing the sound velocity models already in existence.

In the past the Navy has developed analytical, graphical, and numerical sound velocity models for sea water. Much work has been done with all three types of models and the comparisons among them. In this paper numerical methods will be employed through using stepwise multiple regression analysis. However,

new numerical techniques in term generation within the stepwise multiple regression have been created in order to help eliminate the trial and error methods of deciding which terms should appear in the regression model and facilitate the laborious procedures of data preparation.

Since underwater sound velocity is a function of many independent variables, its method of obtainment still puzzles the minds of men today. Nevertheless, if one could definitely conclude that only certain independent variables were necessary for the determination of sound velocity in sea water, the problem would still not be solved. Many independent variables that are now considered essential to compute sound velocity such as salinity, temperature, and pressure can be obtained by only crude methods of data collection at great expense. Data collection becomes more expensive as the depth of the observation increases. No reliable method exists for the computation of sound velocity at a given position that eliminates the need for on-location measurements of the desired independent variables. Thus, expensive data collection and data storage must precede deep underwater calculation of sound velocity.

If one would investigate sound velocity models already developed, complex equations with many independent variables would be encountered. Furthermore, each model would be valid for only a

small section of the body of water being considered. Since the composition of sea water is so variable, it limits a given model from being accurate over a large section. Thus, a number of models must be incorporated in order to determine sound velocity for a sizeable body of water.

A further investigation of known models of sound velocity and graphs of the important independent sound velocity variables would illustrate a more predictable or stable system as the depth increases for a particular latitude and longitude of the body of water in question. This phenomena indicates that at near surface depths the role of the independent variables are quite important for it is at these shallow depths that these variables are most erratic. Much of this can be accounted for by the seasonal change of the earth's atmosphere.

Therefore, it seems reasonable that some critical depth should exist such that below this depth it becomes feasible to build a simplified model of sound velocity for large portions of the ocean. By large portions is meant portions larger than the sections used for sound velocity models which are accurate for all depths. Of course there are exceptions to this general observation. For example, whenever a discontinuity exists such as at the interface of two different bodies of water, the above may not apply.

Thus, the author of this paper believes that this critical depth should be established; that the more accurate and well-known equations for the calculation of sound velocity should continue to be used above this critical depth where data collection is less expensive; and that a new model should be employed below this critical depth which would contain fewer independent variables. It is also below this critical depth that the collection of data is most expensive. If this new model is to be a positive contribution, then it must be accurate, hold for large portions of the body of water being considered, and be less expensive to implement.

The most expensive part of data collection, along with all of its present difficulties, could be discarded if this model could completely eliminate the need for on-location measurements. This would definitely indicate a model dependent only upon position. The more important position parameters for this study are latitude, longitude, and depth. The feasibility of this is discussed in Chapter II and the model itself is investigated in Chapter III. Even if only a few independent variables could be dropped, substantial savings would be realized.

The massiveness of the oceans creates an obstacle when handling data for oceanographic problems. While the data for a certain section of the ocean might be relatively sparse, the total amount of data for the section is extremely voluminous. This

plus other factors such as limited computer facilities, have defined the size of the section of the North Atlantic for this study which could reasonably be examined in detail. A 8° by 20° rectangle off the east coast of the United States has been chosen. It extends from 30° to 38° N latitude and from -48° to -68° W longitude. The nomenclature used is north latitude is positive and west longitude is negative.

II. LITERATURE REVIEW

Oceanography¹ is the study of the sea, embracing and integrating all knowledge pertaining to the sea's physical boundaries, the chemistry and physics of sea water, and marine biology. It encompasses portions of all the physical sciences. However, oceanography may be divided into five basic sciences: physics, chemistry, meteorology, biology, and geology. Of these five basic divisions, physical oceanography is the largest and most diversified. The physical aspect which will be investigated in this study is the determination of the speed of sound in sea water.

Inasmuch as characteristics of the sea may change with respect to both space and time, the periodicity and extent of these changes must be reviewed. Surveys are made at sea aboard a laboratory-equipped ship in order to obtain oceanographic information. The greater portion of oceanographic work at sea is carried out while occupying an oceanographic station in which the ship is lying-to (anchored). An oceanographic station² is any group of oceanographic observations made at the same, or virtually the same, geographic position at nearly the same time.

It is not a difficult matter to sample the surface of the ocean for chemical and physical analysis. But, it is more difficult to obtain a sample of water from the ocean depths with accurate measures of depth and temperature and with the assurance

that the sample is not mixed with surrounding waters.

Chemical properties of sea water are determined by analyzing samples of water obtained at various places and depths. Samples from below the surface are obtained by means of metal bottles designed for this purpose. The open bottles are attached at suitable intervals to a wire lowered into the sea. Each opened bottle flushes itself during lowering. When they reach the desired depths, a metal ring called a messenger is dropped down the wire. When the messenger arrives at the first bottle, it disconnects the top of the bottle from the wire. The bottle then reverses, making a 180° arc with the wire, while trapping a sample of the water at that depth; and releases a second messenger which travels on down the wire. The process is repeated at each bottle until all are closed, then they are hauled up and each bottle detached as it comes within reach. This widely used device is referred to by Bowditch³ as the Nansen bottle and is shown in Figure 1. It is equipped with a removable frame for attaching thermometers which are shown in Figure 2.

If the oceans all over the world were sampled with the above techniques and the most accurate methods of chemical analysis for determining the composition of the sea water at each location were used, it would be found that, although the total amounts of dissolved salts is variable, the relative proportions of the major

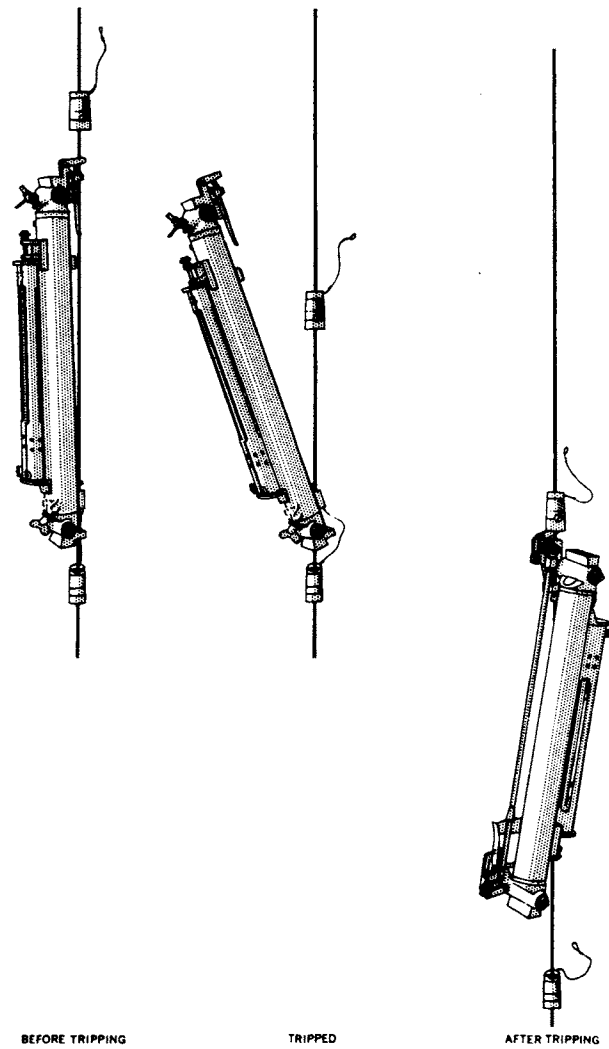


Figure 1. Nansen Bottle in Three Positions

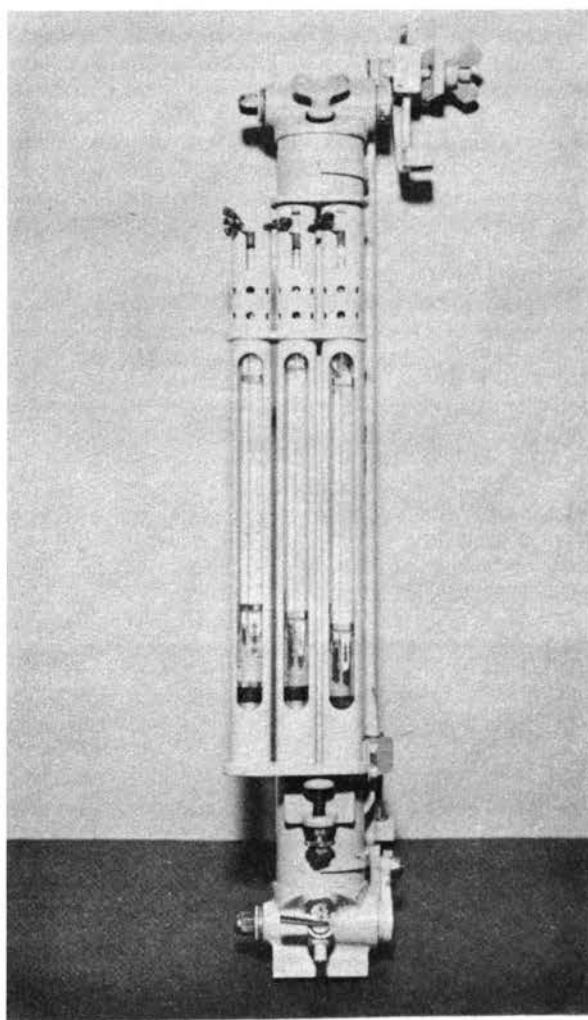


Figure 2. Nansen Bottle with Thermometers

elements (Na, Cl, Mg, Ca, etc.) are constant. Turekian⁴ ascertained this fact from the study by W. Dittmar on the samples collected on the Challenger expedition in the 1870's.

The saltiness of the ocean, or "salinity", is defined as the number of grams of dissolved salts in 1,000 grams of sea water. The total range of salinity of the open ocean is from 33 to 38 parts per thousand.

The oceans can be thought of as a gigantic pump which transfers heat from the equator to the poles. This transfer is effected in the surface waters of the oceans. The deep waters of the oceans all have their origins in the high latitudes and hence are considerably colder than the surface waters. The vertical distribution of temperature in the sea nearly everywhere shows a decrease of temperature with depth. Since colder water is denser, it sinks below warmer water. This results in a temperature distribution just opposite to that in the earth's crust, where temperature increases with depth below the surface of the ground. Figure 3 shows the variation of temperature and salinity with depth at one locality.

The peculiarities and limitations of sound in sea water could best be understood if the sound was transmitted in an ideal ocean. Such an ocean is assumed to be homogenous, infinite in extent, and perfectly elastic. It is obvious that the oceans have no such

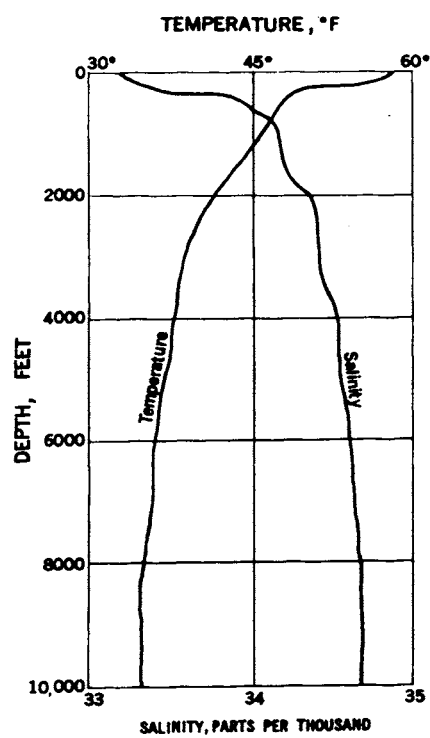


Figure 3. Variation of Temperature and Salinity with Depth at One Locality

ideal qualities. It is not infinite in extent, being bounded by the bottom and the surface. It is not homogenous; the upper layers are usually warmer than the lower ones. Furthermore, the properties of sound transmission are evidence of its non-elasticity.

Stephenson and Woodsmall⁵ stated that the velocity of sound in water is given by the expression

$$V = \sqrt{dp/d\rho} \quad (2.1)$$

where p is the pressure and ρ is the density. Thus, the velocity of sound at a given point is determined by the pressure and density at that point. In the ocean, pressure increases with depth, and the density will vary as the temperature and salinity change. For convenience in calculation from well established physical data, the formula used is

$$V = \sqrt{r/\rho C} \quad (2.2)$$

where r is the ratio of specific heats at constant volume and constant pressure, and C is the compressibility. The numerical values of these quantities depend on the temperature, salinity, and depth or pressure. Therefore, Berryman⁶ concluded, the main environmental influences on sound velocity are temperature, salinity, and pressure.

In sea water an increase in temperature, pressure, or

salinity results in greater speed of sound. Of the three, temperature has the greatest influence on the speed of sound in sea water in the upper layers. At depth, pressure, and in coastal areas, changes in salinity, may have the greatest effect. Normally, the change of these three elements is much more rapid in a vertical direction than in a horizontal direction. The change with depth varies with location. Typical curves showing the change of temperature and salinity with depth were shown in Figure 3. The increase of pressure with depth is almost uniform. A typical curve of speed of sound with depth is shown in Figure 4.

Sound energy moves through the water at speeds varying from less than 4,700 feet/second to greater than 5,100 feet/second. The first comprehensive sound velocity tables were published in 1924 by Heck and Service⁷. In 1939 Kuwahara⁸ brought out a new set of sound velocity tables with added refinements and corrections for oceanographic work. Kuwahara presented sound speed as a function of temperature, pressure, and salinity. The tables of Kuwahara are believed to be the most accurate tables available at this time.

In general, sound velocity increases: (1) four to eight feet/second for every 1°F increase in temperature, (2) about four feet/second for every one part per thousand (‰) increase in salinity, and (3) about two feet/second for every 100 foot increase in

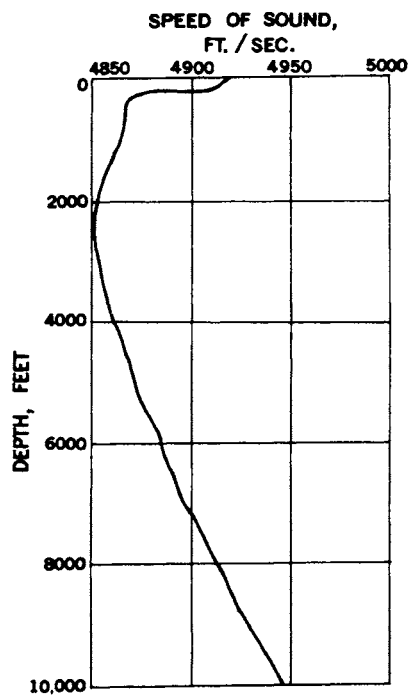


Figure 4. Typical Variation of Speed of Sound with Depth in the Ocean

depth⁹. Changes in the variables temperature, salinity, and depth or pressure are shown in Figure 5.

Kinsler and Frey¹⁰ concluded that the composite effect of the factors temperature, salinity, and depth can be represented by the empirical equation

$$c = 1449 + 4.6t - 0.055t^2 + 0.0003t^3 + (1.39 - 0.012t)(S - 35) + 0.017d \quad (2.3)$$

where c is the velocity in meters per second, t is the temperature of the water in °C, S is its salinity expressed in parts per thousand, and d is the depth below the surface in meters. This equation is a simplification of more complicated equations obtained by Wilson¹¹ and others as the best fits to experimentally measured data.

Wilson's equation is given for the speed of sound in sea water. The experimental data used to determine this equation were obtained in temperature, pressure, and salinity ranges $-4^{\circ}\text{C} < T < 30^{\circ}\text{C}$, $1\text{kg}/\text{cm}^2 < P < 1000\text{kg}/\text{cm}^2$, and $0\text{‰} < S < 37\text{‰}$. The equation is:

$$V = 1449.14 + V_T + V_P + V_S + V_{STP} \quad (2.4)$$

$$V_T = 4.5721T - 4.4532 \times 10^{-2}T^2 - 2.6045 \times 10^{-4}T^3 + 7.9851 \times 10^{-6}T^4 \quad (2.5)$$

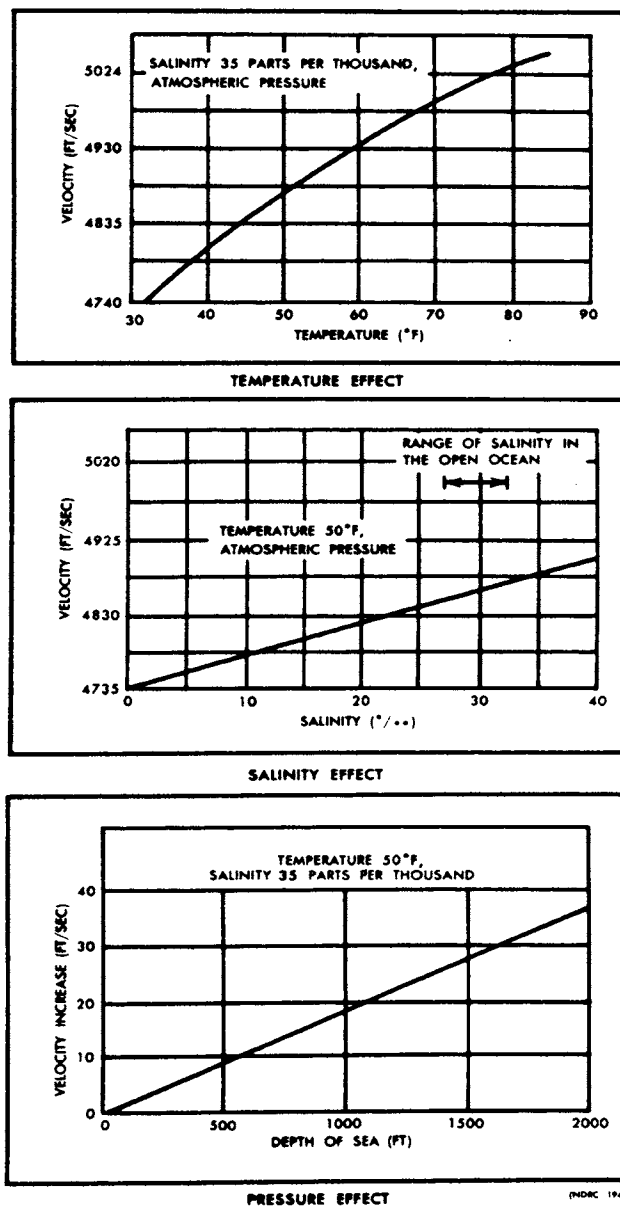


Figure 5. Effects of Variables on Sound Velocity

$$V_P = 1.60272 \times 10^{-1} P + 1.0268 \times 10^{-5} P^2 + 3.5216 \times 10^{-9} P^3 - 3.3603 \times 10^{-12} P^4 \quad (2.6)$$

$$V_S = 1.39799(S - 35) + 1.69202 \times 10^{-3}(S - 35)^2 \quad (2.7)$$

$$\begin{aligned} V_{STP} = & (S - 35)(-1.1244 \times 10^{-2} T + 7.7711 \times 10^{-7} T^2 \\ & + 7.7016 \times 10^{-5} P - 1.2943 \times 10^{-7} P^2 + 3.1580 \times 10^{-8} PT \\ & + 1.5790 \times 10^{-9} PT^2 + P(-1.8607 \times 10^{-4} T \\ & + 7.4812 \times 10^{-6} T^2 + 4.5283 \times 10^{-8} T^3) \\ & + P^2(-2.5294 \times 10^{-7} T + 1.8563 \times 10^{-9} T^2) \\ & + P^3(-1.9646 \times 10^{-10} T). \end{aligned} \quad (2.8)$$

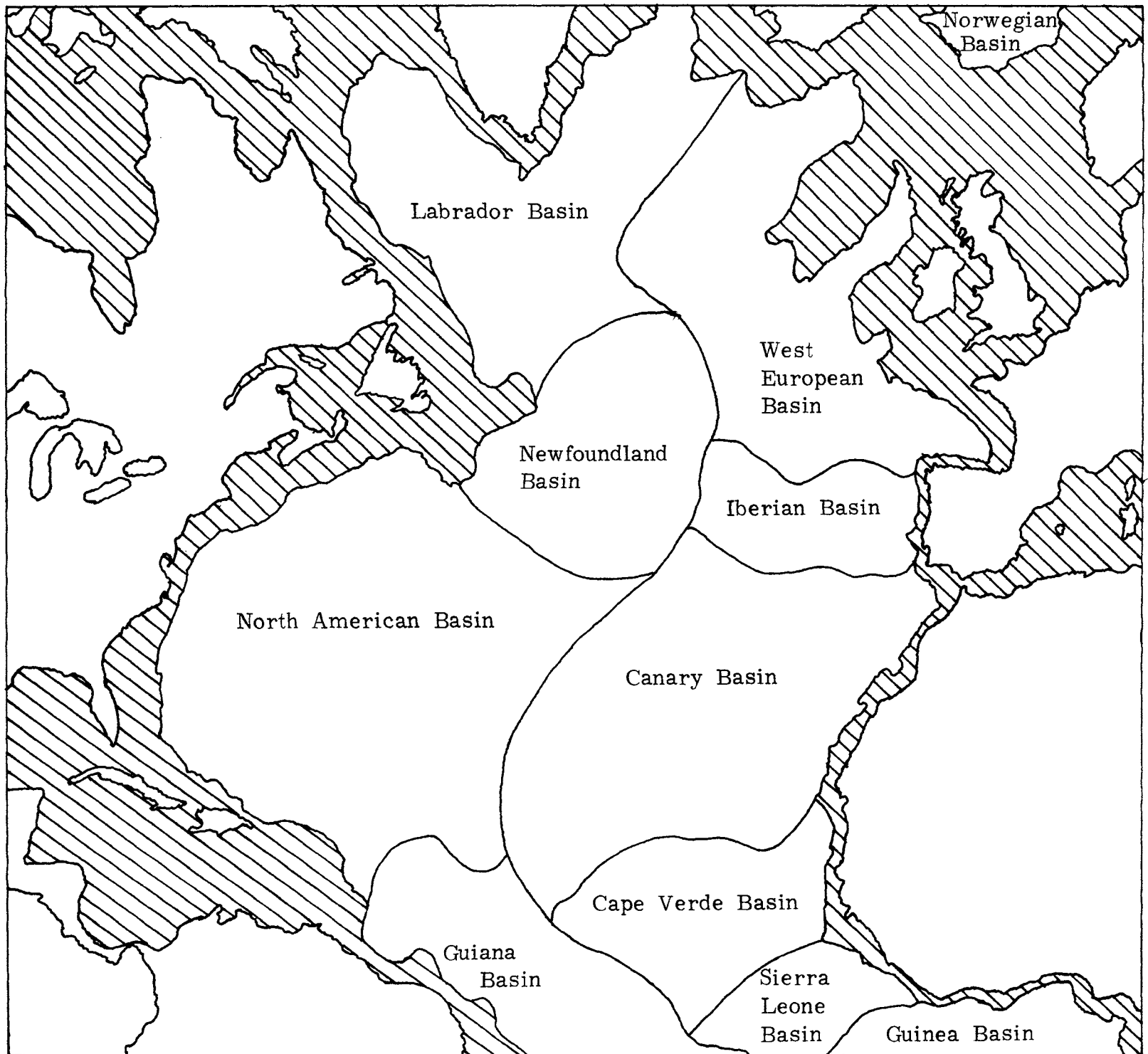
The units of temperature, pressure, salinity, and sound speed are °C, kg/cm², parts per thousand, and meters/second respectively. This equation may be used to predict sound speeds to within 0.30 m/sec over the indicated temperature, pressure, and salinity ranges.

Experimental multiple regression models have been investigated for a 4° by 4° square off the coast of New York in a study by Gillett¹². In that study models were developed to predict ocean temperature, salinity, and sound velocity. The sound velocity model yielded a prediction equation which produced results that

were nearly identical to values of Wilson's equation for that same area; plus the regression model was significantly simpler in form. It was established that sound velocity valid for only a very small area in the North Atlantic could be predicted adequately by regression equations. In his paper, he suggested that reasonable prediction equations could be obtained in larger areas of the North Atlantic Ocean. One of the purposes of this study is to pursue this idea and expand on its utility.

Generally, the speed of sound in the North Atlantic Ocean varies overall by less than five percent, its mean value being approximately 5,000 feet/second. As stated above, ocean sound speed has been demonstrated as a function of temperature, salinity, and pressure. Pressure produces a vertical gradient of approximately 0.016 feet/second/foot. On the other hand, temperature and salinity are the primary unpredictable variables which affect underwater sound speed. The natural variations in the temperature-salinity relationships of the major water masses occupying the deepwater physiographic basins below 1,000 fathoms (1 fathom = 6 feet = 1.83 meters) in the North Atlantic were investigated by Moore¹³ to determine whether these variations resulted in appreciable differences in sound speed. The generalized outline of these basins is indicated by Map I; the shaded regions being the extensions of the continental landmasses which would appear

Map I. Generalize Outline of North Atlantic Ocean Basins



if the present day sea level were lowered approximately 1,000 fathoms.

The major water masses in the North Atlantic below 1,000 fathoms are: North Atlantic Deep Water, North Atlantic Bottom Water, and South Atlantic Deep Water. The most pervasive water mass in the North Atlantic is the North Atlantic Deep Water, as it is located in all deep basins. Its temperature-salinity relation is almost linear, ranging roughly from approximately 3°C (37.4°F) at 1,000 fathoms to about 2°C (35.6°F) at its lower extent.

Differences between the temperature and salinity structures of the North Atlantic Deep and South Atlantic Deep Waters do not result in an appreciable change in average sound velocity. However, both water masses increase very slightly in temperature and salinity with increasing latitude, resulting in a very slight increase of sound speed at depth from south to north. In addition, sound speed is lower in the cooler, less saline North Atlantic Bottom Water than in the warmer, more saline North Atlantic Deep Water.

From the above discussion, it is apparent that sound velocity is more stable at the deeper underwater depths. It is this fact that led to this study. But, before a study such as this can be undertaken, a reliable source of data must be available. Through

the cooperation of the United States Naval Oceanographic Office (NAVOCEANO), an atlas of the North Atlantic Ocean¹⁴ was supplied along with numerous sound velocity articles. Originally over 100,000 oceanographic stations were available for that atlas. However, NAVOCEANO reduced the number of stations to a more tractable figure by eliminating undesirable or questionable data. Three criteria were established: (1) the oceanographic cast was required to extend at least to 100 meters' depth, (2) the surface measurements had to include both temperature and salinity, and (3) the deepest sound velocity value had to be greater than the value at the next-to-deepest depth in order to reject stations that did not extend to the depth at which minimum sound velocity occurs.

After applying the above three criteria, the output consisted of 22,832 observations. By an observation, in the atlas being considered, is meant the information necessary to draw and locate one sound velocity profile. Sound velocity information was computed from temperature, salinity, and depth data according to the equation developed by Wilson.

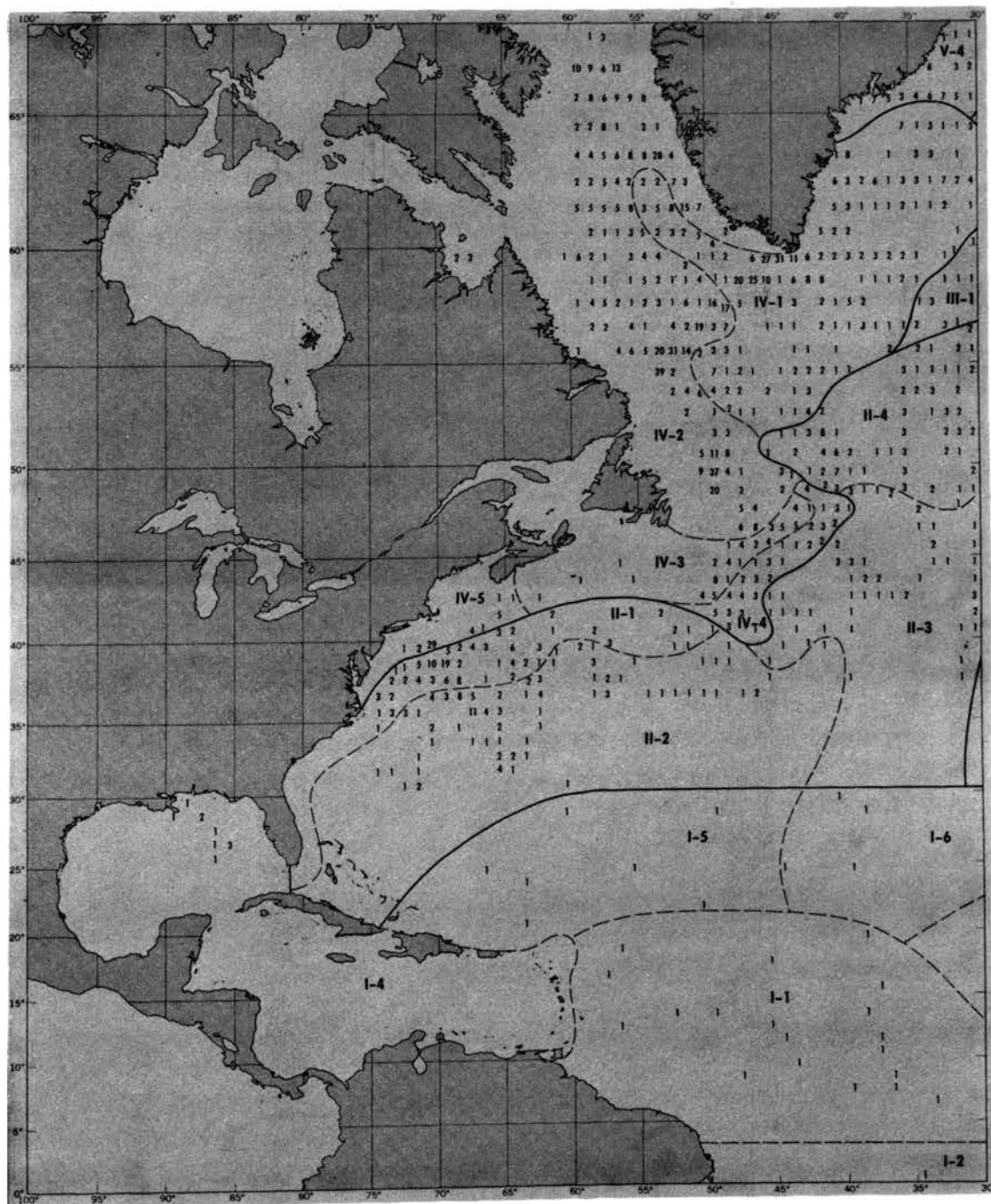
All observations were divided into seasons. The seasons were considered to consist of three month periods as follows: winter (January through March), spring (April through June), summer (July through September), and autumn (October through

December). The number of observations per season per one degree square was then plotted on four maps, one for each season. The purpose of the maps was to show the distribution of data in the North Atlantic Ocean. Map II illustrates the distribution of data for the summer season. The extent of the main geographic divisions are indicated by solid lines; subdivisions are outlined with dashed lines. The particular area of interest for this study lies in region II-2 of the map and is known as the Sargasso Sea of the Western North Atlantic.

From the sound velocity profiles, seasonal sound velocity profile envelopes were graphed for each region outlined on the data distribution maps. The winter, spring, summer, and autumn sound velocity profile envelopes for region II-2 are shown in Figures 6, 7, 8, and 9 respectively. In Figure 8 the shaded area indicates a subenvelope, representing the subrange of sound velocities within which a majority of the profiles lie. These four figures substantiate the idea of building more reasonable and feasible sound velocity models below some critical depth for large portions of the North Atlantic.

Table I gives the range of depths and sound velocities at the sound channel axis for the Sargasso Sea. Table II gives the number of profiles for the same area.

Station data of the atlas was originally stored on 75 tapes



Map II. Distribution of Data and Sound Velocity Structure Domains of the North Atlantic, Summer

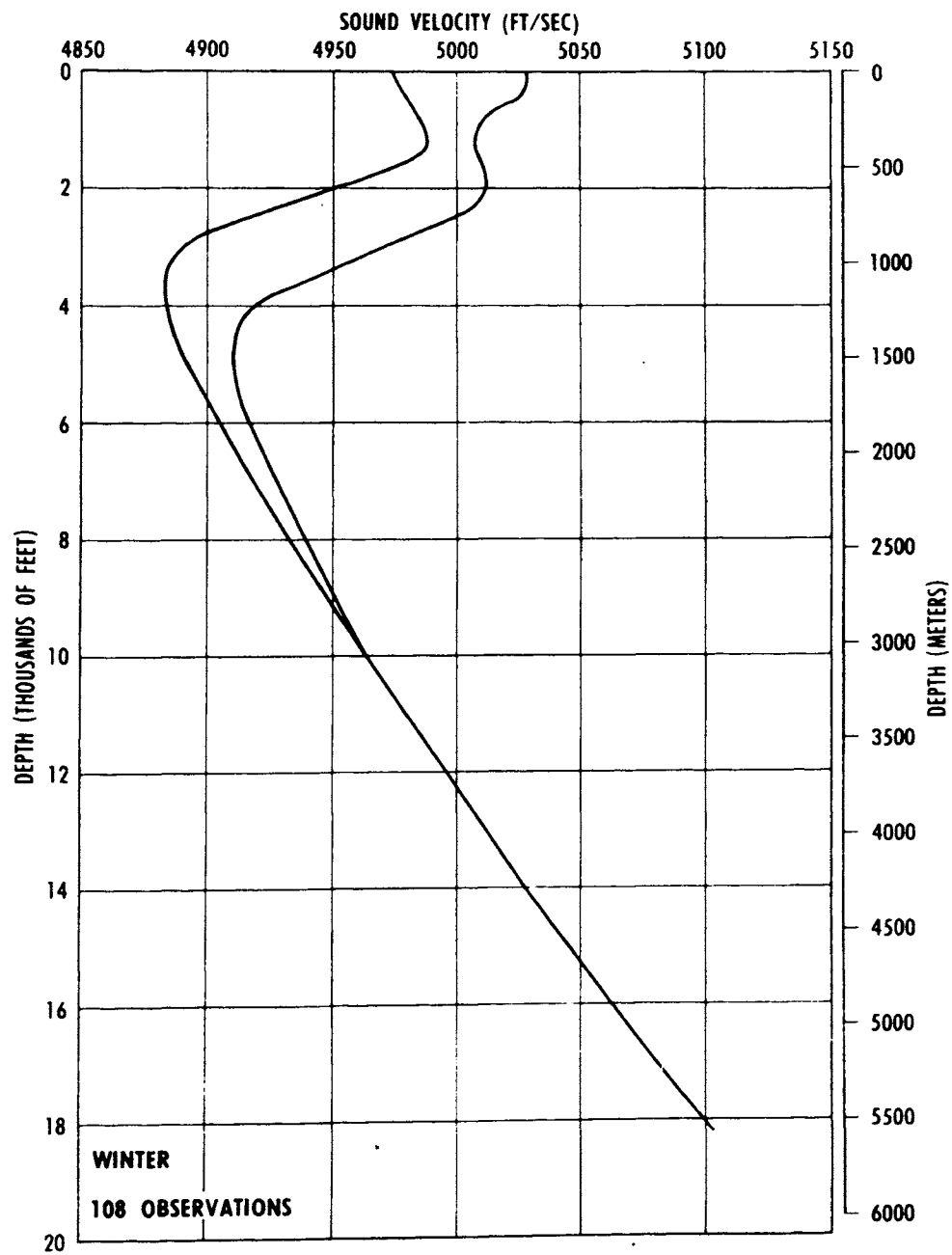


Figure 6. Sound Velocity Structure for Region II-2, Winter

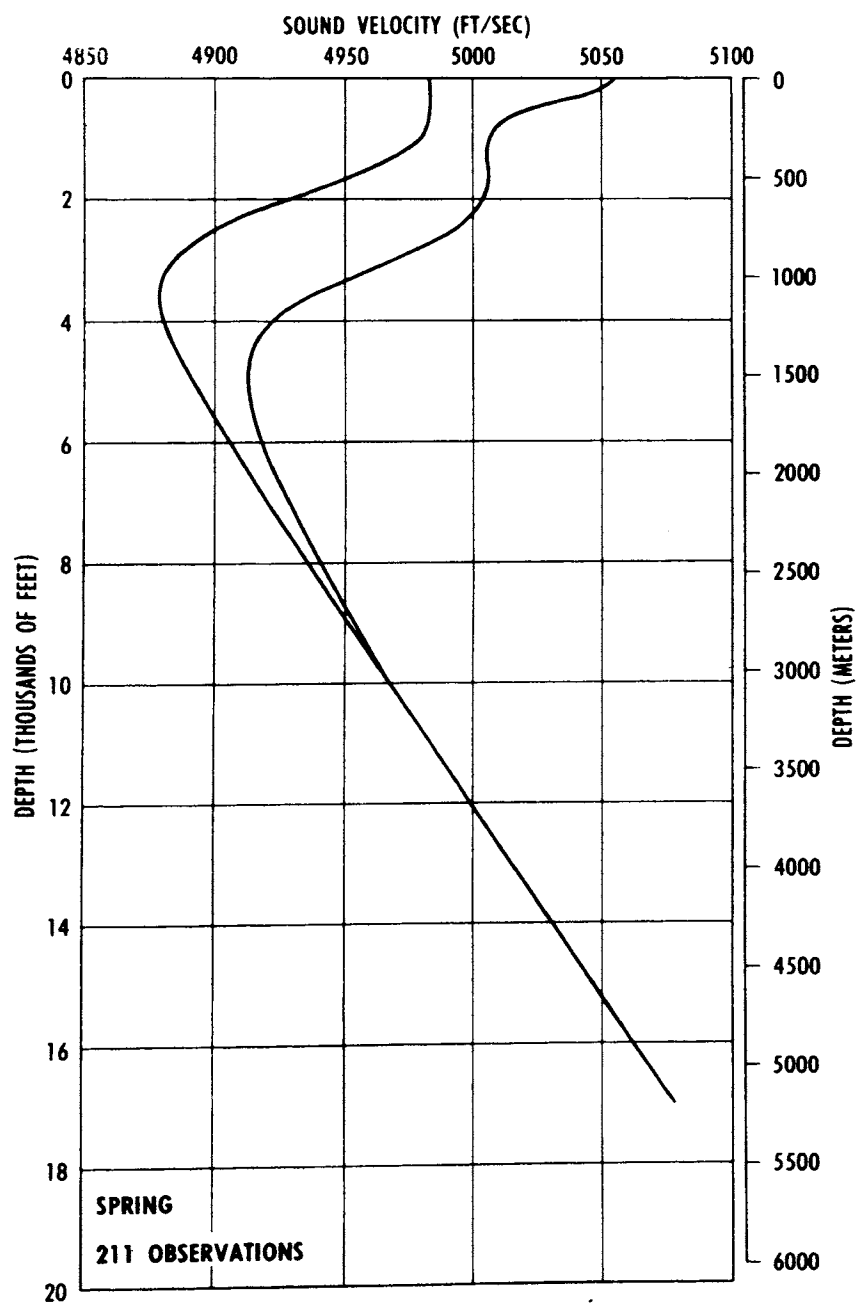


Figure 7. Sound Velocity Structure for Region II-2, Spring

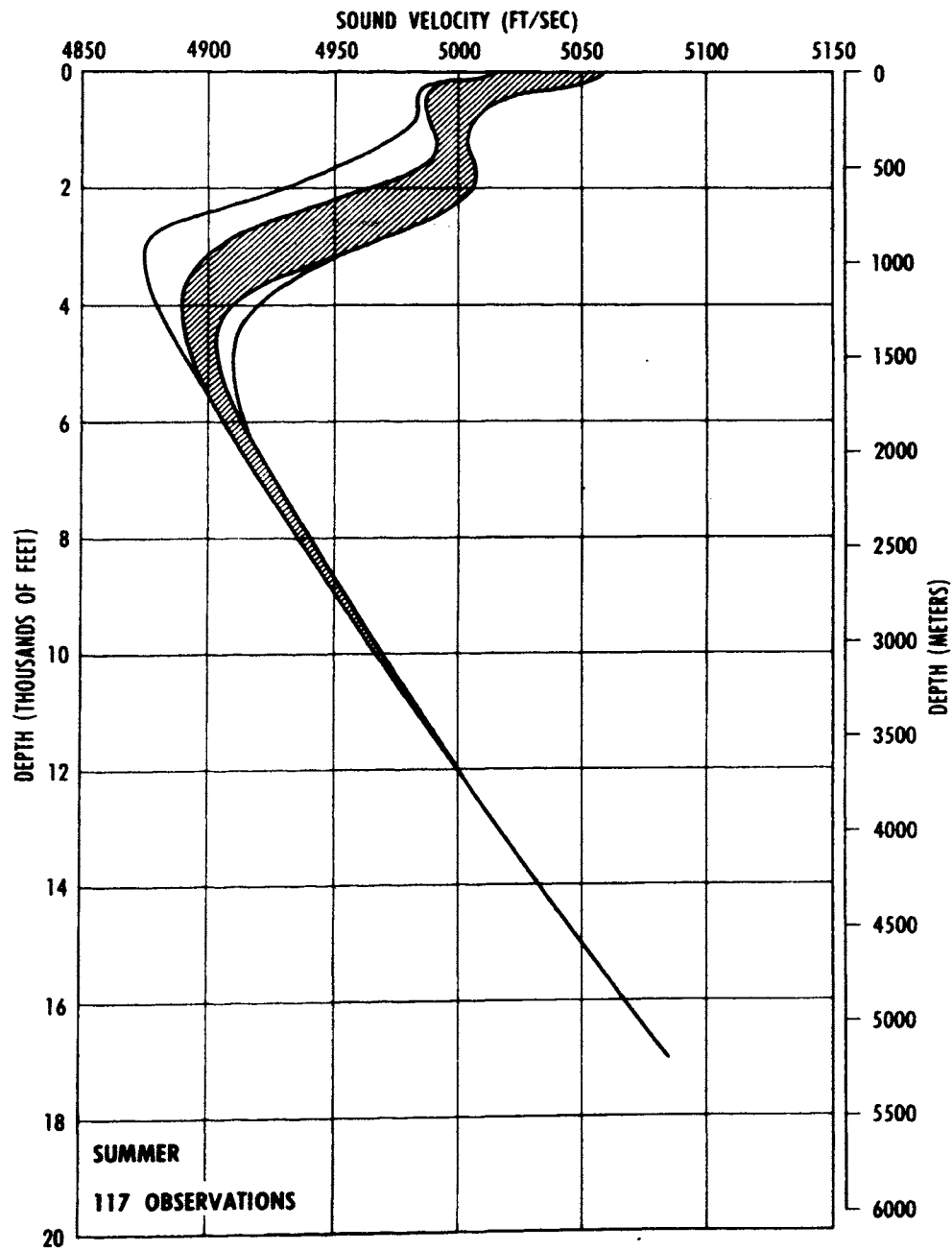


Figure 8. Sound Velocity Structure for Region II-2, Summer

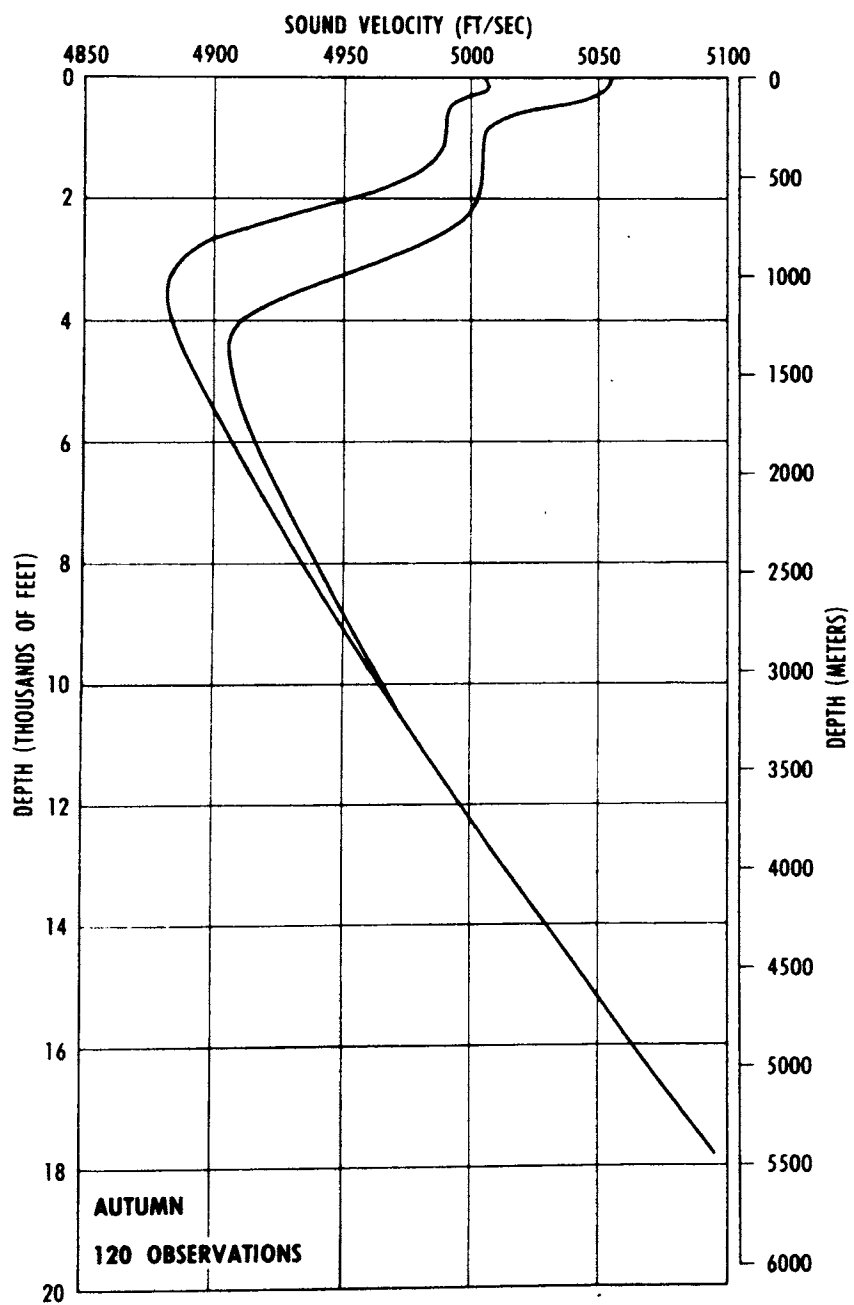


Figure 9. Sound Velocity Structure for Region II-2, Autumn

SEASON	DEPTH (FT)		VELOCITY (FT/SEC)	
	MIN	MAX	MIN	MAX
WINTER	3600	4900	4885	4910
SPRING	3750	4900	4879	4913
SUMMER	3100	5200	4875	4910
AUTUMN	3600	4450	4881	4906

Table I. Range of Depths and Sound Velocities at the Sound Channel Axis in the Sargasso Sea of the Western North Atlantic

SEASON	NUMBER OF PROFILES
WINTER	108
SPRING	211
SUMMER	117
AUTUMN	120

Table II. Number of Profiles in the Sargasso Sea of the Western North Atlantic

of card-line images. However, through the efforts of Yergen¹⁵, the ocean station data is now stored on four "rapid access" tapes. The tape containing the data for the Sargasso Sea and surrounding area plus the program to access the tape were made available by NAVOCEANO.

III. DISCUSSION

At present the highest accuracy achievable by computing sound speed from oceanographic station data consisting of observations of temperature and salinity at various depths is at best within a few feet per second. This is because of errors of measurement and systematic errors of the sound speed equation. Although sound velocity in the ocean is a function of depth, temperature, and salinity, there exists a pattern at the deeper depths in certain areas of the North Atlantic Ocean where sound velocity seems predictable as a function of other characteristics. Since the Sargasso Sea is so calm and of such a stable nature, it appears reasonable that a near homogenous population might exist with a fixed pattern. It is the objective of this study to find characteristics in the Sargasso Sea that would eliminate the need for on-location measurement of temperature and salinity to predict sound velocity without losing the accuracy of Wilson's equations. The characteristics investigated were seasonal factor, latitude, longitude, and depth.

In general no relationship exists between season, latitude, longitude, temperature, and salinity. However, some areas of the ocean, just because of the nature of the body of water, have established patterns of salinity and temperature with respect to position. Now the question arises whether the Sargasso Sea is an

area where temperature and salinity have a predictable pattern or arrangement. With the assistance of graphic software it was displayed through a series of contour maps that temperature and salinity profiles at the deeper depths of the Sargasso Sea do have a predictable pattern that would allow sound velocity to be represented by a simple function. It was demonstrated that both temperature and salinity at a given depth plane change gently with respect to position to yield a smooth response surface. In addition, all the deeper depth planes have similar characteristics.

Adjacent to the west side of the Sargasso Sea is the Gulf Stream which rapidly shifts position depending on the season of the year. Consequently, the boundaries of the Sargasso Sea are constantly being altered. In order that a near homogenous area could be considered, the boundaries of the Sargasso Sea were investigated for all seasons. This investigation defined the area of interest as 30° to 38° N latitude and -48° to -68° W longitude. A diagram revealing the data distribution for this area is shown in Figure 10 at the depth plane of 2500 meters.

The utility of multiple regression analysis was explored in summarizing the entire body of collected data. The manner in which the observations were collected limits the amount of available data at the deeper depths. Only the best data available were used.

LATITUDE	38	1	1	2	2	2	3	0	0	0	1	1	0	0	0	0	0	1	0	0
	37	2	0	3	0	1	2	0	0	0	1	2	0	0	0	1	1	1	1	0
	36	8	11	2	0	1	2	0	0	0	0	0	0	0	0	0	0	0	0	0
	35	3	0	9	5	0	1	0	0	0	0	0	0	1	0	0	0	0	0	1
	34	4	3	4	0	1	0	0	0	0	1	1	0	0	0	0	0	0	0	0
	33	0	2	3	2	2	1	1	1	1	0	0	0	0	0	1	0	2	0	1
	32	0	2	3	3	1	0	0	0	0	0	1	1	0	1	0	0	0	0	1
	31	2	0	3	1	1	1	0	1	1	1	0	0	0	0	0	0	0	1	0
	30																			
		-68	-66	-64	-62	-60	-58	-56	-54	-52	-50	-48								
		LONGITUDE																		

Figure 10. Data Distribution at 2500 Meters

Appendix A contains the completely documented computer program activated on the IBM 360/50 computer and used for all regression analysis within this paper. In the program is developed statistical and computer techniques and methods for summarizing data to support Navy requirements in research. If $n-1$ equals the number of independent variables, then n is the number of independent variables plus the dependent variable. Thus, there will be $n-1$ simultaneous linear algebraic equations to solve. These equations, known as the normal equations, have a solution that usually results in handling a square matrix of order $2n-1$ for stepwise multiple regression analysis procedures. However, through the efforts of Efroymson¹⁶, this matrix can be handled in storage as an $(n \times n)$ square matrix. Thus, this allows an approximate reduction by a factor of four of core storage for a given number of independent variables. And, for a given size of core storage a greater number of independent variables are available. It should be noted that errors were encountered in the article by Efroymson and are corrected in Appendix A.

Although there are $n-1$ independent input variables, the number of independent variables possible for regression could become more numerous when other independent variables such as cross products are considered. To differentiate between an input variable and a regression variable, the first shall be referred to as

a "variable" and the latter as a "term". The new techniques of independent term generation in the computer program is a significant contribution to the regression problem.

In the use of regression analysis it is necessary to know, or to assume, (1) the major independent variables, or main effects; and (2) a functional relationship between these variables, or a regression model. The oceanographic problem becomes one of searching for adequate models. It is indicated by graphic displays that adequate models can be derived for many ocean areas from the present archive of oceanic data. When working with regression analysis, the error between the predicted value and the actual value of the dependent variable for a particular observation is known as the residual (e_i = residual for observation i). If m is the number of observations, then a regression equation is

sought which will minimize $\sum_{i=1}^m e_i^2$. It is assumed that e_i is a random variable with mean zero and some unknown variance σ^2 , that is $E(e_i) = 0$, $V(e_i) = \sigma^2$. Furthermore, the assumption is made that e_i and e_j are uncorrelated, $i \neq j$, so that $\text{cov}(e_i, e_j) = 0$.

Let c_i denote the true value of sound velocity in sea water for observation i , and let \hat{c}_i denote the predicted value. Then the residual of observation i is

$$e_i = c_i - \hat{c}_i. \quad (3.1)$$

If this equation is juggled properly, according to Draper and Smith¹⁷, it can be rewritten as

$$\sum_{i=1}^m (c_i - \bar{c})^2 = \sum_{i=1}^m (c_i - \hat{c}_i)^2 + \sum_{i=1}^m (\hat{c}_i - \bar{c})^2 \quad (3.2)$$

where \bar{c} is the average sound velocity of the m observations.

$c_i - \bar{c}$ is the deviation of observation i from the overall mean; and so, the left-hand side of equation (3.2) is the sum of squares of deviations of the observations from the mean. Since $c_i - \hat{c}_i$ is the deviation of the i th observation from its predicted or fitted value, and $\hat{c}_i - \bar{c}$ is the deviation of the predicted value of the i th observation from the mean, equation (3.2) can be expressed in the following form.

$$\begin{array}{ccccc} \text{Sum of squares} & & \text{Sum of squares} & & \text{Sum of squares} \\ \text{about} & = & \text{about} & + & \text{due} \\ \text{the mean} & & \text{regression} & & \text{regression} \end{array} \quad (3.3)$$

One measure of the goodness of fit of a regression equation is the square of the multiple correlation coefficient (R^2). By definition the ratio

$$R^2 = \frac{\text{Sum of squares due to regression}}{\text{Sum of squares about the mean}} = \frac{\sum (\hat{c}_i - \bar{c})^2}{\sum (c_i - \bar{c})^2}. \quad (3.4)$$

R^2 is a measure of the usefulness of the regression terms, other than the constant term, in the model. If the prediction is perfect,

then $R^2 = 1$. $R^2(100)$ is the percent of the total variation about the mean (\bar{c}) that is accounted for by regression. Ideally a suitable regression model is sought that has the least number of terms as possible with a high R^2 as close to one as possible.

All ocean station data used within this study were collected at specific depth planes. Each observation, beginning at 500 meters and extending to the ocean floor, had a recorded depth of 500, 600, 800, 1000, 1200, 1500, 2000, 2500, 3000, 4000, or 5000 meters. The data contained on the magnetic computer tape had a major sort on the depth planes mentioned above. Each observation contained the following information: (1) day of month, (2) month, (3) year, (4) hour, (5) latitude in thousandths of a degree, (6) longitude in thousandths of a degree, (7) depth in meters, (8) temperature in degrees centigrade, (9) salinity in parts per thousand, (10) ∇_t , (11) sound velocity in feet per second, (12) oxygen content, (13) quality code, and (14) bottom depth. Table III exhibits the average temperature and salinity plus the number of observations and average sound velocity at each depth plane from 500 meters to the ocean floor.

The accuracy obtained by Wilson's sound velocity equations is also the accuracy required in this study if its objectives are to be fulfilled. In other words, a successful model must have a standard deviation of sound velocity of approximately 1 ft/sec or

<u>DEPTH PLANE</u>	<u>AVERAGE TEMPERATURE</u>	<u>AVERAGE SALINITY</u>	<u>AVERAGE SOUND VELOCITY</u>	<u>NUMBER OF OBSERVATIONS</u>
500	16.6838	36.2895	4991.312	336
600	15.3909	36.0725	4985.699	333
800	11.3923	35.4947	4950.652	328
1000	7.5268	35.1401	4913.566	316
1200	5.4328	35.0594	4897.093	308
1500	4.3490	35.0109	4898.855	261
2000	3.6726	34.9779	4917.214	182
2500	3.3108	34.9686	4940.187	130
3000	2.9165	34.9507	4962.890	95
4000	2.3615	34.9079	5012.273	60
5000	2.2330	34.8860	5068.609	10

Table III. Ocean Station Data at Specified Depth Planes

less with a reasonable number of independent terms that are not dependent on data sampling.

A review of Figures 6, 7, 8, and 9 in Chapter II suggested that 3000 meters should be the maximum critical depth considered. A simplified regression model of sound velocity within the specified accuracy was easily obtained for depth planes of 3000 meters and below. Essentially, the independent term of depth controlled the model. This expected result warranted an investigation of 2500 meters as the critical depth.

Since the sound velocity profiles begin to show some scattering at a depth of 2500 meters, it was puzzling whether season had any accountable significance in this behavior. Graphs of month vs temperature, month vs salinity, and month vs sound velocity showed no predictable pattern. This strongly indicated that season would not be a significant factor of sound velocity below 2500 meters in the Sargasso Sea. To reassure this conclusion, month was considered as one of the possible input variables with the hope that it would be rejected (not enter in regression).

In an effort to locate all independent terms which have the slightest correlation with sound velocity as a function of position, many regression models with a low F-level of 1.25 were investigated in a systematic manner with the sole purpose of collecting a library of terms. The input variables considered in building this

library of independent terms were month, latitude, longitude, and depth and at times will be referred to as M, L, LN, and D respectively. In addition sound velocity will be denoted by SV.

The first part of this systematic approach involved building a regression model for each combination of the four input variables taking two at a time with sound velocity as the dependent variable. Thus, the number of computer runs executed was six ($4!/2!2!$). Each computer run had 99 independent terms available for regression with the highest power on any particular input variable not exceeding nine. Equivalently, this represents all possible combinations of the two input variables being considered. These computer runs were accomplished by use of NORMAL mode as explained in Appendix A. Next a regression model for each combination of the four input variables taking three at a time was implemented with sound velocity as the dependent variable and resulted in four ($4!/3!1!$) runs. Each computer run had 99 independent terms available for regression with three as the highest power on some input variables and four on others. Again these computer runs were carried out as defined by NORMAL mode. Finally, all four input variables were considered in a single regression model with sound velocity as the dependent variable. This regression model had 80 independent terms available for regression under NORMAL mode with the highest power of any given

input variable being two.

After recalling the contour maps previously discussed, the decision was made that the behavior of all input variables would not justify any independent terms in the above computer runs with a power larger than five. When re-examining all the independent terms with powers higher than five, it was found that these terms entered at a low F-level with neither significantly decreasing the standard error of sound velocity nor increasing the value of R^2 . In fact, many times no change was evident by the addition of one of these terms.

After collecting all independent terms that entered into regression from all above computer runs and eliminating the terms with powers higher than five, the following independent terms comprise the library of terms: D , D^2 , D^3 , D^4 , $(LN)D^3$, $(LN)^4$, $(LN)^4D^4$, L , LD^3 , $L(LN)^2$, $L^2(LN)D$, L^4 , L^4D , L^4D^5 , M , MD , $M(LN)$, $M(LN)^4D^2$, M^2D^5 , $M^2(LN)^4D^2$, M^3 , M^3D , M^3D^2 , M^3D^3 , $M^3(LN)^4D^2$, $M^3L^2(LN)$, $M^3L^4(LN)^4$, M^4L^3 , and M^5D . One should keep in mind that this library has many insignificant independent terms because of the low F-level specified in the regression program plus the massive term collecting procedures.

When permitting the entire library of terms to become available as independent terms for regression, many excellent models were established through the use of the ACCEPT mode in the

computer program. However, keeping in mind the objectives of this study, the most satisfying model was

$$\begin{aligned} SV = & 4803.75202 + 4.134663 \times 10^{-3} D + 1.033088 L \\ & + 8.623 \times 10^{-12} L D^3 - 1.948 \times 10^{-9} L^4 D \end{aligned} \quad (3.5)$$

with the standard deviation of sound velocity from the supplied data being 1.02 ft/sec and the multiple correlation coefficient squared having a value of 0.9991 or 99.91%. The order of entry for each independent term plus its contribution to reducing the standard error of sound velocity and increasing R^2 are shown in Table IV.

As previously suspected, this model rejected a seasonal factor by not allowing any independent term that was a function of month to enter regression. However, if sound velocity is to be a function of position, it is somewhat surprising that none of the independent terms which were a function of longitude entered regression. It should be noted that the next term that would have entered into the regression model was a function of longitude. The validity of the independent terms in equation (3.5) will be discussed later in this chapter.

This model is satisfying when considering its simplicity, the accuracy inherent in the low standard error and high R^2 , the large area of interest, and the elimination of on-location data

<u>STEP NUMBER</u>	<u>INDEPENDENT TERM</u>	<u>STANDARD ERROR OF SOUND VELOCITY</u>	<u>MULTIPLE CORRELATION COEFFICIENT SQUARED (%)</u>
1	D	1.9469	99.65%
2	LD ³	1.1189	99.89%
3	L	1.0981	99.89%
4	L ⁴ D	1.0200	99.91%

Table IV. Variables Entering Regression

collection. Nevertheless, a different approach was tested in an attempt to improve the above model for the same critical depth of 2500 meters.

Since temperature and salinity are gently changing within the deeper depth planes, it was thought that an average temperature and salinity at the various depth planes, along with the variables latitude and depth, might yield a more precise model. The average values of temperature and salinity employed at the respective depth planes are listed in Table III and shall be referred to as T_c and S_c respectively.

Again the same systematic approach was utilized with respect to the input variables of constant temperature, constant salinity, and depth. In other words, the first three computer runs consisted of building a regression model for each combination of the three input variables taking two of them at a time. Then all three input variables were made available in a single computer run.

After reviewing all four computer runs, no new terms were found to be significant. In a final effort, the input variables latitude, depth, constant temperature, and constant salinity were combined into a single computer run. The following model resulted.

$$SV = 4705.30155 + 0.48452T_cS_c + 5.887591 \times 10^{-2}D + 1.042915L \quad (3.6)$$

This model has a standard deviation of sound velocity of 1.0256 ft/sec and a R^2 of 99.90%. Although this regression equation is extremely simple, it has the disadvantage of having two additional input variables (T_c and S_c) whose values are a function of the existing data. Since this model did not improve either the standard deviation or R^2 , it can be concluded that the model of equation (3.5) is more profitable.

It was reasonable to now conclude that the critical depth can be raised from 3000 meters to 2500 meters with the model represented by equation (3.5). However, the question should be asked whether it is feasible for 2000 meters to become the critical depth. An investigation of 2000 meters as the critical depth led to the following results: (1) standard deviation of sound velocity of approximately 1.25 ft/sec, and (2) multiple regression correlation coefficient of approximately 99.88%. Since this is not within a reasonable limit of the desired accuracy, it can now be concluded that the critical depth as established by the criteria of this study is 2500 meters; and, the best model below this critical depth is represented by equation (3.5).

The precision of the sound velocity model depends upon the precision of the supplied data and upon the fit of the model to the data. The difference between the computed data and supplied data may be used to estimate the precision of the results. To further

explore the utility of equation (3.5), Figure 11 illustrates the distribution of the residuals for the 295 observations utilized in this study. Furthermore, 139 residuals had a value less than zero with the remaining 156 residuals being a value greater than zero. The longest run of residuals with the same sign was 38 at the depth plane of 3000 meters.

Regression analysis appears to have considerable potential as a technique for estimating sound velocity. However, the physical reality of the estimates must also be considered, since it is always possible to improve the statistical measures of goodness of a regression-model estimate by merely adding additional terms to the model. From a physical viewpoint these terms may be nonsense terms. Therefore, some justification of the terms in equation (3.5) will follow.

Deep water is produced by the cooling of the surface water at high latitudes in late winter. This cooling increases the density of the surface water to the point at which it is able to sink to the bottom and flow southward filling the deep basins. In the Atlantic Ocean there is a large water mass known as the North Atlantic Deep Water which comprises about half the total volume of the ocean and which is clearly of North Atlantic origin. This fact suggests the investigation of the change of temperature and density with latitude.

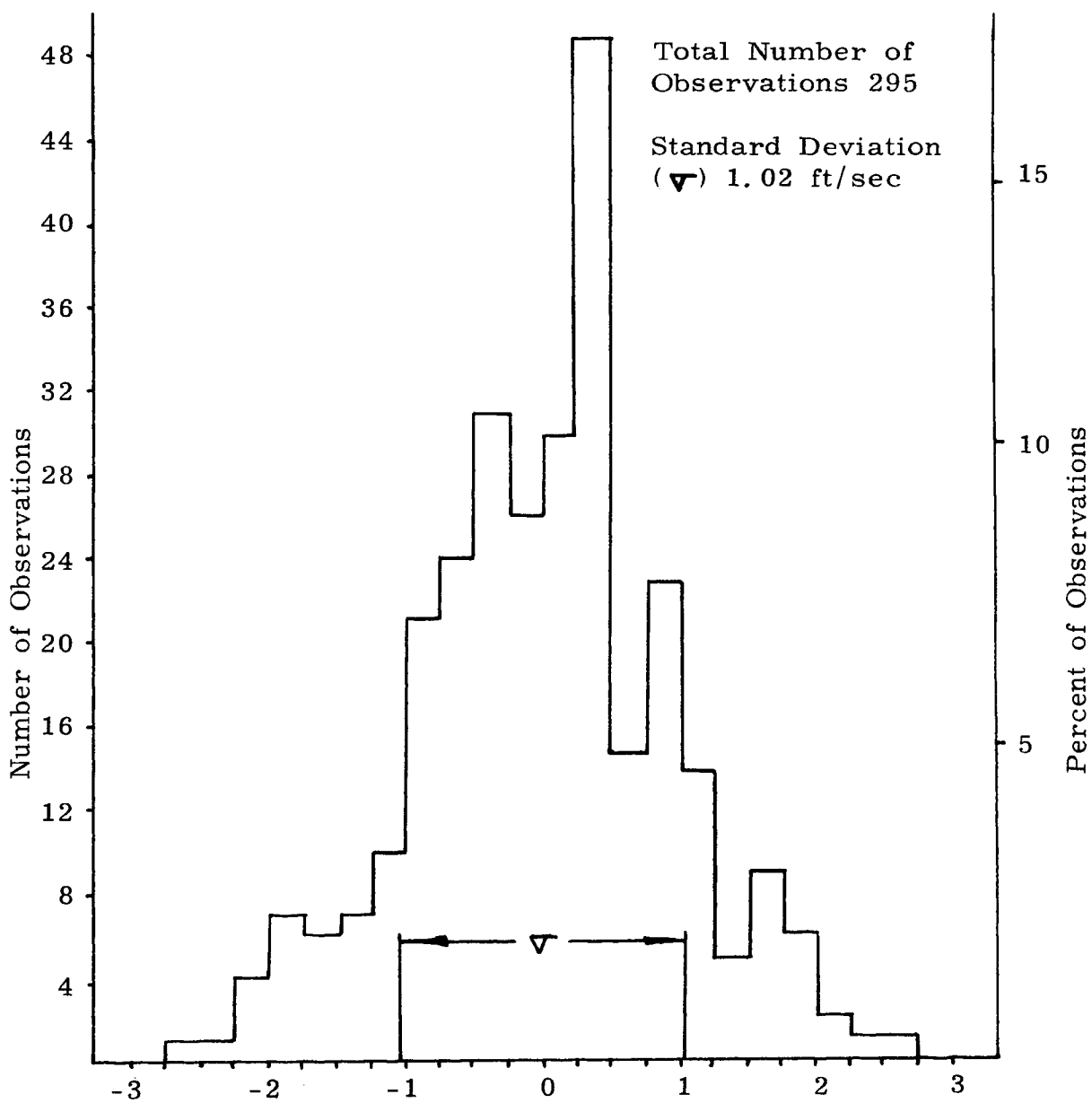


Figure 11. Sound Velocity Residuals, ft/sec

Many scattergram plots were examined for this particular area of the Sargasso Sea at the depth plane of 2500 meters. Two rewarding results were discovered: (1) a definite increase in sound velocity with an increase in temperature that appeared close to being linear, and (2) a slight increase in sound velocity with an increase in latitude. These results prompted the investigation of latitude with respect to temperature. The area of interest at a depth of 2500 meters was divided into strips, each 1° of longitude in width and eight degrees of latitude in height. Another way to describe this division would be to let each column of Figure 10 become equivalent to one strip.

A scattergram plot of latitude vs temperature was made for each strip. A typical scattergram plot is illustrated in Figure 12 for a constant longitude of -65° . After combining all the information obtained from the plots, it was found that an increase of latitude in a northern direction resulted in an increase in temperature which also implies an increase in sound velocity. But, this is not surprising, for, as Moore¹³ pointed out, the North Atlantic Deep Water increases very slightly in temperature and salinity with increasing latitude, resulting in a very slight increase of sound velocity at depth from south to north. This fact supports predicting sound velocity as a function of latitude as is done in equation (3.5). A scattergram plot revealed that an increase in

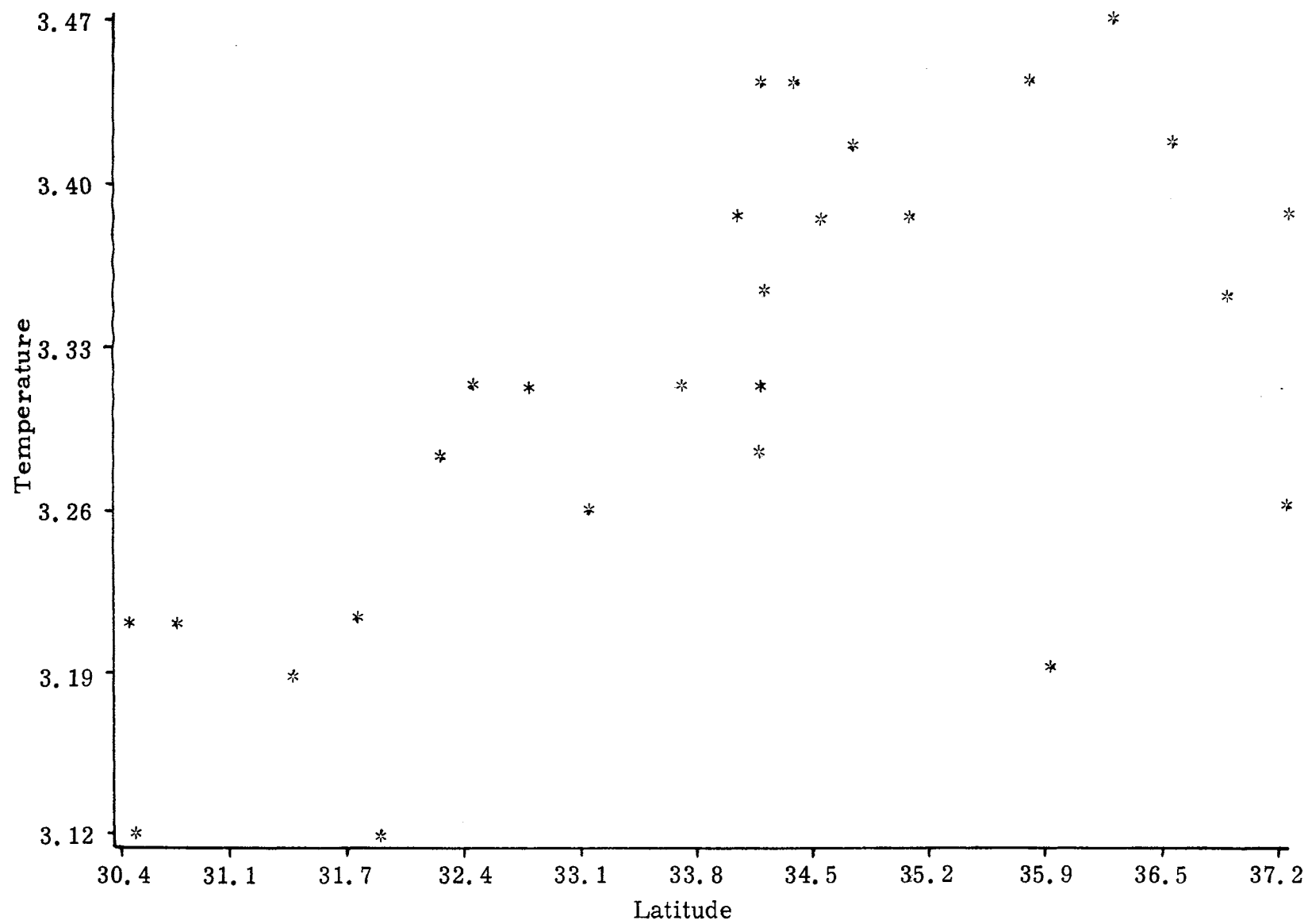


Figure 12. Scatter Diagram of Latitude vs Temperature

depth results in a close to linear increase in sound velocity.

Of course, depth as a linear independent term needs no justification since in equation (2.3) Kinsler and Frey¹⁰ have established sound velocity as a linear function of depth. However, since salinity contributes such a small amount to this equation, it could be rewritten as

$$SV = k + aD + f(t) \quad (3.7)$$

where k is a constant and a is the coefficient of the linear independent term of depth. This leaves $f(t)$ to be established.

Using temperature as the dependent variable, a regression model was developed with latitude and depth as input variables. This computer run demonstrated temperature for the area of interest to be a highly correlated function of the independent terms D , L , and LD^3 . Thus, equation (3.7) nearly takes the form of equation (3.5). The only independent term not appearing is L^4D ; but, it was the last or least correlated independent term that entered into regression equation (3.5). L^4D might account for the part of equation (2.3) ignored by estimating it by equation (3.7).

For use in oceanographic work it is generally more convenient to express sound velocity in terms of depth instead of pressure. The conversion of pressure to an equivalent depth may be done by dividing the depth into thin layers and summing the product of the average density in each layer and the thickness of

each layer. Wilson¹⁸ formulated this numerical integration as $P_i = \sum \bar{g}_\Theta \bar{\rho}_i t$ where P_i is the pressure at the bottom of layer i , $\bar{\rho}_i$ is the average density between each layer, t is the thickness of the layer, and \bar{g}_Θ is the acceleration due to gravity at the latitude Θ and the mean depth of the layer. Since sound velocity is a function of pressure, the above numerical integration further substantiates the validity of the sound velocity model represented by equation (3.5) as a function of depth and latitude. However, since latitude is present in the sound velocity model, and it is a function of both temperature and gravity, the relative amount of latitude accredited to temperature and gravity respectively is undetectable.

It was concluded that the regression model, as expressed in equation (3.5), is a physically acceptable estimator of sound velocity for the area covered by these analyses.

IV. CONCLUSION

In this study the desired functional relationship of sound velocity in terms of position only was determined from analytical and theoretical considerations and from an investigation of scatter diagrams prepared from the data being analyzed. A regression model of sound velocity was developed consisting of latitude and depth that is capable of estimating sound velocity below a critical depth in a large area of the North Atlantic Ocean to a standard deviation of approximately 1 ft/sec. The critical depth established for the desired accuracy was found to be 2500 meters.

From both a statistical and a physical viewpoint, relatively simple regression models have a considerable potential as estimators of sound velocity with a high degree of accuracy at the deeper depth planes. It is assumed such models can be derived for many ocean areas utilizing the present archive of ocean station data.

On the assumption that the regression model is reasonably valid, the regression technique has the capability of eliminating the collection of ocean station data at the deeper depths and, thus, resulting in a substantial saving. In addition, it provides an effective method of editing sound velocity data for erroneous observations.

This study suggests regression techniques may be used as a

new approach to summarizing archived ocean station data that is more objective and amenable to computer usage than present methods.

As an outgrowth of this study it is recommended that regression models be investigated in other areas of the ocean with some correlation between accuracy and critical depth. When shallower critical depths are considered, seasonal effects could become a significant factor.

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VI. VITA

Richard Roland Kunkel was born June 5, 1945 in St. Louis, Missouri. His primary and secondary education was also received in St. Louis. His secondary education was highlighted by his attendance at Missouri Boy's State.

In September 1963 he started his undergraduate training upon entering the University of Missouri - Rolla. Before receiving his Bachelor of Science degree in Applied Mathematics in May 1967, he had experienced membership and offices in honorary and professional societies.

Initially enrolled in the Graduate School of the University of Missouri - Rolla in June 1967, he maintained the Seismic Station of the university in fulfillment of his assistantship for the summer of 1967. In September 1967 a National Science Foundation Grant was awarded to him. He received his Master of Science degree in Geophysical Engineering in January 1969. He continued to hold the National Science Foundation Grant while working toward his Doctor of Philosophy degree in Geophysical Engineering.

His professional experience includes working as an Industrial Engineer during the summer of 1966 for United States Steel Corporation and as an Oceanographer for the United States Naval Oceanographic Office during the summer of 1969. It should be noted that he has been associated with naval projects since Sep-

tember 1967.

On June 3, 1967 he was married to the former Karen Frances Short. At the time of this writing, they have one child, a boy named Timothy Paul.

VII. APPENDIX A

MULTIPLE STEPWISE REGRESSION PROGRAM
WITH NEW TERM GENERATING TECHNIQUES

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I. INTRODUCTION

A regression analysis provides a relationship between a dependent variable and one or more independent variables. In this program the linear relationship is estimated by least square methods. This program proceeds in a stepwise fashion performing successive regression analyses, including the "best" term first, finding next the term whose additional contribution to the first is greatest, and so on.

The use of a stepwise procedure not only has the advantage of providing useful analytic information to the user, but also provides protection against failures in computational accuracy.

II. GENERAL DESCRIPTION

This program computes a sequence of multiple linear regression equations in a stepwise manner. Up to fourteen original variables can be used. The variable to be considered as the dependent variable (Y) can be specified on a control card. The remaining variables are considered as the independent variables. If the user would wish not to use all of the independent variables, then a change of format on a control card will allow the use of only the specified independent variables.

Along with each independent variable is associated a maximum power. The maximum power of an independent variable is the highest allowed power to which that independent variable may be raised. The independent variables are then expanded to a new set of terms which includes all possible combinations of the independent variables to varying powers within the maximum power of each independent variable. For example, if three independent variables are used (Z_1, Z_2, Z_3) with a maximum power of 1, 2, and 2 respectively, then the independent terms generated are

$$X_1=Z_3, X_2=Z_3^2, X_3=Z_2, X_4=Z_2Z_3, X_5=Z_2Z_3^2, X_6=Z_2^2, X_7=Z_2^2Z_3,$$

$$X_8=Z_2^2Z_3^2, X_9=Z_1, X_{10}=Z_1Z_3, X_{11}=Z_1Z_3^2, X_{12}=Z_1Z_2, X_{13}=Z_1Z_2Z_3,$$

$$X_{14}=Z_1Z_2Z_3^2, X_{15}=Z_1Z_2^2, X_{16}=Z_1Z_2^2Z_3, \text{ and } X_{17}=Z_1Z_2^2Z_3^2.$$

Note that the expanded set contains terms (Xs') and not variables (Zs').

The number of independent terms is $\sum_{i=1}^{NM1} (MAXP_i + 1) - 1$, where NM1 is the number of independent variables and $MAXP_i$ is the maximum power of independent variable i .

As can be seen, the list of independent terms could become exorbitant. However, this program includes a system for the user to control the number of terms by specifying the program mode. Three program modes are possible: NORMAL, ACCEPT, and DELETE. If all possible combinations are desired as above, then the NORMAL program mode is used and the terms generated comprise a complete set of terms. However, if only selected terms are desired, then a subset of the complete set of terms can be designated in the ACCEPT program mode. For the above example, the numbers 121 and 101 on a control card would only allow the terms $Z_1 Z_2^2 Z_3$ and $Z_1 Z_3$ to be considered for regression. Moreover, a group of terms that contains all terms with the term $Z_1 Z_3$ included in them can be stipulated. For example, 1*1 on a control card would allow the independent terms $Z_1 Z_3$, $Z_1 Z_2 Z_3$, and $Z_1 Z_2^2 Z_3$ to be generated.

In a similar manner certain terms can be deleted from the complete set of independent terms. This is accomplished by specifying the DELETE program mode. For the above example, if in DELETE mode, the numbers 121 and 101 on a control card would allow all independent terms of the complete set with the

exception of $Z_1Z_2^2Z_3$ and Z_1Z_3 to be generated. Likewise 1*1 would allow all but the terms Z_1Z_3 , $Z_1Z_2Z_3$, and $Z_1Z_2^2Z_3$ of the complete set to be generated.

At each step one independent term is added to the regression equation. The term added is the one which makes the greatest reduction in the error sum of squares. Equivalently it is the term which has highest partial correlation with the dependent variable partialled on the independent terms which have already been added; and equivalently it is the term which, if it were added, would have the highest F value. A term may be indicated to be significant in any early stage and thus enter the regression equation. After several other terms are added to the regression equation, the initial term may be indicated to be insignificant. The insignificant term will be removed from the regression equation before adding an additional term. Therefore, only significant terms are included in the final regression equation.

III. PROGRAM OUTPUT

- A. Output prior to performing regression:
 - 1. Problem number
 - 2. F level to enter a term
 - 3. F level to remove a term
 - 4. Number of independent variables
 - 5. Number of independent terms
 - 6. Maximum power of each independent variable
 - 7. Number of observations
 - 8. Weighted number of data
 - 9. Standard error of Y
- B. Optional output prior to performing regression:
 - 1. Input data
 - 2. Weighted sum of terms
 - 3. Weighted mean of terms
 - 4. Weighted sum of squares and cross products
 - 5. Weighted residual sum of squares and cross products
 - 6. Correlation coefficients
 - 7. List of term numbers generated (used only when in accept or delete mode)
- C. At each step:
 - 1. Step number
 - 2. Term entered or removed
 - 3. F level
 - 4. Standard error of Y
 - 5. Analysis of variance table
 - 6. For terms in the equation
 - a. Regression coefficient
 - b. Standard error of coefficient
 - c. Powers of the independent variables
 - 7. Constant term
 - 8. Multiple correlation coefficient squared
- D. Optional output after performing regression:
 - 1. List of residuals

Since the user is not aware whether terms or variables are being used, the word "variable" will appear on the output pages. This is the more commonly accepted terminology.

IV. PROBLEM LIMITATIONS

1. Number of original variables (14)
2. Number of terms (150)
3. F level to enter a term \geq F level to remove a term
4. Maximum power of an independent variable is nine

V. ORDER OF CONTROL CARDS IN JOB DECK

1. Start of input data control card
2. Input data cards - place data input deck here
3. End of input data control card
4. Information control card
5. Print control card
6. Maximum powers control card
7. Format control card
8. Variable mode control card
9. Variable mode control data cards

If more than one analysis of a set of input data is required, cards 4-9 can be repeated. If more than one set of input data needs to be analyzed, repeat cards 1-9.

VI. CONTROL CARD PREPARATION

1. Start of input data control card
Col. 1 -10 START DATA

3. End of input data control card
Col. 1 - 8 END DATA

4. Information control card
Col. 1 - 6 INFORM
Col. 11-15 Numeric problem number
Col. 16-20 Number of original variables
Col. 21-25 F level to enter a term (X.XX)
Col. 26-30 F level to remove a term (X.XX)
Col. 35 1 if all observations are equally weighted;
otherwise, 0

5. Print card
Col. 1 - 5 PRINT
Col. 15 1 if the input data is to be printed; otherwise, 0
Col. 20 1 if the weighted sums of terms are to be
printed; otherwise, 0
Col. 25 1 if the weighted means of terms are to be
printed; otherwise, 0
Col. 30 1 if the weighted sums of squares and cross
products are to be printed; otherwise, 0
Col. 35 1 if the weighted residual sums of squares and
cross products are to be printed; otherwise, 0
Col. 40 1 if the correlation coefficients are to be
printed; otherwise, 0
Col. 45 1 if the list that transforms term numbers from
ACCEPT or DELETE mode to NORMAL mode
is to be printed; otherwise, 0 (will always be 0
in the NORMAL mode)
Col. 50 1 if the residuals are to be printed; otherwise,
0

6. Maximum powers control card
Col. 1 -10 MAX POWERS
Col. 10+5I Maximum power allowed for independent variable
I

7. Format control card
 - Col. 1 - 6 FORMAT
 - Col. 7 -78 Format of the input data enclosed in parenthesis
 - Col. 79-80 Number of the variable designated as the dependent variable
8. Variable mode control card
 - Col. 1 - 6 NORMAL, DELETE, or ACCEPT
 - Col. 11-15 Number of variable mode control data cards
(if in the NORMAL mode, this number will be 0)
9. Variable mode control data cards

These cards contain the powers of the independent variables used to compose each term of the subset of independent terms to be accepted or deleted from the complete set of terms. An asterisk in place of a power allows all powers up to its maximum power of that particular independent variable to be accepted or deleted. For each term (or group of terms if asterisks are used) the number of powers and asterisks must equal the number of independent variables used. Blanks can be placed between powers and asterisks. A comma must separate the powers of one term from the powers of another term.

VII. EXAMPLES OF CONTROL CARDS

PROGRAM		MULTIPLE STEPWISE REGRESSION ANALYSIS										PUNCHING INSTRUCTIONS		GRAPHIC		PAGE 1 OF 1	
PROGRAMMER		RICHARD R. KUNKEL										DATE		1970		CARD ELECTRO NUMBER	
STATEMENT																	
1	5	10	15	20	25	30	35	40	45	50	55	60	65	70	75	80	Identification Sequence
START DATA																	
	7.		26.		1.		78.		6.5		60.						
	10.		68.		13.		109.4		8.		12.						
END DATA																	
INFORM			1		5		2.50		2.50		1						
PRINT			0		0		1		0		0		1				
MAX POWERS			3		3		2		2								
FORMAT(2F10.3,10X,3F10.3)																	3
ACCEPT			2														
	1200,	0		0	1		2.00		02					3			
	2 1 0	,			0				0		2					1	
INFORM			2		6		2.00		2.00		1						
PRINT			0		0		0		0		0		0				
MAX POWERS			4		1		5		2		3						
FORMAT(6F10.3)																	4
ACCEPT			1														
	**511	,11 11	1	,		4	14*2										

Two runs on the same set of data have been indicated.

Run one:

Problem number 1

Five original variables

F level to enter a term is 2.50

F level to remove a term is 2.50

All observations are equally weighted

Weighted means of terms, correlation coefficients, and residuals will be printed

There are four independent variables (Z_1 , Z_2 , Z_3 , Z_4) with highest power allowed of 3, 2, 2, 2 respectively

The first ten columns of each data card contain the value of Z_1 , columns 11-20 the value of Z_2 , columns 31-40 the value of the dependent variable (Y), columns 41-50 the value of Z_3 , and columns 51-60 the value of Z_4

The program is in the ACCEPT mode and has two variable mode control data cards

The independent terms to be considered for regression are

$$Z_1 Z_2^2, Z_3 Z_4^2, Z_4^2, Z_1^3 Z_2^2 Z_3, \text{ and } Z_3^2 Z_4$$

Run two:

Problem number 2

Six original variables

F level to enter a term is 2.00

F level to remove a term is 2.00

All observations are equally weighted

No optional information is to be printed

There are five independent variables (Z_1, Z_2, Z_3, Z_4, Z_5)
with highest power allowed of 4, 1, 5, 2, 3 respectively

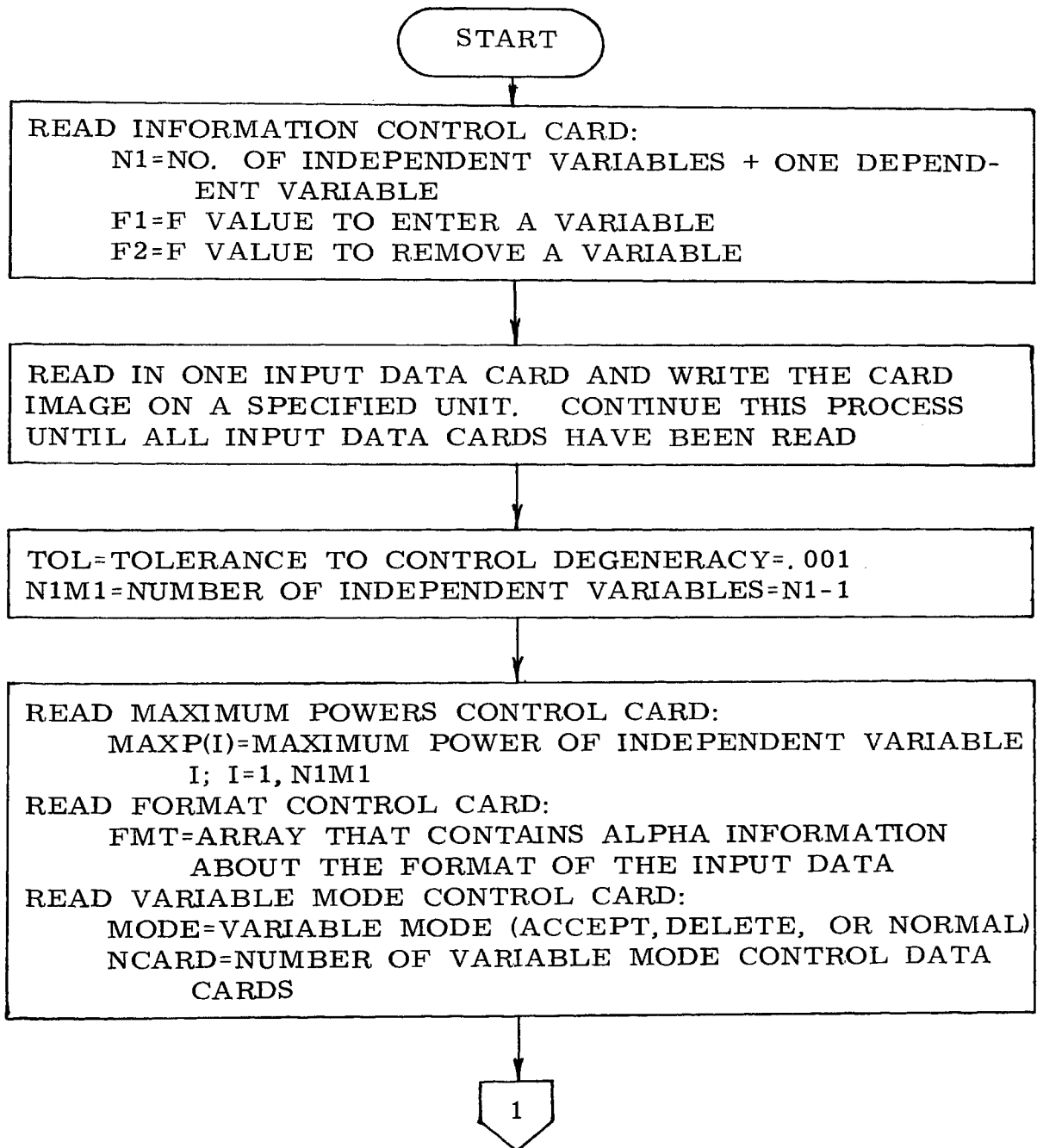
Starting with column one on each data card, the value of
variables Z_1, Z_2, Z_3, Y, Z_4 , and Z_5 are read from
consecutive fields of ten columns each

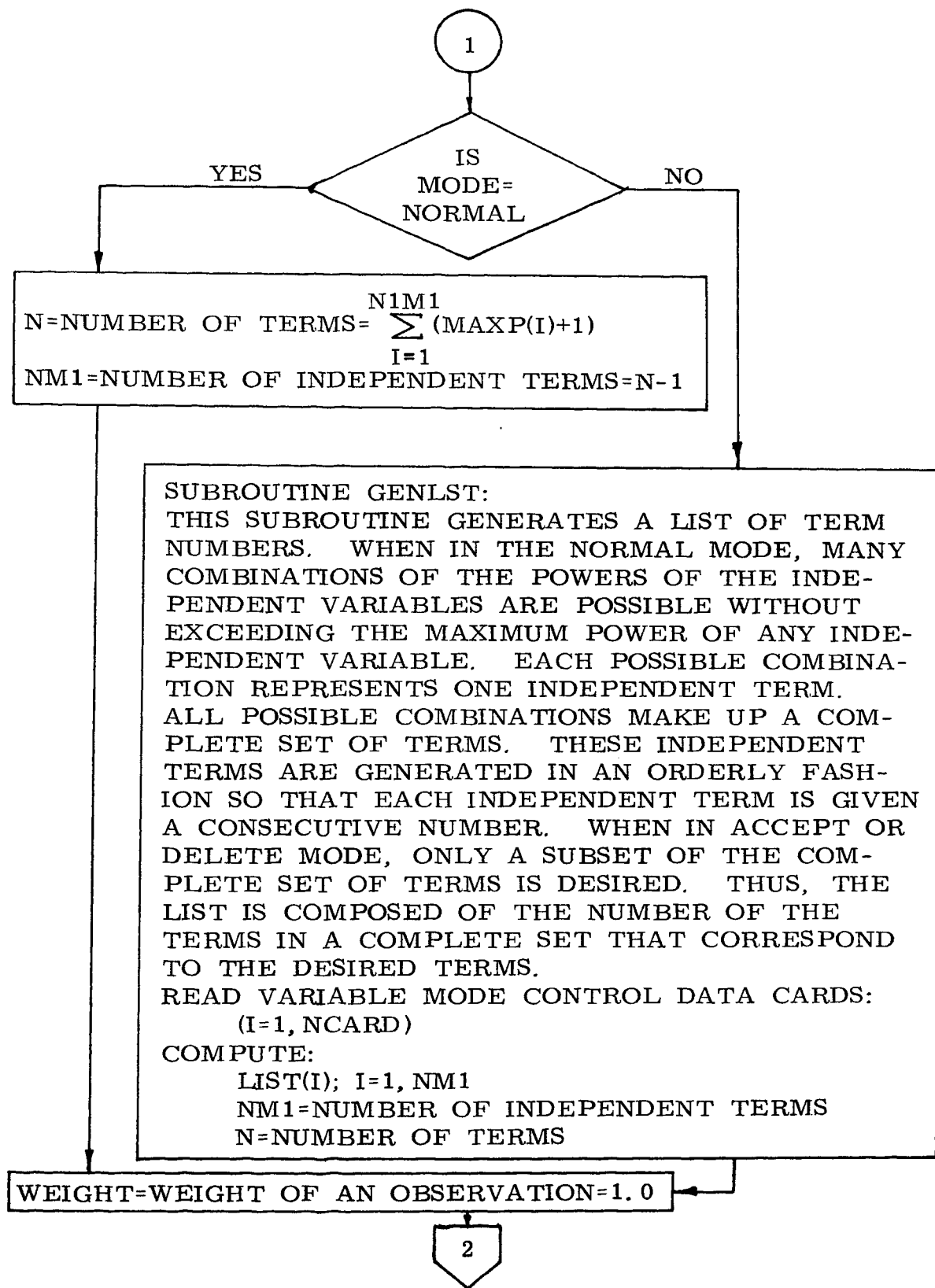
The program is in the ACCEPT mode and has one variable
mode control data card

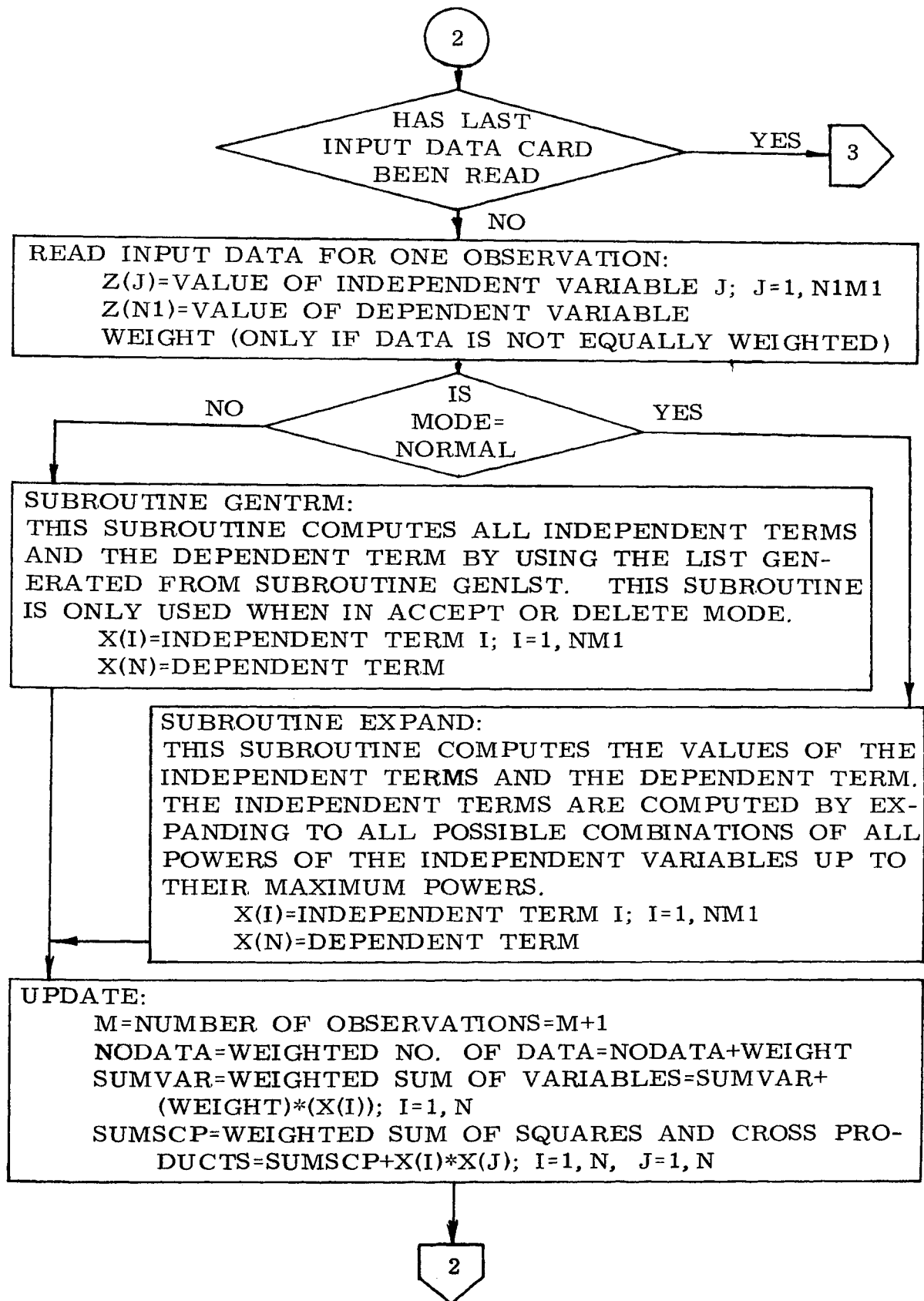
The independent terms to be considered for regression are

$$\begin{aligned} &Z_3^5 Z_4 Z_5, \quad Z_2 Z_3^5 Z_4 Z_5, \quad Z_1 Z_3^5 Z_4 Z_5, \quad Z_1 Z_2 Z_3^5 Z_4 Z_5, \\ &Z_1^2 Z_3^5 Z_4 Z_5, \quad Z_1^2 Z_2 Z_3^5 Z_4 Z_5, \quad Z_1^3 Z_3^5 Z_4 Z_5, \quad Z_1^3 Z_2 Z_3^5 Z_4 Z_5, \\ &Z_1^4 Z_3^5 Z_4 Z_5, \quad Z_1^4 Z_2 Z_3^5 Z_4 Z_5, \quad Z_1 Z_2 Z_3^4 Z_4 Z_5, \quad Z_1^4 Z_2 Z_3^4 Z_5^2, \\ &Z_1^4 Z_2 Z_3^4 Z_4 Z_5^2, \quad \text{and} \quad Z_1^4 Z_2 Z_3^4 Z_4^2 Z_5^2 \end{aligned}$$

VIII. BLOCK FLOW CHART







3

COMPUTE:

$$\begin{aligned} \text{XBAR}(I) &= \text{WEIGHTED MEAN} = \frac{\sum_{t=1}^M \text{WEIGHT}_t X_{it}}{\sum_{t=1}^M \text{WEIGHT}_t} \\ &= \text{SUMVAR}(I) / \text{NODATA}; \quad I=1, N \end{aligned}$$

$$\begin{aligned} S(I, J) &= \text{WT. RESIDUAL SUM OF SQUARES \& CROSS PRODUCTS} \\ &= \left(\sum_{t=1}^M \text{WT}_t \sum_{t=1}^M \text{WT}_t X_{it} X_{jt} - \sum_{t=1}^M \text{WT}_t X_{it} \sum_{t=1}^M \text{WT}_t X_{jt} \right) / \sum_{t=1}^M \text{WT}_t \\ &= \text{SUMSCP}(I, J) - \text{XBAR}(I) * \text{XBAR}(J) * \text{NODATA}; \quad I=1, N, \quad J=I, N \end{aligned}$$

$$\text{SIGMA}(I) = \text{SQRT}(S(I, I)); \quad I=1, N$$

R(I, J) = SIMPLE CORRELATION COEFFICIENTS

$$= S(I, J) / \text{SIGMA}(I) * \text{SIGMA}(J); \quad I=1, \text{NM1}, \quad J=I+1, N$$

$$R(J, I) = R(I, J)$$

$$R(I, I) = 1.00; \quad I=1, N$$

$$\text{DF} = \text{DEGREES OF FREEDOM} = \sum_{t=1}^M \text{WEIGHT}_t - 1.0 = \text{NODATA} - 1.0$$

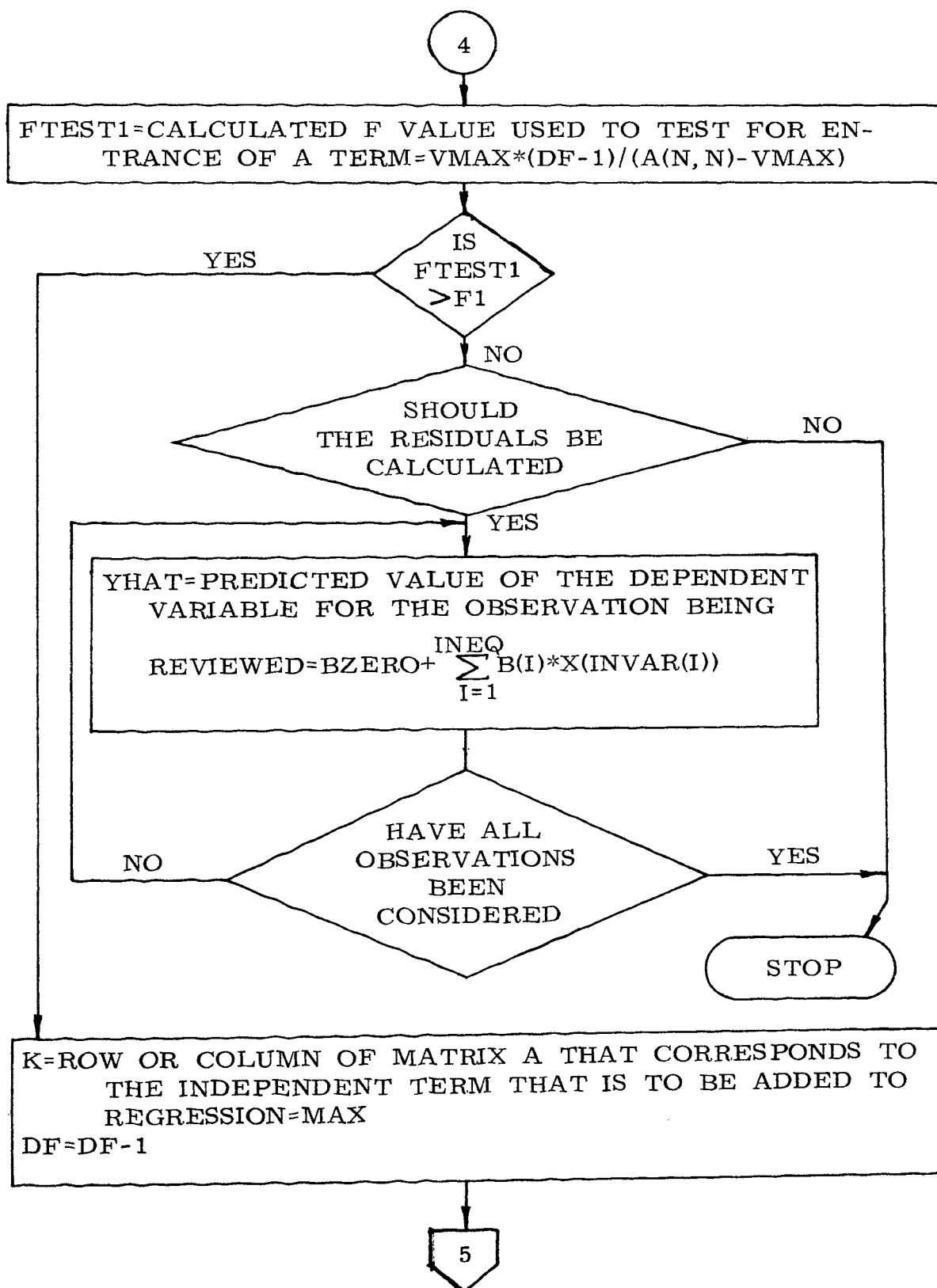
$$\text{ERRORY} = \text{STANDARD ERROR OF Y} = \text{SIGMA}(N) * \text{SQRT}(R(N, N) / \text{DF})$$

MAX = VALUE OF I CORRESPONDING TO LARGEST ABSOLUTE
VALUE OF R(I, N); I=1, NM1

$$A(I, J) = R(I, J); \quad I=1, N, \quad J=1, N$$

$$\begin{aligned} \text{VMAX} &= \text{VARIANCE REDUCTION BY ADDING VARIABLE MAX} \\ &\text{TO REGRESSION} = A(\text{MAX}, N) * A(N, \text{MAX}) \end{aligned}$$

4



5

CALCULATE NEXT MATRIX:

1. $A(I, J)_{\text{new}} = (A(K, K) * A(I, J) - A(I, K) * A(K, J)) / A(K, K); I \neq K, J \neq K$
2. $A(I, J)_{\text{new}} = -A(I, K) / A(K, K); I \neq K, J = K$
3. $A(I, J)_{\text{new}} = A(K, J) / A(K, K); J \neq K, I = K$
4. $A(K, K)_{\text{new}} = 1 / A(K, K)$

ERRORY = SIGMA(N) * SQRT(A(N, N) / DF)

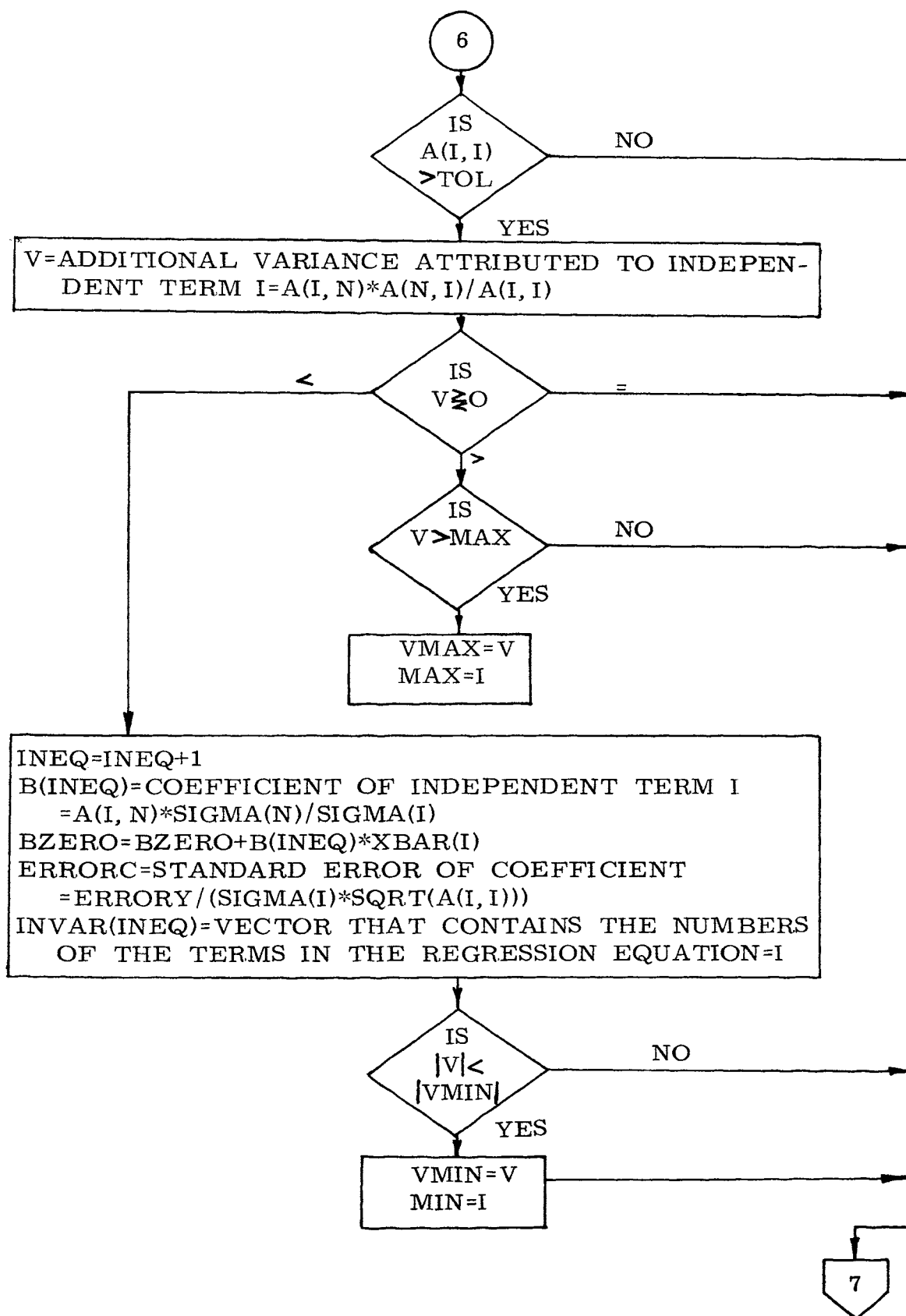
COMPUTE PARAMETERS FOR AOV TABLE:

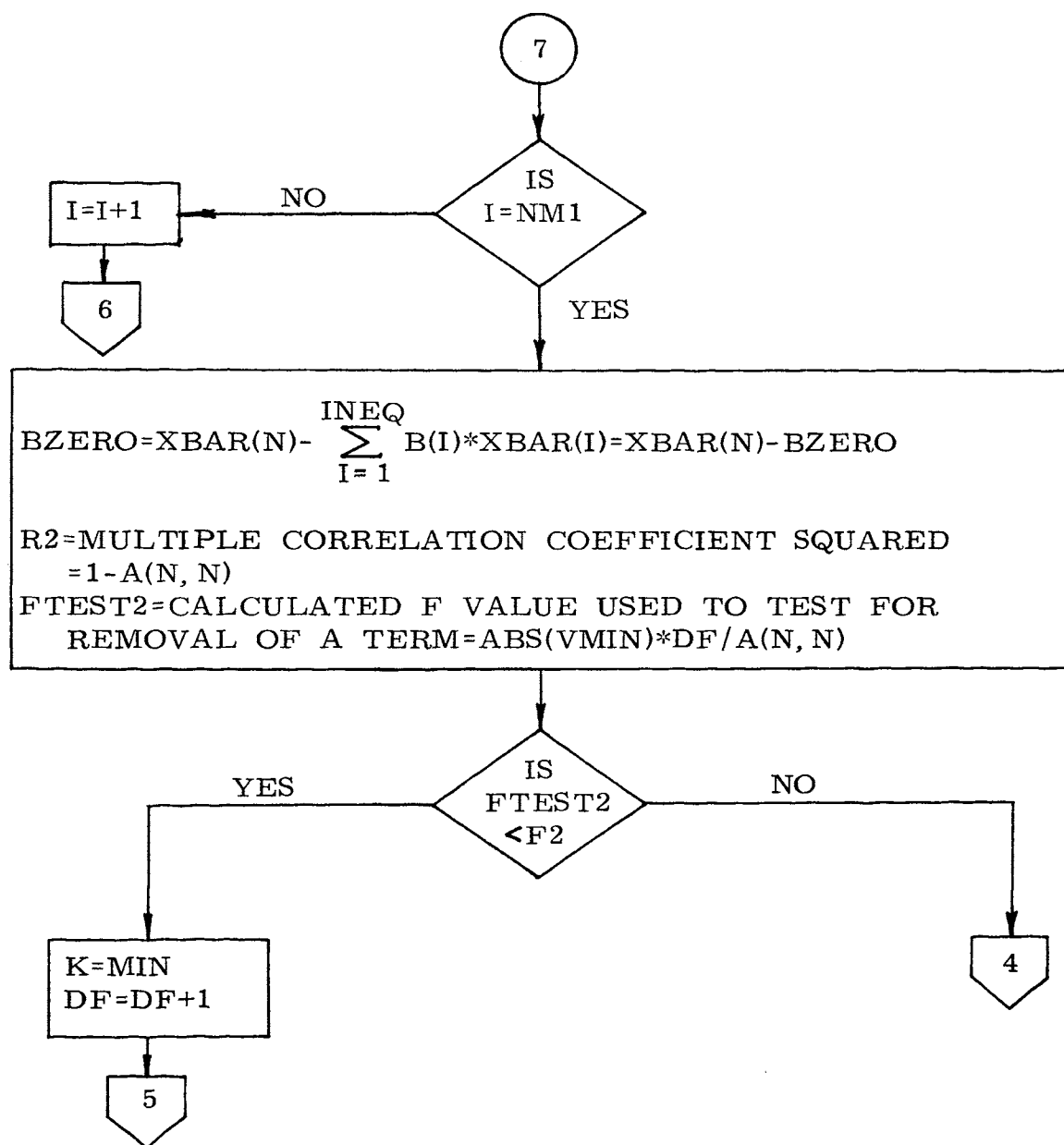
TOALSS = TOTAL SUM OF SQUARES = SUMSCP(N, N)
 MEANSS = MEAN SUM OF SQUARES = TOALSS - S(N, N)
 REGDF = DEGREES OF FREEDOM ATTRIBUTED TO
 REGRESSION = NODATA - DF - 1
 RESS = RESIDUAL SUM OF SQUARES
 = A(N, N) * (TOALSS - MEANSS)
 REGSS = REGRESSION SUM OF SQUARES
 = TOALSS - MEANSS - RESS
 REGMS = REGRESSION MEAN SQUARE = REGSS / REGDF
 RESMS = RESIDUAL MEAN SQUARE = RESS / DF
 RATIO = F RATIO = REGMS / RESMS

INITIALIZATION:

I = VARIABLE NUMBER = 1
 INEQ = COUNTER OF THE NUMBER OF TERMS IN
 REGRESSION = 0
 VMIN = VARIANCE INCREASE BY REMOVING A VARIABLE
 = 5. E10
 VMAX = VARIANCE REDUCTION BY ADDING A VARIABLE
 = 0. 0
 MIN = NUMBER OF THE IND. TERM THAT CAUSES THE
 LEAST VARIANCE INCREASE WHEN TAKEN OUT OF
 REGRESSION = 0
 MAX = NUMBER OF THE IND. TERM THAT CAUSES THE
 GREATEST VARIANCE REDUCTION WHEN PUT INTO
 REGRESSION = 0
 BZERO = CONSTANT TERM = 0

6





IX. PROGRAM LISTING

```
C    MULTIPLE REGRESSION ANALYSIS (STEPWISE)
      REAL Z(15),X(150),SUMVAR(150),XBAR(150),SUMSCP(150,150),S(150,150)
1    ,SIGMA(150),R(150,150),A(150,150),NODATA,MEANSS,B(150)
      INTEGER DF,STEPNO,PRONUM,MAXP(15),P(15),REGDF,LIST(150),CONTRL,
1DEPVAR,FMT(18),INVAR(150),INPTAP(20)
      DOUBLE PRECISION LEFT3,LEFT5
      DATA LEFT1/2HX-/,LEFT2/2HZ(/,LEFT3/6HSUM X(/,LEFT4/2HX(/,
1LEFT5/5H * Z(/,IFORM/4HFORM/,ISTAR/4HSTAR/,IEND/4HEND /,
2INFO/4HINFO/,IPRIN/4HPRIN/,IMAX/4HMAX /,INORM/4HNORM/,
3IACCE/4HACCE/,IDELE/4HDELE/
      EQUIVALENCE (SUMVAR,XBAR),(SUMSCP,S,R,A),(X,SIGMA)
      TOL=.001
10  READ(1,1000,END=620)CONTRL,PRONUM,N1,F1,F2,IW
1000 FORMAT(A4,6X,2I5,2F5.2,I5)
      20 IF(CONTRL.NE.ISTAR) GO TO 50
      30 READ(1,1010)INPTAP
1010 FORMAT(20A4)
      IF(INPTAP(1).EQ.IEND) GO TO 40
      WRITE(4,1010)INPTAP
      GO TO 30
40  ENDFILE 4
      REWIND 4
      GO TO 10
50  IF(CONTRL.EQ.INFO) GO TO 60
      WRITE(3,3000)
3000 FORMAT(' INCORRECT OR MISSING CONTROL CARD - EITHER INFORMATION CA
1RD OR START OF INPUT DATA CARD')
      GO TO 620
60  WRITE(3,3010)PRONUM,N1,F1,F2
```



```

3010 FORMAT('1PROBLEM NO',I5// ' NO OF VARIABLES =',I5// ' F LEVEL TO ENT
      1ER VARIABLE =',F5.2// ' F LEVEL TO REMOVE VARIABLE =',F5.2)
      READ(1,1020)CONTRL,INDATA,ISUMVR,IXBAR,ISMSCP,IS,IR,ILIST,IRESID
1020 FORMAT(A4,6X,14I5)
      IF(CONTRL.EQ.IPRIN) GO TO 70
      WRITE(3,3020)
3020 FORMAT(' INCORRECT OR MISSING CONTROL CARD - PRINT CARD')
      GO TO 620
70  N1M1=N1-1
      READ(1,1020)CONTRL,(MAXP(I),I=1,N1M1)
      IF(CONTRL.EQ.IMAX) GO TO 80
      WRITE(3,3030)
3030 FORMAT(' INCORRECT OR MISSING CONTROL CARD - MAXIMUM POWERS CARD')
      GO TO 620
80  READ(1,1030)CONTRL,FMT,DEPVAR
1030 FORMAT(A4,2X,18A4,I2)
      IF(CONTRL.EQ.IFORM) GO TO 90
      WRITE(3,3040)
3040 FORMAT(' INCORRECT OR MISSING CONTROL CARD - FORMAT CARD')
      GO TO 620
90  READ(1,1020)MODE,NCARD
      IF(MODE.EQ.INORM) GO TO 110
      IF((MODE.EQ.IDELE).OR.(MODE.EQ.IACCE)) GO TO 100
      WRITE(3,3050)
3050 FORMAT(' INCORRECT OR MISSING CONTROL CARD - VARIABLE MODE CARD')
      GO TO 620
100 CALL GENLST(MODE,N1M1,N,NM1,NCARD,MAXP(1),LIST(1),A(1,1),A(1,76))
      GO TO 130
110 N=1
      DO 120 I=1,N1M1
120 N=N*(MAXP(I)+1)

```

```

      NM1=N-1
130  WRITE(3, 3060)N1M1, NM1, (LEFT1, I, MAXP(I), I=1, N1M1)
3060  FORMAT(/' NO. OF INDEPENDENT VARIABLES =', I3/' NO. OF INDEPENDENT
      1  TERMS =', I4/' 3X, 'INDEPENDENT', 4X, 'MAX'/5X, 'VARIABLE', 4X, 'POWER'/
      2(7X, A2, I2, 7X, I2))
      IF(INDATA.EQ. 0) GO TO 140
      WRITE(3, 3070)(LEFT2, (I), I=1, N1)
3070  FORMAT(///20X, 'INPUT DATA'/' OBSERVATION', 10(3X, A2, I2, '), 2X)/
      1(15X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, ')
      2, 5X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, '), 5X, A2, I2, ')
      3)
140  DO 150 I=1, N
      SUMVAR(I)=0. 0
      DO 150 J=1, N
150  SUMSCP(I, J)=0. 0
      NODATA=0. 0
      WEIGHT=1. 0
      M=0
160  IF(IW.EQ. 0) GO TO 162
      READ(4, FMT, END=240)(Z(J), J=1, N1)
      GO TO 170
162  READ(4, FMT, END=240)(Z(J), J=1, N1), WEIGHT
170  M=M+1
      TEMP=Z(DEPVAR)
      DO 180 J=DEPVAR, N1M1
180  Z(J)=Z(J+1)
      Z(N1)=TEMP
      IF(INDATA.EQ. 0) GO TO 190
      WRITE(3, 3080)M, (Z(J), J=1, N1)
3080  FORMAT(3X, I4, 10F10. 3, (/11X, 10F10. 3))
190  NODATA=NODATA+WEIGHT

```

```

        IF(MODE.EQ.INORM) GO TO 200
        CALL GENTRM(N1M1, NM1, MAXP(1), LIST(1), Z(1), X(1))
        GO TO 210
200  CALL EXPAND(N1M1, MAXP(1), Z(1), X(1))
210  DO 220 J=1, N
220  SUMVAR(J)=SUMVAR(J)+WEIGHT*X(J)
        DO 230 I=1, N
        DO 230 J=I, N
230  SUMSCP(I, J)=SUMSCP(I, J)+WEIGHT*X(I)*X(J)
        GO TO 160
240  WRITE(3, 3090)M, NODATA
3090  FORMAT('/ NO. OF OBSERVATIONS =', I5// ' WEIGHTED NO. OF DATA =',
1F7.2)
        IF(ISUMVR.EQ.0) GO TO 250
        WRITE(3, 3100)
3100  FORMAT(///20X, 'WEIGHTED SUMS OF VARIABLES'/)
        WRITE(3, 3110)((LEFT3, I, SUMVAR(I)), I=1, NM1)
3110  FORMAT(3(1X, A6, I2, ' ) =', F14.5, 4X))
        WRITE(3, 3120)SUMVAR(N)
3120  FORMAT(' SUM    Y    =', F14.5)
250  DO 260 I=1, N
260  XBAR(I)=SUMVAR(I)/NODATA
        IF(IXBAR.EQ.0) GO TO 270
        WRITE(3, 3130)
3130  FORMAT(///20X, 'WEIGHTED MEAN OF VARIABLES'/)
        WRITE(3, 3110)((LEFT3, I, XBAR(I)), I=1, NM1)
        WRITE(3, 3120)XBAR(N)
270  IF(ISMSCP.EQ.0) GO TO 280
        WRITE(3, 3140)
3140  FORMAT(///20X, 'WEIGHTED SUMS OF SQUARES AND CROSS PRODUCTS'/)
        WRITE(3, 3150)((LEFT4, I, J, SUMSCP(I, J)), J=I, NM1), I=1, NM1)

```

```

3150 FORMAT(3(1X, A2, I2, ') VS X(' , I2, ') =' , F16.5, 4X))
      WRITE(3, 3160)((LEFT4, I, SUMSCP(I, N)), I=1, NM1)
3160 FORMAT(3(1X, A2, I2, ') VS   Y   =' , F16.5, 4X))
      WRITE(3, 3170)SUMSCP(N, N)
3170 FORMAT(' Y       VS   Y   =' , F16.5)
280  TOALSS=SUMSCP(N, N)
      DO 300 I=1, N
      DO 290 J=I, N
290  S(I, J)=SUMSCP(I, J)-XBAR(I)*XBAR(J)*NODATA
300  SIGMA(I)=SQRT(S(I, I))
      IF(IS.EQ.0) GO TO 310
      WRITE(3, 3180)
3180 FORMAT(///20X, 'WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS PRODUCTS
1'/)
      WRITE(3, 3150)((LEFT4, I, J, S(I, J)), J=I, NM1), I=1, NM1)
      WRITE(3, 3160)((LEFT4, I, S(I, N)), I=1, NM1)
      WRITE(3, 3170)S(N, N)
310  MEANSS=TOALSS-S(N, N)
      DO 320 I=1, NM1
      IP1=I+1
      DO 320 J=IP1, N
320  R(I, J)=S(I, J)/(SIGMA(I)*SIGMA(J))
      DO 330 I=1, NM1
      IP1=I+1
      DO 330 J=IP1, N
330  R(J, I)=R(I, J)
      DO 340 I=1, N
340  R(I, I)=1.0
      IF(IR.EQ.0) GO TO 350
      WRITE(3, 3190)
3190 FORMAT(///20X, 'CORRELATION COEFFICIENTS'//)

```

```

        WRITE(3, 3150)((LEFT4, I, J, R(I, J)), J=I, NM1), I=1, NM1)
        WRITE(3, 3160)((LEFT4, I, R(I, N)), I=1, NM1)
350  DF=NODATA-1.0
        ERRORY=SIGMA(N)*SQRT(R(N, N)/DF)
        WRITE(3, 3200)ERRORY
3200  FORMAT(/' STANDARD ERROR OF Y =', F8.3)
        IF(ILIST.EQ.0) GO TO 360
        WRITE(3, 3210)(I, LIST(I), I=1, NM1)
3210  FORMAT(/' LIST GENERATION'/3X, '(TERM GENERATED) CORRESPONDS TO THE
        1 X TERM GENERATED IN THE NORMAL MODE'//5X, 'TERM NO. ', 3X, 'TERM GENE
        2RATED'/(6X, I5, 6X, I5))
360  VMAX=0.0
        DO 370 I=1, NM1
        IF(ABS(R(I, N)).LE.VMAX) GO TO 370
        MAX=I
        VMAX=ABS(R(I, N))
370  CONTINUE
        VMAX=A(MAX, N)*A(N, MAX)
        STEPNO=1
        GO TO 480
380  STEPNO=STEPNO+1
        ERRORY=SIGMA(N)*SQRT(A(N, N)/DF)
        WRITE(3, 3220)ERRORY
3220  FORMAT(3X, 'STANDARD ERROR OF Y =', F12.4/3X, 'ANALYSIS OF VARIANCE'
        1/12X, 'SOURCE', 6X, 'DF', 4X, 'SUM OF SQUARES', 4X, 'MEAN SQUARE', 3X,
        2'F RATIO')
        WRITE(3, 3230)M, TOALSS
3230  FORMAT(10X, 'TOTAL', 7X, I4, 4X, F14.3)
        WRITE(3, 3240)MEANSS
3240  FORMAT(10X, 'MEAN', 11X, '1', 4X, F14.3)
        REGDF=NODATA-DF-1

```

```

      RESSS=A(N, N)*(T)ALSS-MEANSS)
      REGSS=TOALSS-MEANSS-RESSS
      REGMS=REGSS/REGDF
      RESMS=RESSS/DF
      RATIO=REGMS/RESMS
      WRITE(3, 3250)REGDF, REGSS, REGMS, RATIO
3250  FORMAT(10X, 'REGRESSION', 2X, I4, 4X, F14. 3, 2X, F13. 3, 2X, F8. 3)
      WRITE(3, 3260)DF, RESSS, RESMS
3260  FORMAT(10X, 'RESIDUAL', 4X, I4, 4X, F14. 3, 2X, F13. 3/3X, 'VARIABLES IN EQU
      IATION'/10X, 'VARIABLE', 5X, 'COEFFICIENT', 5X, 'STD ERROR OF COEF')
      I=1
      INEQ=0
      VMIN=5. E10
      VMAX=0. 0
      MIN=0
      MAX=0
      BZERO=0. 0
390  IF(A(I, I). LE. TOL)GO TO 420
      V=A(I, N)*A(N, I)/A(I, I)
      IF(V)410, 420, 400
400  IF(V. LE. VMAX)GO TO 420
      VMAX=V
      MAX=I
      GO TO 420
410  INEQ=INEQ+1
      B(INEQ)=A(I, N)*SIGMA(N)/SIGMA(I)
      BZERO=BZERO+B(INEQ)*XBAR(I)
      ERRORC=ERRORY/SIGMA(I)*SQRT(A(I, I))
      WRITE(3, 3270)I, B(INEQ), ERRORC
3270  FORMAT(12X, 'X-', I3, 6X, F10. 5, 7X, F10. 5)
      INVAR(INEQ)=I

```

```

        IF(ABS(V).GE.ABS(VMIN)) GO TO 420
        VMIN=V
        MIN=I
420  IF(I.EQ.NM1) GO TO 430
        I=I+1
        GO TO 390
430  DO 470 J=1,INEQ
        IF(MODE.EQ.INORM) GO TO 440
        IRET=LIST(INVAR(J))
        GO TO 450
440  IRET=INVAR(J)
450  DO 460 IJ=1,N1M1
        IZ=IRET/(MAXP(N1-IJ)+1)
        P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
460  IRET=IZ
470  WRITE(3,3280)INVAR(J),P(1),(LEFT5,IK,P(IK),IK=2,N1M1)
3280  FORMAT(17X,'X(',I3,11H) = Z( 1)**,I1,9(A5,I2,3H)**,I1)/(23X,A5,I2,
        13H)**,I1,A5,I2,3H)**,I1,A5,I2,3H)**,I1,A5,I2,3H)**,I1,A5,I2,3H)**,
        2I1,A5,I2,3H)**,I1,A5,I2,3H)**,I1,A5,I2,3H)**,I1,A5,I2,3H)**,I1,A5,
        3I2,3H)**,I1))
        BZERO=XBAR(N)-BZERO
        R2=(1-A(N,N))*100.0
        WRITE(3,3290)BZERO,R2
3290  FORMAT(3X,'CONSTANT =',F12.5/3X,'MULTIPLE CORRELATION COEFFICIENT
        1SQUARED =',F6.2,' PERCENT')
        FTEST2=ABS(VMIN)*DF/A(N,N)
        IF(FTEST2.GE.F2) GO TO 480
        WRITE(3,3300)STEPNO,MIN,FTEST2
3300  FORMAT(///1X,'STEP NO. ',I3/3X,'VARIABLE REMOVED',I4/
        13X,'F LEVEL',F8.4)
        K=MIN

```

```

        DF=DF+1
        GO TO 560
480  FTEST1=VMAX*(DF-1)/(A(N,N)-VMAX)
        IF(FTEST1.GT.F1) GO TO 550
        REWIND 4
        IF(IRESID.EQ.0) GO TO 10
        WRITE(3,3310)
3310  FORMAT(3X,'PREDICTED VS. ACTUAL RESULTS'/10X,'OBSERVATION',10X,
1'ACTUAL',11X,'PREDICTED',11X,'DEVIATION')
        DO 540 IK=1,M
        READ(4,FMT)(Z(J),J=1,N1)
        TEMP=Z(DEPVAR)
        DO 485 IL=DEPVAR,N1M1
485  Z(IL)=Z(IL+1)
        Z(N1)=TEMP
        SUMPR=0.0
        DO 530 J=1,INEQ
        IF(MODE.EQ.INORM) GO TO 490
        IRET=LIST(INVAR(J))
        GO TO 500
490  IRET=INVAR(J)
500  DO 510 IJ=1,N1M1
        IZ=IRET/(MAXP(N1-IJ)+1)
        P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
510  IRET=IZ
        PROD=1.0
        DO 520 II=1,N1M1
        IF(P(II).EQ.0) GO TO 520
        PROD=PROD*Z(II)**P(II)
520  CONTINUE
530  SUMPR=SUMPR+PROD*B(J)

```



```

        YHAT=BZERO+SUMPB
        DEV=Z(N1)-YHAT
540  WRITE(3, 3320)IK, Z(N1), YHAT, DEV
3320  FORMAT(12X, I5, 4X, F16.5, 4X, F16.5, 4X, F16.5)
        REWIND 4
        GO TO 10
550  WRITE(3, 3330)STEPNO, MAX, FTEST1
3330  FORMAT(///1X, 'STEP NO. ', I3/3X, 'VARIABLE ENTERING', I4/
        13X, 'F LEVEL', F8.4)
        K=MAX
        DF=DF-1
560  PIVOT=A(K, K)
        DO 590 I=1, N
        IF(I.EQ. K) GO TO 590
        PIVCOL=A(I, K)
        DO 580 J=1, N
        IF(J.EQ. K) GO TO 570
        A(I, J)=(A(I, J)*PIVOT-PIVCOL*A(K, J))/PIVOT
        GO TO 580
570  A(I, J)=-A(I, K)/PIVOT
580  CONTINUE
590  CONTINUE
        DO 610 J=1, N
        IF(J.EQ. K) GO TO 600
        A(K, J)=A(K, J)/PIVOT
        GO TO 610
600  A(K, K)=1.0/PIVOT
610  CONTINUE
        GO TO 380
620  CALL EXIT
        END

```

```

SUBROUTINE GENLST(MODE, N1M1, N, NM1, NCARD, MAXP, LIST, ELM, ALPHA)
DATA IBLK/4H    /, ICOM/4H,    /, IAST/4H*    /, ISHIFT/Z01000000/,
1IACCE/4HACCE/, IDELE/4HDELE/
INTEGER P(15), MAXP(15), ALPHA(3000), ELM(200, 15), LIST(150)
K=NCARD*80
READ(1, 1000)(ALPHA(J), J=1, K)
1000 FORMAT(80A1)
IROW=1
ICOL=0
DO 40 I=1, K
IF(ALPHA(I).EQ.IBLK) GO TO 40
IF(ALPHA(I).NE.ICOM) GO TO 20
IF(ICOL.EQ.N1M1) GO TO 10
WRITE(3, 3000)
3000 FORMAT(' INCORRECT NUMBER OF CHARACTERS BETWEEN COMMAS ON A VARIAB
1LE MODE CARD')
STOP
10 IROW=IROW+1
ICOL=0
GO TO 40
20 ICOL=ICOL+1
IF(ALPHA(I).EQ.IAST) GO TO 30
ELM(IROW, ICOL)=15-IABS(ALPHA(I)/ISHIFT)
GO TO 40
30 ELM(IROW, ICOL)=IAST
40 CONTINUE
DO 50 I=1, N1M1
50 P(I)=0
P(N1M1)=1
I=0
LL=0

```

```

60 ITEST=N1M1
70 I=I+1
   DO 90 II=1,IROW
   DO 80 IJ=1,ICOL
   IF(ELM(II,IJ).EQ.IAST) GO TO 80
   IF(ELM(II,IJ).NE.P(IJ)) GO TO 90
80 CONTINUE
   GO TO 100
90 CONTINUE
   IF(MODE.EQ.IACCE) GO TO 120
   GO TO 110
100 IF(MODE.EQ.IDELE) GO TO 120
110 LL=LL+1
   LIST(LL)=I
120 IF(P(ITEST).EQ.MAXP(ITEST)) GO TO 130
   P(ITEST)=P(ITEST)+1
   GO TO 70
130 IF(P(ITEST-1).NE.MAXP(ITEST-1)) GO TO 140
   IF(ITEST.EQ.2) GO TO 160
   ITEST=ITEST-1
   GO TO 130
140 DO 150 II=ITEST,N1M1
150 P(II)=0
   P(ITEST-1)=P(ITEST-1)+1
   GO TO 60
160 NM1=LL
   N=LL+1
   RETURN
   END

```

```

SUBROUTINE GENTRM(N1M1, NM1, MAXP, LIST, Z, X)
  DIMENSION Z(15), X(150)
  INTEGER P(15), MAXP(15), LIST(150)
  N1=N1M1+1
  DO 20 I=1, NM1
    IRET=LIST(I)
    DO 10 IJ=1, N1M1
      IZ=IRET/(MAXP(N1-IJ)+1)
      P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
10  IRET=IZ
      X(I)=1.0
      DO 20 II=1, N1M1
        IF(P(II).EQ.0) GO TO 20
        X(I)=X(I)*Z(II)**P(II)
20  CONTINUE
      X(NM1+1)=Z(N1)
      RETURN
  END

```

```

SUBROUTINE EXPAND(N1M1, MAXP, Z, X)
  DIMENSION Z(15), X(125)
  INTEGER P(15), MAXP(15)
  DO 10 I=1, N1M1
10  P(I)=0
    P(N1M1)=1
    I=0
20  ITEST=N1M1
30  I=I+1
    X(I)=1.0
    DO 40 II=1, N1M1
      IF(P(II).EQ.0) GO TO 40
      X(I)=X(I)*Z(II)**P(II)
40  CONTINUE
      IF(P(ITEST).EQ.MAXP(ITEST)) GO TO 50
      P(ITEST)=P(ITEST)+1
      GO TO 30
50  IF(P(ITEST-1).NE.MAXP(ITEST-1)) GO TO 60
      IF(ITEST.EQ.2) GO TO 80
      ITEST=ITEST-1
      GO TO 50
60  DO 70 II=ITEST, N1M1
70  P(II)=0
      P(ITEST-1)=P(ITEST-1)+1
      GO TO 20
80  X(I+1)=Z(N1M1+1)
      RETURN
      END

```

X. COMMENTED PROGRAM LISTING

C MULTIPLE REGRESSION ANALYSIS (STEPWISE)
C A(I, J)=(N BY N) SQUARE MATRIX ON WHICH LINEAR TRANSFORMATIONS ARE
C PERFORMED IN ORDER TO OBTAIN THE REGRESSION EQ. AT EACH STEP
C B(I)=ESTIMATED COEFFICIENT OF A INDEPENDENT TERM - NOT NECESSARILY
C TERM I
C BZERO=CONSTANT TERM
C CONTRL=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION
C OF ALPHA CHARACTERS USED TO DETECT INCORRECT OR MISSING
C CONTROL CARDS
C DEPVAR=VALUE OF THE NUMBER OF THE INPUT VARIABLE THAT IS
C DESIGNATED AS THE DEPENDENT VARIABLE
C DEV=DEVIATION BETWEEN THE OBSERVED AND THE PREDICTED VALUE OF THE
C DEPENDENT VARIABLE
C DF=DEGREES OF FREEDOM
C ERRORC(I)=STANDARD ERROR OF COEFFICIENT OF VARIABLE I
C ERRORY=STANDARD ERROR OF DEPENDENT VARIABLE
C EXPAND=SUBROUTINE THAT GENERATES THE VALUES OF ALL THE TERMS FOR A
C GIVEN OBSERVATION WHEN IN NORMAL MODE
C FMT(I)=ARRAY OF ALPHA INFORMATION THAT INDICATES THE FORMAT TO
C USE WHEN READING THE INPUT DATA
C FTEST1=CALCULATED F VALUE USED TO TEST FOR ENTRANCE OF A VARIABLE
C FTEST2=CALCULATED F VALUE USED TO TEST FOR REMOVAL OF A VARIABLE
C F1=F VALUE FOR ENTERING VARIABLE
C F2=F VALUE FOR REMOVING VARIABLE
C GENLST=SUBROUTINE THAT GENERATES A LIST OF TERM NUMBERS - WHEN IN
C THE NORMAL MODE MANY COMBINATIONS OF THE POWERS OF THE
C INDEPENDENT VARIABLES ARE POSSIBLE WITHOUT EXCEEDING THE
C MAXIMUM POWER OF ANY INDEPENDENT VARIABLE - EACH POSSIBLE
C COMBINATION REPRESENTS ONE INDEPENDENT TERM - ALL POSSIBLE

C COMBINATIONS MAKE UP A COMPLETE SET OF TERMS - THESE
 C INDEPENDENT TERMS ARE GENERATED IN AN ORDERLY FASHION SO THAT
 C EACH INDEPENDENT TERM IS GIVEN A CONSECUTIVE NUMBER - WHEN IN
 C ACCEPT OR DELETE MODE, ONLY A SUBSET OF THE COMPLETE SET OF
 C TERMS IS DESIRED - THUS THE LIST IS COMPOSED OF THE NUMBER OF
 C THE TERMS IN A COMPLETE SET THAT CORRESPOND TO THE DESIRED
 C TERMS
 C GENTRM=SUBROUTINE THAT GENERATES THE VALUES OF ALL THE DESIRED
 C TERMS FOR A GIVEN OBSERVATION WHEN IN DELETE OR ACCEPT MODE
 C I=TERM NUMBER AND COUNTER
 C II=DO LOOP PARAMETER
 C IJ=DO LOOP PARAMETER
 C IK=DO LOOP PARAMETER
 C IL=DO LOOP PARAMETER
 C ILIST=SWITCH THAT INDICATES WHETHER THE LIST THAT TRANSFORMS
 C DELETE OR ACCEPT MODE TO NORMAL MODE SHOULD BE PRINTED - A
 C VALUE OF ZERO INDICATES NO PRINT OUT
 C INDATA=SWITCH THAT INDICATES WHETHER THE INPUT DATA SHOULD BE
 C PRINTED, A VALUE OF ZERO INDICATES NO PRINT-OUT
 C INEQ=SUBSCRIPT OF THE VECTOR THAT CONTAINS THE INDEPENDENT TERMS
 C IN THE REGRESSION EQUATION
 C INPTAP(I)=ARRAY USED TO TRANSFER CARD IMAGES FROM INPUT DATA CARDS
 C TO THE LOGICAL UNIT DESIGNATED
 C INVAR(I)=VECTOR THAT CONTAINS THE VALUE OF THE NUMBER OF THE TERMS
 C PRESENTLY IN THE REGRESSION EQUATION
 C IP1=LOWER BOUND ON A DO LOOP
 C IR=SWITCH THAT INDICATES WHETHER THE CORRELATION COEFFICIENTS
 C SHOULD BE PRINTED, A VALUE OF ZERO INDICATES NO PRINT-OUT
 C IRESID=SWITCH THAT INDICATES WHETHER THE RESIDUALS SHOULD BE
 C PRINTED, A VALUE OF ZERO INDICATES NO PRINT-OUT
 C IRET=NUMBER OF THE TERM IN NORMAL MODE THAT IS TO BE RETRIEVED AS

C POWERS OF ITS INDEPENDENT VARIABLES
 C IS=SWITCH THAT INDICATES WHETHER THE WEIGHTED RESIDUAL SUMS OF
 C SQUARES AND CROSS PRODUCTS SHOULD BE PRINTED, A VALUE OF ZERO
 C INDICATES NO PRINT-OUT
 C ISMSCP=SWITCH THAT INDICATES WHETHER THE WEIGHTED SUMS OF SQUARES
 C AND CROSS PRODUCTS SHOULD BE PRINTED, A VALUE OF ZERO
 C INDICATES NO PRINT-OUT
 C ISUMVR=SWITCH THAT INDICATES WHETHER THE WEIGHTED SUMS OF
 C VARIABLES SHOULD BE PRINTED, A VALUE OF ZERO INDICATES NO
 C PRINT-OUT
 C IW=SWITCH THAT INDICATES WHETHER THE WEIGHTS OF ALL OBSERVATIONS
 C ARE CONSTANT OR VARIABLE, A VALUE OF ONE INDICATES ALL
 C OBSERVATIONS HAVE EQUAL WEIGHTS
 C IXBAR=SWITCH THAT INDICATES WHETHER THE WEIGHTED MEAN OF VARIABLES
 C SHOULD BE PRINTED, A VALUE OF ZERO INDICATES NO PRINT-OUT
 C IZ=FRACTIONAL PART OF IRET TO STILL BE RETRIEVED
 C J=DO LOOP PARAMETER
 C K=ROW AND COLUMN OF MATRIX A THAT CORRESPONDS TO THE INDEPENDENT
 C TERM THAT IS TO BE ADDED OR REMOVED
 C LEFT1=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION OF
 C THE TWO CHARACTERS X-
 C LEFT2=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION OF
 C THE TWO CHARACTERS Z(
 C LEFT3=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION OF
 C THE SIX CHARACTERS SUM X(
 C LEFT4=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION OF
 C THE TWO CHARACTERS X(
 C LEFT5=INTEGER VARIABLE WHOSE VALUE IS THE BINARY REPRESENTATION OF
 C THE FIVE CHARACTERS * Z(
 C LIST(I)=VALUE OF THE NUMBER OF THE INDEPENDENT TERM GENERATED IN
 C THE NORMAL MODE THAT CORRESPONDS TO THE NUMBER OF THE

C INDEPENDENT TERM GENERATED IN THE MODE OF THE PROGRAM BEING
 C PROCESSED
 C M=NUMBER OF OBSERVATIONS
 C MAX=THE NUMBER OF THE INDEPENDENT TERM THAT WOULD CAUSE THE
 C GREATEST VARIANCE REDUCTION WHEN PUT INTO REGRESSION
 C MAXP(I)=MAXIMUM POWER OF INDEPENDENT VARIABLE I ALLOWED IN ANY
 C INDEPENDENT TERM
 C MEANSS=SUM OF SQUARES OF THE MEAN IN THE ANALYSIS OF VARIANCE
 C TABLE
 C MIN=THE NUMBER OF THE INDEPENDENT TERM THAT WOULD CAUSE THE LEAST
 C VARIANCE INCREASE WHEN TAKEN OUT OF REGRESSION
 C MODE=ALPHA INFORMATION USED TO DETECT THE VARIABLE MODE
 C N=NUMBER OF INDEPENDENT TERMS + THE ONE DEPENDENT TERM
 C NCARD=NUMBER OF VARIABLE MODE CONTROL DATA CARDS
 C NM1=NUMBER OF INDEPENDENT TERMS
 C NODATA=WEIGHTED NUMBER OF DATA
 C N1=NUMBER OF INDEPENDENT VARIABLES + ONE FOR THE DEPENDENT
 C VARIABLE
 C N1M1=NUMBER OF INDEPENDENT VARIABLES
 C P(I)=POWER OF THE INDEPENDENT VARIABLE I NEEDED TO COMPOSE THE
 C INDEPENDENT TERM BEING CONSIDERED
 C PIVCOL=PIVOT COLUMN OF MATRIX A
 C PIVOT=PIVOT ELEMENT OF MATRIX A
 C PROD=CUMULATIVE PRODUCT OF INDEPENDENT VARIABLES TIMES THEIR
 C RESPECTIVE POWERS FOR THE INDEPENDENT TERM BEING CALCULATED
 C PRONUM=PROBLEM NUMBER
 C R(I, J)=SIMPLE CORRELATION COEFFICIENT OF VARIABLES I AND J
 C RATIO=F RATIO IN THE ANALYSIS OF VARIANCE TABLE
 C REGDF=DEGREES OF FREEDOM ATTRIBUTED TO REGRESSION
 C REGMS=REGRESSION MEAN SQUARE IN THE ANALYSIS OF VARIANCE TABLE
 C REGSS=REGRESSION SUM OF SQUARES IN THE ANALYSIS OF VARIANCE TABLE

C RESMS=RESIDUAL MEAN SQUARE IN THE ANALYSIS OF VARIANCE TABLE
 C RESS=RESIDUAL SUM OF SQUARES IN THE ANALYSIS OF VARIANCE TABLE
 C R2=MULTIPLE CORRELATION COEFFICIENT SQUARED
 C S(I,J)=WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS PRODUCTS OF
 C TERMS I AND J
 C SIGMA(I)=SQUARE ROOT OF S(I,I)
 C STEPNO=STEP NUMBER - NUMBER OF DIFFERENT REGRESSION EQUATIONS
 C CALCULATED
 C SUMPR=CUMULATIVE SUM OF EACH INDEPENDENT TERM TIMES ITS
 C CORRESPONDING REGRESSION COEFFICIENT FOR A GIVEN OBSERVATION
 C SUMSCP(I,J)=WEIGHTED SUM OF SQUARES AND CROSS PRODUCTS OF TERMS I
 C AND J
 C SUMVAR(I)=WEIGHTED SUMS OF TERM I
 C TEMP=TEMPORARY STORAGE AREA
 C TOALSS=TOTAL SUM OF SQUARES IN THE ANALYSIS OF VARIANCE TABLE
 C TOL=TOLERANCE TO CONTROL THE POSSIBILITY OF DEGENERACY
 C V=ADDITIONAL VARIANCE ATTRIBUTED TO THE INDEPENDENT TERM BEING
 C CONSIDERED
 C VMAX=VARIANCE REDUCTION BY ADDING A TERM - TERM NUMBER EQUALS MAX
 C VMIN=VARIANCE INCREASE BY DELETING A TERM - TERM NUMBER EQUALS MIN
 C WEIGHT=WEIGHTING FACTOR FOR A PARTICULAR OBSERVATION
 C X(I)=INDEPENDENT TERM I FOR A SPECIFIED OBSERVATION - IT IS
 C ONE OF MANY COMBINATIONS OF THE INDEPENDENT VARIABLES
 C X(N)=Z(N1)
 C XBAR(I)=WEIGHTED MEAN OF TERM I
 C YHAT=PREDICTED VALUE OF THE DEPENDENT VARIABLE
 C Z(I)=INDEPENDENT VARIABLE I, (I=1,N1M1), FOR A SPECIFIC
 C OBSERVATION
 C Z(N1)=THE DEPENDENT VARIABLE FOR A SPECIFIC OBSERVATION
 C
 C REAL Z(15),X(150),SUMVAR(150),XBAR(150),SUMSCP(150,150),S(150,150)

```

1, SIGMA(150), R(150, 150), A(150, 150), NODATA, MEANSS, B(150)
  INTEGER DF, STEPNO, PRONUM, MAXP(15), P(15), REGDF, LIST(150), CONTRL,
1DEPVAR, FMT(18), INVAR(150), INPTAP(20)
  DOUBLE PRECISION LEFT3, LEFT5
  EQUIVALENCE (SUMVAR, XBAR), (SUMSCP, S, R, A), (X, SIGMA)
  DATA LEFT1/2HX-/, LEFT2/2HZ(/, LEFT3/6HSUM X(/, LEFT4/2HX(/,
1LEFT5/5H * Z(/, IFORM/4HFORM/, ISTAR/4HSTAR/, IEND/4HEND /,
2INFO/4HINFO/, IPRIN/4HPRIN/, IMAX/4HMAX /, INORM/4HNORM/,
3IACCE/4HACCE/, IDELE/4HDELE/

```

```

C
C   SET THE TOLERANCE TO CONTROL THE POSSIBILITY OF DEGENERACY
C
  TOL=.001
C
C   READ CONTROL CARD - EITHER START OF INPUT DATA CARD OR INFORMATION
C   CARD
C
  10 READ(1, 1000, END=620)CONTRL, PRONUM, N1, F1, F2, IW
  1000 FORMAT(A4, 6X, 2I5, 2F5.2, I5)
C
C   IF THE LAST CARD READ WAS A START OF INPUT DATA CONTROL CARD, THEN
C   WRITE THE CARD IMAGES OF THE FOLLOWING INPUT DATA CARDS ON A
C   SPECIFIED LOGICAL UNIT (TAPE OR DISK) - OTHERWISE MAKE
C   FURTHER TESTS ON THE CARD IN QUESTION
C
  20 IF(CONTRL.NE.ISTAR) GO TO 50
C
C   READ A DATA CARD AND PLACE THE CARD IMAGE AS ALPHA INFORMATION IN
C   ARRAY INPTAP
C
  30 READ(1, 1010)INPTAP

```

```

1010 FORMAT(20A4)
C
C   IF THE MOST RECENTLY READ CARD WAS A DATA CARD, THEN WRITE THE
C       CARD IMAGE CONTAINED IN ARRAY INPTAP ON THE SPECIFIED UNIT -
C       OTHERWISE THE MOST RECENT CARD WAS AN END OF INPUT DATA
C       CONTROL CARD AND AN END OF FILE MARK IS WRITTEN ON THE UNIT
C       SPECIFIED
C
C   IF(INPTAP(1).EQ.IEND) GO TO 40
C
C   WRITE THE CARD IMAGE ON THE LOGICAL UNIT SPECIFIED
C
C   WRITE(4,1010)INPTAP
C
C   GO READ THE NEXT CARD - IT WILL BE A DATA CARD OR AN END OF INPUT
C       DATA CONTROL CARD
C
C   GO TO 30
C
C   WRITE AN END OF FILE MARK ON THE UNIT SPECIFIED
C
40  ENDFILE 4
    REWIND 4
C
C   GO READ THE NEXT CONTROL CARD - INFORMATION CARD
C
C   GO TO 10
C
C   CHECK WHETHER THE INFORMATION CONTROL CARD IS CORRECT
C
50  IF(CONTRL.EQ.INFO) GO TO 60

```

```

C
C   PRINT MESSAGE THAT THE INFORMATION CONTROL CARD IS INCORRECT
C
      WRITE(3, 3000)
3000 FORMAT(' INCORRECT OR MISSING CONTROL CARD - EITHER INFORMATION CA
      1RD OR START OF INPUT DATA CARD')
      GO TO 620
C
C   PRINT INFORMATION FROM THE INFORMATION CONTROL CARD
C
      60 WRITE(3, 3010)PRONUM, N1, F1, F2
3010 FORMAT('1PROBLEM NO', I5, '/' ' NO OF VARIABLES =', I5, '/' ' F LEVEL TO ENT
      1ER VARIABLE =', F5.2, '/' ' F LEVEL TO REMOVE VARIABLE =', F5.2)
C
C   READ PRINT CONTROL CARD
C
      READ(1, 1020)CONTRL, INDATA, ISUMVR, IXBAR, ISMSCP, IS, IR, ILIST, IRESID
1020 FORMAT(A4, 6X, 14I5)
C
C   CHECK WHETHER THE PRINT CONTROL CARD IS CORRECT
C
      IF(CONTRL. EQ. IPRIN) GO TO 70
C
C   PRINT MESSAGE THAT PRINT CONTROL CARD IS INCORRECT
C
      WRITE(3, 3020)
3020 FORMAT(' INCORRECT OR MISSING CONTROL CARD - PRINT CARD')
      GO TO 620
C
C   COMPUTE THE NUMBER OF INDEPENDENT VARIABLES (N1M1)
C

```

```

70 N1M1=N1-1
C
C   READ MAXIMUM POWERS CONTROL CARD
C
C   READ(1, 1020)CONTRL, (MAXP(I), I=1, N1M1)
C
C   CHECK WHETHER THE MAXIMUM POWERS CONTROL CARD IS CORRECT
C
C   IF(CONTRL. EQ. IMAX) GO TO 80
C
C   PRINT MESSAGE THAT THE MAXIMUM POWERS CONTROL CARD IS INCORRECT
C
C   WRITE(3, 3030)
3030 FORMAT(' INCORRECT OR MISSING CONTROL CARD - MAXIMUM POWERS CARD')
C   GO TO 620
C
C   READ FORMAT CONTROL CARD
C
C   80 READ(1, 1030)CONTRL, FMT, DEPVAR
1030 FORMAT(A4, 2X, 18A4, I2)
C
C   CHECK WHETHER THE FORMAT CONTROL CARD IS CORRECT
C
C   IF(CONTRL. EQ. IFORM) GO TO 90
C
C   PRINT MESSAGE THAT FORMAT CONTROL CARD IS INCORRECT
C
C   WRITE(3, 3040)
3040 FORMAT(' INCORRECT OR MISSING CONTROL CARD - FORMAT CARD')
C   GO TO 620
C

```

```

C      READ THE VARIABLE MODE CONTROL CARD
C
90 READ(1,1020)MODE,NCARD
C
C      DETERMINE THE VARIABLE MODE (ACCEPT, DELETE, OR NORMAL)
C
      IF(MODE.EQ.INORM) GO TO 110
      IF((MODE.EQ.IDELE).OR.(MODE.EQ.IACCE)) GO TO 100
C
C      PRINT MESSAGE THAT THE VARIABLE MODE CONTROL CARD IS INCORRECT
C
      WRITE(3,3050)
3050 FORMAT(' INCORRECT OR MISSING CONTROL CARD - VARIABLE MODE CARD')
      GO TO 620
C
C      GENERATE A LIST OF INDEPENDENT TERM NUMBERS FOR THE VARIABLE MODE
C      BEING CONSIDERED - THE LIST IS COMPOSED OF A SUBSET OF THE
C      COMPLETE SET OF TERM NUMBERS, AND CONTAINS THE TERM NUMBERS
C      OF THE INDEPENDENT TERMS BEING USED AS IF THEY HAD BEEN
C      GENERATED IN THE NORMAL MODE
C
100 CALL GENLST(MODE,N1M1,N,NM1,NCARD,MAXP(1),LIST(1),A(1,1),A(1,76))
      GO TO 130
C
C      COMPUTE THE NUMBER OF TERMS IN THE NORMAL MODE (N)
C
110 N=1
      DO 120 I=1,N1M1
120 N=N*(MAXP(I)+1)
C
C      COMPUTE THE NUMBER OF INDEPENDENT TERMS IN THE NORMAL MODE (NM1)

```

```

C
    NM1=N-1
C
C    PRINT INFORMATION ON THE MAXIMUM POWERS CONTROL CARD
C
    130 WRITE(3, 3060)N1M1, NM1, (LEFT1, I, MAXP(I), I=1, N1M1)
    3060 FORMAT('/' NO. OF INDEPENDENT VARIABLES =', I3/' NO. OF INDEPENDENT
        1 TERMS =', I4/' 3X, 'INDEPENDENT', 4X, 'MAX'/5X, 'VARIABLE', 4X, 'POWER'/
        2(7X, A2, I2, 7X, I2))
C
C    CHECK WHETHER THE INPUT DATA SHOULD BE PRINTED
C
    IF(INDATA.EQ.0)GO TO 140
C
C    PRINT HEADING FOR INPUT DATA
C
    WRITE(3, 3070)(LEFT2, (I), I=1, N1)
    3070 FORMAT(///20X, 'INPUT DATA'/' OBSERVATION', 10(3X, A2, I2, ')', 2X)/
        1(15X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')',
        2, 5X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')', 5X, A2, I2, ')')
        3)
C
C    INITIALIZE THE ARRAYS SUMVAR AND SUMSCP TO THE VALUE ZERO
C
    140 DO 150 I=1, N
        SUMVAR(I)=0.0
        DO 150 J=1, N
    150 SUMSCP(I, J)=0.0
C
C    INITIALIZE THE WEIGHTED NUMBER OF DATA, THE WEIGHT, AND THE
C    NUMBER OF OBSERVATIONS

```



```

C      NODATA=0.0
      WEIGHT=1.0
      M=0
C
C      DETERMINE WHETHER ALL OBSERVATIONS HAVE THE SAME WEIGHT
C
C      160 IF(IW.EQ.0) GO TO 162
C
C      READ ONE OBSERVATION OF THE INPUT DATA FROM THE SPECIFIED LOGICAL
C      UNIT WITH THE FORMAT OF THE FORMAT CONTROL CARD
C
C      READ(4,FMT,END=240)(Z(J),J=1,N1)
      GO TO 170
C
C      READ ONE OBSERVATION OF THE INPUT DATA AND THE WEIGHT OF THAT
C      OBSERVATION FROM THE SPECIFIED LOGICAL UNIT WITH THE FORMAT
C      OF THE FORMAT CONTROL CARD
C
C      162 READ(4,FMT,END=240)(Z(J),J=1,N1), WEIGHT
C
C      INCREMENT THE NUMBER OF OBSERVATIONS BY ONE
C
C      170 M=M+1
C
C      MOVE THE VALUE OF THE DEPENDENT VARIABLE TO A TEMPORARY STORAGE
C      AREA
C
C      TEMP=Z(DEPVAR)
C
C      MOVE THE VALUE OF EACH INPUT VARIABLE POSITIONED BEYOND THE

```

```

C          DEPENDENT VARIABLE TO THE LOCATION OF THE INPUT VARIABLE
C          THAT PRECEDED IT
C
C          DO 180 J=DEPVAR, N1M1
180 Z(J)=Z(J+1)
C
C          MOVE THE VALUE OF THE DEPENDENT VARIABLE TO THE LOCATION OF THE
C          LAST INPUT VARIABLE
C
C          Z(N1)=TEMP
C
C          CHECK WHETHER THE INPUT DATA OF THE OBSERVATION BEING CONSIDERED
C          SHOULD BE PRINTED
C
C          IF(INDATA.EQ. 0)GO TO 190
C
C          PRINT THE INPUT DATA OF THE OBSERVATION BEING CONSIDERED
C
C          WRITE(3, 3080)M, (Z(J), J=1, N1)
3080 FORMAT(3X, I4, 4X, 10F10.3, (/11X, 10F10.3))
C
C          INCREMENT THE WEIGHTED NUMBER OF DATA BY THE WEIGHT
C
C          190 NODATA=NODATA+WEIGHT
C
C          IF THE MODE OF THE PROGRAM IS NORMAL, THEN CALL SUBROUTINE EXPAND
C          TO GENERATE A COMPLETE SET OF TERMS - OTHERWISE CALL
C          SUBROUTINE GENTRM TO GENERATE A SUBSET OF THE COMPLETE SET
C          OF TERMS
C
C          IF(MODE.EQ. INORM) GO TO 200

```

```

C
C   GENERATE THE TERMS FOR THE OBSERVATION AND MODE (ACCEPT OR DELETE)
C   BEING CONSIDERED
C
C   CALL GENTRM(N1M1, NM1, MAXP(1), LIST(1), Z(1), X(1))
C   GO TO 210
C
C   GENERATE ALL TERMS IN NORMAL MODE FOR THE OBSERVATION BEING
C   CONSIDERED
C
C   200 CALL EXPAND(N1M1, MAXP(1), Z(1), X(1))
C   210 DO 220 J=1, N
C
C   UPDATE THE CUMULATIVE WEIGHTED SUM OF TERMS BY ADDING THE
C   CONTRIBUTION OF THE OBSERVATION BEING CONSIDERED
C
C   220 SUMVAR(J)=SUMVAR(J)+WEIGHT*X(J)
C       DO 230 I=1, N
C       DO 230 J=I, N
C
C   UPDATE THE CUMULATIVE WEIGHTED SUM OF SQUARES AND CROSS PRODUCTS
C   BY ADDING THE CONTRIBUTION OF THE OBSERVATION BEING
C   CONSIDERED
C
C   230 SUMSCP(I, J)=SUMSCP(I, J)+WEIGHT*X(I)*X(J)
C       GO TO 160
C
C   PRINT THE NUMBER OF OBSERVATIONS AND THE WEIGHTED NUMBER OF DATA
C
C   240 WRITE(3, 3090)M, NODATA
C   3090 FORMAT('/' NO. OF OBSERVATIONS =', I5//' WEIGHTED NO. OF DATA =',

```

```

1F7. 2)
C
C   CHECK WHETHER THE WEIGHTED SUM OF TERMS SHOULD BE PRINTED
C
C   IF(ISUMVR. EQ. 0)GO TO 250
C
C   PRINT THE WEIGHTED SUM OF TERMS
C
C   WRITE(3, 3100)
3100 FORMAT(///20X, 'WEIGHTED SUMS OF VARIABLES'/)
C   WRITE(3, 3110)((LEFT3, I, SUMVAR(I)), I=1, NM1)
3110 FORMAT(3(1X, A6, I2, ' ) =', F14. 5, 4X))
C   WRITE(3, 3120)SUMVAR(N)
3120 FORMAT(' SUM    Y    =', F14. 5)
250 DO 260 I=1, N
C
C   COMPUTE THE WEIGHTED MEAN OF ALL THE TERMS
C
C   260 XBAR(I)=SUMVAR(I)/NODATA
C
C   CHECK WHETHER THE WEIGHTED MEANS SHOULD BE PRINTED
C
C   IF(IXBAR. EQ. 0)GO TO 270
C
C   PRINT THE WEIGHTED MEANS
C
C   WRITE(3, 3130)
3130 FORMAT(///20X, 'WEIGHTED MEAN OF VARIABLES'/)
C   WRITE(3, 3110)((LEFT3, I, XBAR(I)), I=1, NM1)
C   WRITE(3, 3120)XBAR(N)
C

```

```

C      CHECK WHETHER THE WEIGHTED SUM OF SQUARES AND CROSS PRODUCTS
C      SHOULD BE PRINTED
C
270 IF(ISMSCP.EQ.0) GO TO 280
C
C      PRINT THE WEIGHTED SUM OF SQUARES AND CROSS PRODUCTS
C
      WRITE(3,3140)
3140 FORMAT(///20X,'WEIGHTED SUMS OF SQUARES AND CROSS PRODUCTS'/)
      WRITE(3,3150)((LEFT4,I,J,SUMSCP(I,J)),J=I,NM1),I=1,NM1)
3150 FORMAT(3(1X,A2,I2,' ) VS X(',I2,' ) =',F16.5,4X))
      WRITE(3,3160)((LEFT4,I,SUMSCP(I,N)),I=1,NM1)
3160 FORMAT(3(1X,A2,I2,' ) VS Y =',F16.5,4X))
      WRITE(3,3170)SUMSCP(N,N)
3170 FORMAT(' Y VS Y =',F16.5)
C
C      COMPUTE THE TOTAL SUM OF SQUARES OF THE DEPENDENT VARIABLE FOR
C      THE ANALYSIS OF VARIANCE TABLE
C
280 TOALSS=SUMSCP(N,N)
      DO 300 I=1,N
      DO 290 J=I,N
C
C      COMPUTE THE WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS PRODUCTS
C      FOR ALL TERMS
C
290 S(I,J)=SUMSCP(I,J)-XBAR(I)*XBAR(J)*NODATA
300 SIGMA(I)=SQRT(S(I,I))
C
C      CHECK WHETHER THE WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS
C      PRODUCTS SHOULD BE PRINTED

```

```

C
  IF(IS.EQ.0) GO TO 310
C
C   PRINT THE WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS PRODUCTS
C
  WRITE(3,3180)
3180 FORMAT(///20X,'WEIGHTED RESIDUAL SUM OF SQUARES AND CROSS PRODUCTS
1')
  WRITE(3,3150)((LEFT4,I,J,S(I,J)),J=1,NM1),I=1,NM1)
  WRITE(3,3160)((LEFT4,I,S(I,N)),I=1,NM1)
  WRITE(3,3170)S(N,N)
C
C   COMPUTE THE SUM OF SQUARES OF THE MEAN FOR THE AOV TABLE
C
310 MEANSS=TOALSS-S(N,N)
  DO 320 I=1,NM1
  IP1=I+1
  DO 320 J=IP1,N
C
C   COMPUTE THE STRICTLY UPPER TRIANGULAR PART OF THE MATRIX OF
C   SIMPLE CORRELATION COEFFICIENTS
C
320 R(I,J)=S(I,J)/(SIGMA(I)*SIGMA(J))
  DO 330 I=1,NM1
  IP1=I+1
  DO 330 J=IP1,N
C
C   COMPUTE THE STRICTLY LOWER TRIANGULAR PART OF THE MATRIX OF SIMPLE
C   CORRELATION COEFFICIENTS
C
330 R(J,I)=R(I,J)

```

```

DO 340 I=1, N
C
C   COMPUTE THE DIAGONAL ELEMENTS OF THE MATRIX OF SIMPLE CORRELATION
C   COEFFICIENTS
C
340 R(I, I)=1. 0
C
C   CHECK WHETHER THE MATRIX OF SIMPLE CORRELATION COEFFICIENTS SHOULD
C   BE PRINTED
C
IF(IR. EQ. 0) GO TO 350
C
C   PRINT THE MATRIX OF SIMPLE CORRELATION COEFFICIENTS
C
WRITE(3, 3190)
3190 FORMAT(///20X, 'CORRELATION COEFFICIENTS'/)
WRITE(3, 3150)((LEFT4, I, J, R(I, J)), J=I, NM1), I=1, NM1)
WRITE(3, 3160)((LEFT4, I, R(I, N)), I=1, NM1)
C
C   COMPUTE THE DEGREES OF FREEDOM
C
350 DF=NODATA-1. 0
C
C   COMPUTE THE STANDARD ERROR OF Y (THE DEPENDENT VARIABLE)
C
ERRORY=SIGMA(N)*SQRT(R(N, N)/DF)
C
C   PRINT THE STANDARD ERROR OF Y
C
WRITE(3, 3200)ERRORY
3200 FORMAT('/ STANDARD ERROR OF Y =', F8. 3)

```

```

C
C CHECK WHETHER THE LIST OF TERM NUMBERS THAT IS A SUBSET OF THE
C COMPLETE SET OF TERM NUMBERS SHOULD BE PRINTED - ONLY
C APPLICABLE WHEN IN DELETE OR ACCEPT MODE
C
C IF(ILIST.EQ.0) GO TO 360
C
C PRINT THE LIST OF CORRESPONDING TERM NUMBERS
C
C WRITE(3,3210)(I,LIST(I),I=1,NM1)
3210 FORMAT(/' LIST GENERATION'/3X,'(TERM GENERATED) CORRESPONDS TO THE
1 X TERM GENERATED IN THE NORMAL MODE'//5X,'TERM NO.',3X,'TERM GENE
2RATED'/(6X,I5,6X,I5))
C
C INITIALIZE VMAX (VARIANCE REDUCTION) TO ZERO
C
C 360 VMAX=0.0
C DO 370 I=1,NM1
C
C FIND THE SIMPLE CORRELATION COEFFICIENT WITH THE LARGEST ABSOLUTE
C VALUE - STORE THE VALUE IN VMAX AND THE SUBSCRIPT OF THE
C CORRESPONDING TERM IN MAX - THIS TERM IS THE MOST HIGHLY
C CORRELATED WITH THE DEPENDENT VARIABLE (Y)
C
C IF(ABS(R(I,N)).LE.VMAX) GO TO 370
C MAX=I
C VMAX=ABS(R(I,N))
370 CONTINUE
C
C COMPUTE THE VARIANCE REDUCTION OF THE MOST HIGHLY CORRELATED TERM
C

```



```

      VMAX=A(MAX, N)*A(N, MAX)
C
C   INITIALIZE THE STEP NUMBER TO THE FIRST STEP
C
      STEPNO=1
      GO TO 480
C
C   INCREMENT THE STEP NUMBER
C
380  STEPNO=STEPNO+1
C
C   COMPUTE AND PRINT THE STANDARD ERROR OF Y FOR THE MOST RECENT
C   REGRESSION EQUATION
C
      ERRORY=SIGMA(N)*SQRT(A(N, N)/DF)
      WRITE(3, 3220)ERRORY
3220  FORMAT(3X, 'STANDARD ERROR OF Y =', F12.4/3X, 'ANALYSIS OF VARIANCE'
1/12X, 'SOURCE', 6X, 'DF', 4X, 'SUM OF SQUARES', 4X, 'MEAN SQUARE', 3X,
2'F RATIO')
C
C   PRINT THE TOTAL DEGREES OF FREEDOM AND THE TOTAL SUM OF SQUARES
C   FOR THE ANALYSIS OF VARIANCE TABLE
C
      WRITE(3, 3230)M, TOALSS
3230  FORMAT(10X, 'TOTAL', 7X, I4, 4X, F14.3)
C
C   PRINT THE DEGREES OF FREEDOM (1) AND THE SUM OF SQUARES FOR THE
C   MEAN
C
      WRITE(3, 3240)MEANSS
3240  FORMAT(10X, 'MEAN', 11X, '1', 4X, F14.3)

```

```

C
C   COMPUTE AND PRINT DEGREES OF FREEDOM (REGDF,RESDF), SUM OF SQUARES
C   (REGSS,RESSS), AND MEAN SQUARES (REGMS,RESMS) FOR REGRESSION
C   AND RESIDUALS - AND COMPUTE AND PRINT THE F RATIO
C
REGDF=NODATA-DF-1
RESSS=A(N,N)*(TOALSS-MEANSS)
REGSS=TOALSS-MEANSS-RESSS
REGMS=REGSS/REGDF
RESMS=RESSS/DF
RATIO=REGMS/RESMS
WRITE(3,3250)REGDF,REGSS,REGMS,RATIO
3250 FORMAT(10X,'REGRESSION',2X,I4,4X,F14.3,2X,F13.3,2X,F8.3)
WRITE(3,3260)DF,RESSS,RESMS
3260 FORMAT(10X,'RESIDUAL',4X,I4,4X,F14.3,2X,F13.3/3X,'VARIABLES IN EQU
1ATION'/10X,'VARIABLE',5X,'COEFFICIENT',5X,'STD ERROR OF COEF')
C
C   INITIALIZE THE NUMBER OF THE TERM BEING CONSIDERED (I), THE
C   SUBSCRIPT FOR THE VECTOR CONTAINING TERMS IN THE REGRESSION
C   EQUATION (INEQ), VARIANCE INCREASE BY DELETING A TERM (VMIN),
C   VARIANCE REDUCTION BY ADDING A TERM (VMAX), NUMBER OF THE
C   TERM CORRESPONDING TO VMIN (MIN), NUMBER OF THE TERM
C   CORRESPONDING TO VMAX (MAX), AND THE CONSTANT TERM (BZERO)
C   EACH TIME A NEW REGRESSION EQUATION IS REVIEWED
C
I=1
INEQ=0
VMIN=5.E10
VMAX=0.0
MIN=0
MAX=0

```

```

      BZERO=0.0
C
C      TEST WHETHER THE TERM CORRESPONDING TO THE DIAGONAL ELEMENT BEING
C      CONSIDERED IN MATRIX A IS DEGENERATIVE
C
390 IF(A(I,I). LE. TOL)GO TO 420
C
C      COMPUTE THE ADDITIONAL VARIANCE ATTRIBUTED TO THE TERM BEING
C      CONSIDERED
C
      V=A(I, N)*A(N, I)/A(I, I)
C
C      IF THE TERM BEING CONSIDERED HAS A NEGATIVE VARIANCE CONTRIBUTION
C      THEN PLACE IT IN THE REGRESSION EQUATION
C
      IF(V)410, 420, 400
C
C      IF THE VARIANCE CONTRIBUTION IS POSITIVE AND GREATER THAN VMAX,
C      THEN ENTER THE VARIANCE CONTRIBUTION INTO VMAX AND ITS
C      CORRESPONDING TERM NUMBER INTO MAX - THIS TERM WILL CAUSE THE
C      GREATEST VARIANCE REDUCTION WHEN INTRODUCED INTO REGRESSION
C
400 IF(V. LE. VMAX)GO TO 420
      VMAX=V
      MAX=I
      GO TO 420
C
C      INCREMENT THE SUBSCRIPT OF THE VECTOR CONTAINING TERMS IN THE
C      REGRESSION EQUATION - THIS IS ALSO THE NUMBER OF TERMS
C      PRESENTLY IN REGRESSION
C

```

```

410 INEQ=INEQ+1
C
C   COMPUTE THE COEFFICIENT FOR THIS PARTICULAR TERM IN THE REGRESSION
C   EQUATION
C
C    $B(INEQ) = A(I, N) * SIGMA(N) / SIGMA(I)$ 
C
C   UPDATE THE CONSTANT TERM BY ADDING THE CONTRIBUTION OF THE TERM
C   BEING CONSIDERED
C
C    $BZERO = BZERO + B(INEQ) * XBAR(I)$ 
C
C   COMPUTE THE STANDARD ERROR OF THE COEFFICIENT FOR THE TERM BEING
C   CONSIDERED
C
C    $ERRORC = ERRORY / SIGMA(I) * SQRT(A(I, I))$ 
C
C   PRINT THE NUMBER OF THE TERM BEING CONSIDERED, ITS COEFFICIENT,
C   AND ITS STANDARD ERROR
C
C   WRITE(3, 3270)I, B(INEQ), ERRORC
3270 FORMAT(12X, 'X-', I3, 6X, F10.5, 7X, F10.5)
C
C   MOVE THE NUMBER OF THIS TERM THAT IS IN THE REGRESSION EQUATION
C   INTO THE VECTOR INVAR
C
C    $INVAR(INEQ) = I$ 
C
C   IF THE MAGNITUDE OF THE VARIANCE CONTRIBUTION IS LESS THAN THE
C   MAGNITUDE OF VMIN, THEN ENTER THE VARIANCE CONTRIBUTION INTO
C   VMIN AND ITS CORRESPONDING TERM NUMBER INTO MIN - THIS TERM

```

```

C          WILL CAUSE THE LEAST VARIANCE INCREASE WHEN DELETED FROM
C          REGRESSION
C
C          IF(ABS(V). GE. ABS(VMIN))GO TO 420
C          VMIN=V
C          MIN=I
C
C          IF ALL INDEPENDENT TERMS HAVE BEEN INVESTIGATED, THEN GO CALCULATE
C          THE POWERS OF THE INDEPENDENT VARIABLES FOR THE INDEPENDENT
C          TERMS IN REGRESSION - OTHERWISE INCREMENT THE TERM COUNTER BY
C          ONE AND PROCESS THE NEXT INDEPENDENT TERM
C
C          420 IF(I. EQ. NM1) GO TO 430
C              I=I+1
C              GO TO 390
C          430 DO 470 J=1,INEQ
C
C          IF THE NORMAL MODE IS USED, SET IRET EQUAL TO THE TERM NUMBER
C          BEING CONSIDERED (INVAR(J)) - OTHERWISE, SET IRET EQUAL TO
C          THE NUMBER THE TERM BEING CONSIDERED WOULD HAVE HAD IF IT
C          WAS IN THE NORMAL MODE
C
C          IF(MODE. EQ. INORM) GO TO 440
C          IRET=LIST(INVAR(J))
C          GO TO 450
C          440 IRET=INVAR(J)
C
C          DETERMINE THE POWERS OF THE INDEPENDENT VARIABLES THAT CORRESPOND
C          TO THE TERM BEING CONSIDERED - THIS IS DONE BY REPEATED
C          DIVISIONS
C

```

```

450 DO 460 IJ=1,N1M1
C
C   DIVIDE BY (THE MAXIMUM POWER OF THE PARTICULAR INDEPENDENT
C     VARIABLE + ONE) AND THEN TRUNCATE
C
C     IZ=IRET/(MAXP(N1-IJ)+1)
C
C   SUBTRACT THE TRUNCATED VALUE FROM THE ORIGINAL VALUE TO OBTAIN
C     THE PARTICULAR POWER
C
C     P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
C
C   DROP THE PART OF THE TERM ALREADY DIVIDED OUT
C
460 IRET=IZ
C
C   PRINT THE TERM BEING CONSIDERED AND ITS CORRESPONDING POWERS OF
C     THE INDEPENDENT VARIABLES
C
470 WRITE(3,3280)INVAR(J), P(1), (LEFT5,IK, P(IK), IK=2, N1M1)
3280 FORMAT(17X, 'X(', I3, 11H) = Z( 1)**, I1, 9(A5, I2, 3H)**, I1)/(23X, A5, I2,
13H)**, I1, A5, I2, 3H)**, I1, A5, I2, 3H)**, I1, A5, I2, 3H)**, I1, A5, I2, 3H)**,
2I1, A5, I2, 3H)**, I1, A5, I2, 3H)**, I1, A5, I2, 3H)**, I1, A5, I2, 3H)**, I1, A5,
3I2, 3H)**, I1))
C
C   CALCULATE THE CONSTANT TERM
C
C     BZERO=XBAR(N)-BZERO
C
C   COMPUTE THE MULTIPLE CORRELATION COEFFICIENT SQUARED
C

```

```

R2=(1-A(N,N))*100.0
C
C   PRINT THE CONSTANT TERM AND THE MULTIPLE CORRELATION COEFFICIENT
C   SQUARED
C
C   WRITE(3, 3290)BZERO, R2
3290 FORMAT(3X, 'CONSTANT =', F12.5/3X, 'MULTIPLE CORRELATION COEFFICIENT
1SQUARED =', F6.2, ' PERCENT')
C
C   COMPUTE THE F VALUE OF THE INDEPENDENT TERM IN REGRESSION THAT HAS
C   THE LEAST CONTRIBUTION TO THE REDUCTION OF VARIANCE
C
C   FTEST2=ABS(VMIN)*DF/A(N, N)
C
C   TEST THIS COMPUTED F VALUE AGAINST A SPECIFIED TABULAR F VALUE -
C   IF THE COMPUTED VALUE IS LESS THAN THE TABULAR VALUE, THEN
C   REMOVE THE INDEPENDENT TERM FROM REGRESSION - OTHERWISE GO
C   TEST FOR THE ADDITION OF ANOTHER INDEPENDENT TERM
C
C   IF(FTEST2.GE. F2)GO TO 480
C
C   PRINT THE STEP NUMBER, THE INDEPENDENT TERM REMOVED FROM
C   REGRESSION, AND THE COMPUTED F VALUE OF THE TERM
C
C   WRITE(3, 3300)STEPNO, MIN, FTEST2
3300 FORMAT(///1X, 'STEP NO. ', I3/3X, 'VARIABLE REMOVED', I4/
13X, 'F LEVEL', F8.4)
C
C   SET THE SUBSCRIPT OF THE PIVOT ELEMENT EQUAL TO THE NUMBER OF THE
C   TERM JUST REMOVED FROM REGRESSION
C

```

```

      K=MIN
C
C      INCREASE THE RESIDUAL DEGREES OF FREEDOM BY ONE TO ACCOUNT FOR THE
C      TERM JUST REMOVED FROM REGRESSION
C
      DF=DF+1
C
      GO DO A TRANSFORMATION ON MATRIX A
C
      GO TO 560
C
      COMPUTE THE F VALUE OF THE MOST HIGHLY CORRELATED TERM THAT IS NOT
      ALREADY IN REGRESSION
C
480  FTEST1=VMAX*(DF-1)/(A(N,N)-VMAX)
C
      TEST WHETHER THE TERM SHOULD ENTER THE REGRESSION EQUATION BY
      CHECKING ITS COMPUTED F VALUE AGAINST A SPECIFIED TABULAR F
      VALUE - IF THE COMPUTED VALUE IS GREATER THAN THE TABULAR
      VALUE, THEN GO ENTER THE TERM INTO REGRESSION - OTHERWISE
      REPOSITION THE DATA POINTER ON THE UNIT SPECIFIED TO THE
      LOCATION OF THE FIRST INPUT DATA ELEMENT
C
      IF(FTEST1.GT.F1) GO TO 550
      REWIND 4
C
      CHECK WHETHER THE RESIDUALS SHOULD BE PRINTED - IF NOT, THEN GO
      READ IN THE NEXT CONTROL CARD
C
      IF(IRESID.EQ.0) GO TO 10
C

```



```

C      PRINT THE HEADING FOR THE RESIDUALS
C
      WRITE(3, 3310)
3310  FORMAT(3X, 'PREDICTED VS. ACTUAL RESULTS'/10X, 'OBSERVATION', 10X,
      1'ACTUAL', 11X, 'PREDICTED', 11X, 'DEVIATION')
      DO 540 IK=1, M
C
C      READ AN OBSERVATION OF INPUT DATA FROM THE UNIT SPECIFIED
C
      READ(4, FMT)(Z(J), J=1, N1)
C
C      MOVE THE VALUE OF THE DEPENDENT VARIABLE TO A TEMPORARY STORAGE
C      AREA
C
      TEMP=Z(DEPVAR)
C
C      MOVE THE VALUE OF EACH INPUT VARIABLE POSITIONED BEYOND THE
C      DEPENDENT VARIABLE TO THE LOCATION OF THE INPUT VARIABLE
C      THAT PRECEDED IT
C
      DO 485 IL=DEPVAR, N1M1
485  Z(IL)=Z(IL+1)
C
C      MOVE THE VALUE OF THE DEPENDENT VARIABLE TO THE LOCATION OF THE
C      LAST INPUT VARIABLE
C
      Z(N1)=TEMP
C
C      INITIALIZE SUMPR ( THE SUM OF INDEPENDENT TERMS TIMES THEIR
C      RESPECTIVE REGRESSION COEFFICIENTS FOR THE OBSERVATION BEING
C      CONSIDERED )

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```

C
    SUMPR=0.0
    DO 530 J=1,INEQ
C
C    IF NORMAL MODE IS USED SET IRET EQUAL TO THE TERM NUMBER BEING
C        CONSIDERED - OTHERWISE SET IRET EQUAL TO THE NUMBER THE TERM
C        WOULD HAVE HAD IF THE MODE WAS NORMAL
C
    IF(MODE.EQ.INORM) GO TO 490
    IRET=LIST(INVAR(J))
    GO TO 500
490 IRET=INVAR(J)
C
C    DETERMINE THE POWERS OF THE INDEPENDENT VARIABLES THAT CORRESPOND
C        TO THE TERM BEING CONSIDERED - THIS IS DONE BY REPEATED
C        DIVISIONS
C
500 DO 510 IJ=1,N1M1
C
C    DIVIDE BY (MAXIMUM POWER OF THE PARTICULAR INDEPENDENT VARIABLE +
C        ONE) AND THEN TRUNCATE
C
    IZ=IRET/(MAXP(N1-IJ)+1)
C
C    SUBTRACT THE TRUNCATED VALUE FROM THE ORIGINAL VALUE TO OBTAIN
C        THE PARTICULAR POWER
C
    P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
C
C    DROP THE PART OF THE TERM ALREADY DIVIDED OUT
C

```

```

510 IRET=IZ
C
C   INITIALIZE PROD (THE PRODUCT OF THE INDEPENDENT VARIABLES TIMES
C       THEIR RESPECTIVE POWERS FOR THE INDEPENDENT TERM BEING
C       CALCULATED)
C
C       PROD=1.0
C       DO 520 II=1,N1M1
C
C       IF THE POWER OF THE INDEPENDENT VARIABLE IN QUESTION IS ZERO, THEN
C           IT SHOULD NOT BE CONSIDERED WHEN BUILDING AN INDEPENDENT TERM
C
C       IF(P(II).EQ.0) GO TO 520
C
C       UPDATE PROD BY MULTIPLYING IT BY THE INDEPENDENT VARIABLE BEING
C           CONSIDERED TIMES ITS CORRESPONDING POWER
C
C       PROD=PROD*Z(II)**P(II)
520 CONTINUE
C
C       UPDATE SUMPR BY ADDING IN PROD TIMES THE REGRESSION COEFFICIENT OF
C           THE INDEPENDENT TERM BEING CONSIDERED
C
530 SUMPR=SUMPR+PROD*B(J)
C
C       CALCULATE THE PREDICTED VALUE OF THE DEPENDENT VARIABLE
C
C       YHAT=BZERO+SUMPR
C
C       CALCULATE THE DEVIATION BETWEEN THE ACTUAL VALUE AND THE PREDICTED
C           VALUE OF THE DEPENDENT VARIABLE FOR THE OBSERVATION BEING

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```

C          CONSIDERED
C
C      DEV=Z(N1)-YHAT
C
C      PRINT THE OBSERVATION NUMBER, THE ACTUAL VALUE, THE PREDICTED
C      VALUE, AND THE DEVIATION BETWEEN THE ACTUAL AND PREDICTED
C      VALUE OF THE DEPENDENT VARIABLE
C
C      540 WRITE(3, 3320)IK, Z(N1), YHAT, DEV
C      3320 FORMAT(12X, I5, 4X, F16.5, 4X, F16.5, 4X, F16.5)
C
C      REPOSITION THE DATA COUNTER TO THE LOCATION OF THE FIRST INPUT
C      DATA ELEMENT ON THE UNIT SPECIFIED
C
C      REWIND 4
C
C      GO READ THE NEXT CONTROL CARD
C
C      GO TO 10
C
C      PRINT THE STEP NUMBER, TERM ENTERING THE REGRESSION EQUATION, AND
C      THE COMPUTED F VALUE
C
C      550 WRITE(3, 3330)STEPNO, MAX, FTEST1
C      3330 FORMAT(///1X, 'STEP NO. ', I3/3X, 'VARIABLE ENTERING', I4/
C      13X, 'F LEVEL', F8.4)
C
C      SET THE SUBSCRIPT OF THE PIVOT ELEMENT EQUAL TO THE NUMBER OF THE
C      TERM ENTERING REGRESSION
C
C      K=MAX

```

```

C
C   DECREASE THE RESIDUAL DEGREES OF FREEDOM BY ONE TO ACCOUNT FOR THE
C   TERM ENTERING REGRESSION
C
C   DF=DF-1
C
C   SET THE PIVOT ELEMENT (PIVOT) FOR TRANSFORMATION OF MATRIX A
C   (THE FIRST TIME MATRIX A = MATRIX R)
C
560 PIVOT=A(K, K)
    DO 590 I=1, N
    IF(I. EQ. K)GO TO 590
C
C   COMPUTE THE ELEMENT NEEDED IN THE PIVOT COLUMN FOR THE ROW OF
C   MATRIX A BEING PROCESSED
C
    PIVCOL=A(I, K)
    DO 580 J=1, N
    IF(J. EQ. K)GO TO 570
C
C   CALCULATE NEW A(I, J) FOR I NOT EQUAL TO K AND J NOT EQUAL TO K
C
    A(I, J)=(A(I, J)*PIVOT-PIVCOL*A(K, J))/PIVOT
    GO TO 580
C
C   CALCULATE NEW A(I, J) FOR I NOT EQUAL K AND J EQUAL K
C
570 A(I, J)=-A(I, K)/PIVOT
580 CONTINUE
590 CONTINUE
    DO 610 J=1, N

```

```

        IF(J.EQ.K) GO TO 600
C
C      CALCULATE NEW A(I, J) FOR I EQUAL K AND J NOT EQUAL K
C
      A(K, J)=A(K, J)/ PIVOT
      GO TO 610
C
C      CALCULATE NEW A(K, K)
C
600 A(K, K)=1. 0/ PIVOT
610 CONTINUE
      GO TO 380
620 CALL EXIT
      END

```

SUBROUTINE GENLST(MODE, N1M1, N, NM1, NCARD, MAXP, LIST, ELM, ALPHA)

THIS SUBROUTINE GENERATES A LIST OF TERM NUMBERS - WHEN IN THE NORMAL MODE MANY COMBINATIONS OF THE POWERS OF THE INDEPENDENT VARIABLES ARE POSSIBLE WITHOUT EXCEEDING THE MAXIMUM POWER OF ANY INDEPENDENT VARIABLE - EACH POSSIBLE COMBINATION REPRESENTS ONE INDEPENDENT TERM - ALL POSSIBLE COMBINATIONS MAKE UP A COMPLETE SET OF TERMS - THESE INDEPENDENT TERMS ARE GENERATED IN AN ORDERLY FASHION SO THAT EACH INDEPENDENT TERM IS GIVEN A CONSECUTIVE NUMBER - WHEN IN ACCEPT OR DELETE MODE, ONLY A SUBSET OF THE COMPLETE SET OF TERMS IS DESIRED - THUS THE LIST IS COMPOSED OF THE NUMBER OF THE TERMS IN A COMPLETE SET THAT CORRESPOND TO THE DESIRED TERMS

ALPHA(I)=ARRAY OF ALPHA INFORMATION THAT INDICATES THE INDEPENDENT TERMS THAT SHOULD BE DELETED OR ACCEPTED

ELM(I, J)=ARRAY THAT CONTAINS THE VALUES OF THE POWERS OF THE INDEPENDENT TERMS THAT ARE TO BE DELETED OR ACCEPTED

I=TERM NUMBER AND COUNTER

ICOL=VALUE OF THE COLUMN OF ARRAY ELM CURRENTLY BEING PROCESSED

II =DO LOOP PARAMETER

IJ =DO LOOP PARAMETER

IROW=VALUE OF THE ROW OF ARRAY ELM CURRENTLY BEING PROCESSED

ITEST=INDEX THAT DENOTES THE INDEPENDENT VARIABLE PRESENTLY BEING PROCESSED

K=NUMBER OF CHARACTERS OF ALPHA INFORMATION READ FROM THE VARIABLE
MODE CONTROL DATA CARDS

LIST(I)=ARRAY THAT CONTAINS THE VALUES OF THE INDEXES FOR THOSE INDEPENDENT TERMS THAT ARE TO BE CONSIDERED IN THE REGRESSION MODEL

```

C      LL=SUBSCRIPT USED FOR THE VECTOR LIST - ALSO COUNTS THE NUMBER OF
C      INDEPENDENT TERMS
C      N=NUMBER OF TERMS
C      NM1=NUMBER OF INDEPENDENT TERMS
C      P(I)=POWERS OF THE INDEPENDENT VARIABLES NEEDED TO COMPOSE THE
C      INDEPENDENT TERM BEING CONSIDERED
C
C      DATA IBLK/4H      /,ICOM/4H,      /,IAST/4H*      /,ISHIFT/Z01000000/,
1IACCE/4HACCE/, IDELE/4HDELE/
C      INTEGER P(15), MAXP(15), ALPHA(3000), ELM(200, 15), LIST(150)
C
C      DETERMINE THE NUMBER OF CHARACTERS OF ALPHA INFORMATION ON THE
C      VARIABLE MODE CONTROL DATA CARDS WHICH SPECIFY THE
C      INDEPENDENT TERMS TO BE DELETED OR ACCEPTED
C
C      K=NCARD*80
C
C      PLACE ALL CHARACTERS FROM THE VARIABLE MODE CONTROL DATA CARDS IN
C      THE ARRAY ALPHA
C
C      READ(1, 1000)(ALPHA(J), J=1, K)
1000 FORMAT(80A1)
C
C      INITIALIZE THE ROW AND COLUMN OF THE ARRAY ELM
C
C      IROW=1
C      ICOL=0
C      DO 40 I=1, K
C
C      IF THE CHARACTER BEING TESTED IS A BLANK, THEN GO TO THE NEXT
C      CHARACTER

```



```

C      IF(ALPHA(I).EQ.IBLK) GO TO 40
C
C      IF THE CHARACTER BEING TESTED IS A COMMA, THEN THE FIRST NUMERIC
C      CHARACTER TO FOLLOW WILL BE A POWER OF THE FIRST INDEPENDENT
C      VARIABLE OF THE NEXT INDEPENDENT TERM TO BE ACTED UPON -
C      OTHERWISE THE CHARACTER DENOTES A POWER OF A INDEPENDENT
C      VARIABLE FOR THE TERM BEING CONSIDERED
C
C      IF(ALPHA(I).NE.ICOM) GO TO 20
C
C      IF THE NUMBER OF CHARACTERS DETECTED BETWEEN THE TWO
C      PREVIOUS COMMAS IS NOT EQUAL TO THE NUMBER OF INDEPENDENT
C      VARIABLES, THEN PRINT AN ERROR MESSAGE AND TERMINATE
C
C      IF(ICOL.EQ.N1M1) GO TO 10
C      WRITE(3,3000)
3000  FORMAT(' INCORRECT NUMBER OF CHARACTERS BETWEEN COMMAS ON A VARIAB
      1LE MODE CARD')
C      STOP
C
C      SINCE THE LAST CHARACTER TESTED WAS A COMMA, INCREMENT THE ROW
C      INDEX AND RESET THE COLUMN INDEX OF ARRAY ELM FOR THE NEXT
C      TERM - THEN GO TO TEST THE NEXT CHARACTER
C
10  IROW=IROW+1
C      ICOL=0
C      GO TO 40
C
C      SINCE THE LAST CHARACTER TESTED WAS A POWER OF AN INDEPENDENT
C      VARIABLE, INCREMENT OVER ONE COLUMN IN ARRAY ELM IN ORDER TO

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```

C          PLACE IN IT THE VALUE OF THE POWER
C
20 ICOL=ICOL+1
C
C      THE ASTERISK (*) IS USED TO DENOTE A VARIABLE POWER THAT WILL
C      ALWAYS BE ACKNOWLEDGED TO MEAN ANY POWER OF THE INDEPENDENT
C      VARIABLE IN QUESTION
C
C      IF THE POWER DETECTED IS NOT AN ASTERISK, THEN CONVERT THE POWER
C      FROM ALPHA INFORMATION TO A NUMERIC NUMBER AND PLACE THE
C      VALUE IN ARRAY ELM, OTHERWISE PUT AN ASTERISK IN THE
C      PARTICULAR ELEMENT OF ARRAY ELM
C
      IF(ALPHA(I).EQ.IAST) GO TO 30
C
      SHIFT ALPHA(I) FROM THE HIGH ORDER BYTE OF THE WORD TO THE LOW
      ORDER BYTE OF THE WORD
C
      ELM(IROW,ICOL)=15-IABS(ALPHA(I)/ISHIFT)
      GO TO 40
30 ELM(IROW,ICOL)=IAST
40 CONTINUE
C
C      INITIALIZE THE POWER OF ALL INDEPENDENT VARIABLES TO ZERO - THEN
C      SET THE POWER OF THE LAST INDEPENDENT VARIABLE TO ONE SO
C      THAT THE FIRST INDEPENDENT TERM MAY BE REPRESENTED
C
      DO 50 I=1, N1M1
50 P(I)=0
      P(N1M1)=1
C

```

```

C      INITIALIZE THE TERM COUNTER (I) AND THE INDEX USED TO INCREMENT
C      THROUGH ARRAY LIST (LL)
C
C      I=0
C      LL=0
C
C      INITIALIZE THE INDEX THAT DENOTES THE INDEPENDENT VARIABLE
C      PRESENTLY BEING PROCESSED
C
60 ITEST=N1M1
C
C      INCREMENT THE TERM COUNTER
C
70 I=I+1
C
C      CHECK WHETHER THE INDEPENDENT TERM BEING GENERATED IS REPRESENTED
C      IN ARRAY ELM - II IS THE ROW INDEX AND IJ IS THE COLUMN INDEX
C      FOR THE ARRAY ELM
C
C      DO 90 II=1,IROW
C      DO 80 IJ=1,ICOL
C
C      IF AN ASTERISK IS ENCOUNTERED IN AN ELEMENT OF ARRAY ELM, THEN
C      THIS IS CONSIDERED A MATCH FOR THE POWER OF THE INDEPENDENT
C      VARIABLE BEING CONSIDERED - PROCEED TO CHECK THE NEXT
C      INDEPENDENT VARIABLE
C
C      IF(ELM(II,IJ).EQ.IAST)GO TO 80
C
C      IF THE VALUE OF THE POWER OF THE INDEPENDENT VARIABLE BEING
C      CONSIDERED IS EQUAL TO THE VALUE OF THE ELEMENT OF ARRAY ELM

```

```

C      BEING CONSIDERED, THEN A MATCH OCCURS AND PROCEED TO CHECK
C      THE POWER OF THE NEXT INDEPENDENT VARIABLE - OTHERWISE SKIP
C      TO THE NEXT ROW OF ARRAY ELM AND START CHECKING IT
C
      IF(ELM(IJ, IJ). NE. P(IJ)) GO TO 90
80 CONTINUE
C
C      NOW THE POWERS OF ALL INDEPENDENT VARIABLES HAVE MATCHED AND THE
C      TERM BEING CONSIDERED IS REPRESENTED IN ARRAY ELM
C
      GO TO 100
90 CONTINUE
C
C      THE INDEPENDENT TERM BEING CONSIDERED WAS NOT REPRESENTED BY ANY
C      ROW OF THE ARRAY ELM
C
C      DETERMINE WHETHER THE VARIABLE MODE IS ACCEPT OR DELETE
C
      IF(MODE. EQ. IACCE) GO TO 120
      GO TO 110
C
C      DETERMINE WHETHER THE VARIABLE MODE IS ACCEPT OR DELETE
C
100 IF(MODE. EQ. IDELE) GO TO 120
C
C      INCREMENT THE INDEX USED FOR THE VECTOR LIST
C
110 LL=LL+1
C
C      PUT THE INDEPENDENT TERM IN THE LIST - THE TERM NUMBER IS PUT IN
C      THE LIST IF IT WAS REPRESENTED IN A ROW OF ARRAY ELM AND WAS

```

```

C      IN ACCEPT MODE, OR IF IT WAS NOT REPRESENTED IN A ROW OF
C      ARRAY ELM AND WAS IN DELETE MODE
C
C      LIST(LL)=I
C
C      PROCEED TO CHANGE THE POWERS OF THE INDEPENDENT VARIABLES SO THAT
C      THE NEXT INDEPENDENT TERM CAN BE REPRESENTED
C
C      CHECK WHETHER THE POWER LAST INCREMENTED HAS REACHED THE MAXIMUM
C      POWER FOR THAT INDEPENDENT VARIABLE
C
C      120 IF(P(ITEST).EQ. MAXP(ITEST)) GO TO 130
C
C      AGAIN INCREMENT THE POWER OF THE SAME INDEPENDENT VARIABLE WHOSE
C      POWER WAS LAST INCREMENTED
C
C      P(ITEST)=P(ITEST)+1
C      GO TO 70
C
C      TEST WHETHER THE POWER OF THE PRECEDING INDEPENDENT VARIABLE HAS
C      REACHED ITS MAXIMUM POWER
C
C      130 IF(P(ITEST-1).NE. MAXP(ITEST-1)) GO TO 140
C
C      TEST WHETHER THE FIRST INDEPENDENT VARIABLE HAS REACHED ITS
C      MAXIMUM POWER - ALL INDEPENDENT TERMS HAVE BEEN CONSIDERED
C      WHEN THIS CONDITION OCCURS
C
C      IF(ITEST.EQ. 2) GO TO 160
C
C      DECREMENT THE COUNTER TO THE PRECEDING VARIABLE

```

```

C
    ITEST=ITEST-1
    GO TO 130
C
C    REINITIALIZE ALL INDEPENDENT VARIABLES FROM THE LAST ONE
C    CONSIDERED UP TO THE LAST ONE
C
    140 DO 150 II=ITEST, N1M1
    150 P(II)=0
C
C    INCREASE THE POWER OF THE PRECEDING INDEPENDENT VARIABLE BY ONE
C
    P(ITEST-1)=P(ITEST-1)+1
    GO TO 60
C
C    COMPUTE THE NUMBER OF INDEPENDENT TERMS
C
    160 NM1=LL
C
C    COMPUTE THE NUMBER OF TERMS
C
    N=LL+1
    RETURN
    END

```

```

SUBROUTINE GENTRM(N1M1, NM1, MAXP, LIST, Z, X)
C
C   THIS SUBROUTINE IS USED ONLY WHEN IN ACCEPT OR DELETE MODE - ALL
C       INDEPENDENT TERMS AND THE DEPENDENT TERM ARE COMPUTED
C
C   I=DO LOOP PARAMETER
C   II=DO LOOP PARAMETER
C   IJ=DO LOOP PARAMETER
C   IRET=NUMBER OF THE TERM IN THE NORMAL MODE THAT IS TO
C       BE RETRIEVED AS POWERS OF THE INDEPENDENT VARIABLES
C   IZ=FRACTIONAL PART OF IRET TO STILL BE RETRIEVED
C   N1=NUMBER OF INPUT VARIABLES
C   P(I)=POWERS OF THE INDEPENDENT VARIABLES NEEDED TO COMPOSE THE
C       INDEPENDENT TERM BEING CONSIDERED
C   X(I)=TERM I OF A GIVEN OBSERVATION
C
C   DIMENSION Z(15), X(150)
C   INTEGER P(15), MAXP(15), LIST(150)
C
C   COMPUTE THE NUMBER OF INDEPENDENT VARIABLES
C
C   N1=N1M1+1
C
C   I REPRESENTS THE INDEPENDENT TERM BEING CONSIDERED
C
C   DO 20 I=1, NM1
C
C   SET IRET EQUAL TO THE TERM NUMBER THAT WOULD HAVE BEEN GENERATED
C       IF THE INDEPENDENT TERM BEING CONSIDERED WAS IN THE NORMAL
C       MODE
C

```

```

      IRET=LIST(I)
C
C   THIS DO LOOP CALCULATES THE POWERS OF THE INDEPENDENT VARIABLE FOR
C   THE INDEPENDENT TERM BEING CONSIDERED
C
      DO 10 IJ=1, N1M1
C
C   DIVIDE BY (MAXIMUM POWER + 1) AND THEN TRUNCATE
C
      IZ=IRET/(MAXP(N1-IJ)+1)
C
C   SUBTRACT OFF THE TRUNCATED VALUE TO OBTAIN THE POWER OF THE
C   INDEPENDENT VARIABLE IN QUESTION
C
      P(N1-IJ)=IRET-IZ*(MAXP(N1-IJ)+1)
C
C   DROP THE PART OF THE TERM ALREADY DIVIDED OUT
C
10  IRET=IZ
C
C   INITIALIZE THE VALUE OF THE INDEPENDENT TERM UNDER CONSIDERATION
C
      X(I)=1.0
      DO 20 II=1, N1M1
C
C   IF THE POWER OF THE INDEPENDENT VARIABLE IN QUESTION IS ZERO, THEN
C   IT SHOULD NOT BE CONSIDERED WHEN BUILDING AN INDEPENDENT TERM
C
      IF(P(II).EQ.0) GO TO 20
C
C   UPDATE THE VALUE OF THE INDEPENDENT TERM UNDER CONSIDERATION

```



```
C      X(I)=X(I)*Z(II)**P(II)
20  CONTINUE
C
C      COMPUTE THE DEPENDENT TERM
C
      X(NM1+1)=Z(N1)
      RETURN
      END
```

```

SUBROUTINE EXPAND(N1M1, MAXP, Z, X)
C
C   THIS SUBROUTINE IS USED ONLY IN NORMAL MODE - IT COMPUTES THE
C   VALUE OF THE COMPLETE SET OF INDEPENDENT TERMS BY EXPANDING
C   TO ALL POSSIBLE COMBINATIONS OF ALL POWERS OF THE INDEPENDENT
C   VARIABLES UP TO THEIR MAXIMUM POWERS - THEN THE DEPENDENT
C   TERM IS COMPUTED
C
C   I=TERM NUMBER AND COUNTER
C   II=DO LOOP PARAMETER
C   ITEST=INDEX THAT DENOTES THE INDEPENDENT VARIABLE PRESENTLY BEING
C   PROCESSED
C   P(I)=POWERS OF THE INDEPENDENT VARIABLES NEEDED TO COMPOSE THE
C   INDEPENDENT TERM BEING CONSIDERED
C   X(I)=TERM I OF A GIVEN OBSERVATION
C
C   DIMENSION Z(15), X(125)
C   INTEGER P(15), MAXP(15)
C
C   INITIALIZE THE POWER OF ALL INDEPENDENT VARIABLES TO ZERO
C
C   DO 10 I=1, N1M1
10  P(I)=0
C
C   SET THE POWER OF THE LAST INDEPENDENT VARIABLE TO ONE, THUS
C   REPRESENTING THE FIRST INDEPENDENT TERM
C
C   P(N1M1)=1
C
C   INITIALIZE THE TERM COUNTER
C

```

```

      I=0
C
C   INITIALIZE THE INDEX THAT DENOTES THE INDEPENDENT VARIABLE
C   PRESENTLY BEING PROCESSED
C
20  ITEST=N1M1
C
C   INCREMENT THE TERM COUNTER
C
30  I=I+1
C
C   INITIALIZE THE VALUE OF THE INDEPENDENT TERM UNDER CONSIDERATION
C
      X(I)=1.0
C
C   II IS THE INDEX THAT DENOTES THE INDEPENDENT VARIABLE BEING
C   PROCESSED
C
      DO 40 II=1,N1M1
C
C   IF THE POWER OF THE INDEPENDENT VARIABLE IN QUESTION IS ZERO, THEN
C   IT SHOULD NOT BE CONSIDERED WHEN BUILDING AN INDEPENDENT TERM
C
      IF(P(II).EQ.0) GO TO 40
C
C   UPDATE THE VALUE OF THE INDEPENDENT TERM BEING CALCULATED BY
C   MULTIPLYING BY AN INDEPENDENT VARIABLE RAISED TO A PARTICULAR
C   POWER
C
      X(I)=X(I)*Z(II)**P(II)
40  CONTINUE

```

```

C
C   PROCEED TO CHANGE THE POWERS OF THE INDEPENDENT VARIABLES SO THAT
C   THE NEXT INDEPENDENT TERM CAN BE REPRESENTED
C
C   CHECK WHETHER THE POWER OF THE INDEPENDENT VARIABLE LAST
C   INCREMENTED HAS REACHED THE MAXIMUM POWER FOR THAT
C   INDEPENDENT VARIABLE
C
C   IF(P(ITEST).EQ. MAXP(ITEST)) GO TO 50
C
C   AGAIN INCREMENT THE POWER OF THE SAME INDEPENDENT VARIABLE WHOSE
C   POWER WAS LAST INCREMENTED
C
C   P(ITEST)=P(ITEST)+1
C   GO TO 30
C
C   TEST WHETHER THE POWER OF THE PRECEDING INDEPENDENT VARIABLE HAS
C   REACHED ITS MAXIMUM POWER
C
C   50 IF(P(ITEST-1).NE. MAXP(ITEST-1)) GO TO 60
C
C   TEST WHETHER THE FIRST INDEPENDENT VARIABLE HAS REACHED ITS
C   MAXIMUM POWER - ALL INDEPENDENT TERMS OF THE COMPLETE SET
C   HAVE BEEN CONSIDERED WHEN THIS CONDITION OCCURS
C
C   IF(ITEST.EQ. 2) GO TO 80
C
C   DECREMENT THE COUNTER TO THE PRECEDING INDEPENDENT VARIABLE
C
C   ITEST=ITEST-1
C   GO TO 50

```

```

C
C   REINITIALIZE ALL INDEPENDENT VARIABLES FROM THE LAST ONE
C   CONSIDERED UP TO THE LAST ONE
C
60 DO 70 II=ITEST, N1M1
70 P(II)=0
C
C   INCREASE THE POWER OF THE PRECEDING INDEPENDENT VARIABLE BY ONE
C   AND GO PROCESS THE NEXT INDEPENDENT TERM
C
P(ITEST-1)=P(ITEST-1)+1
GO TO 20
C
C   COMPUTE THE DEPENDENT TERM
C
80 X(I+1)=Z(N1M1+1)
RETURN
END

```